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# Hashing Techniques

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**KAIST**

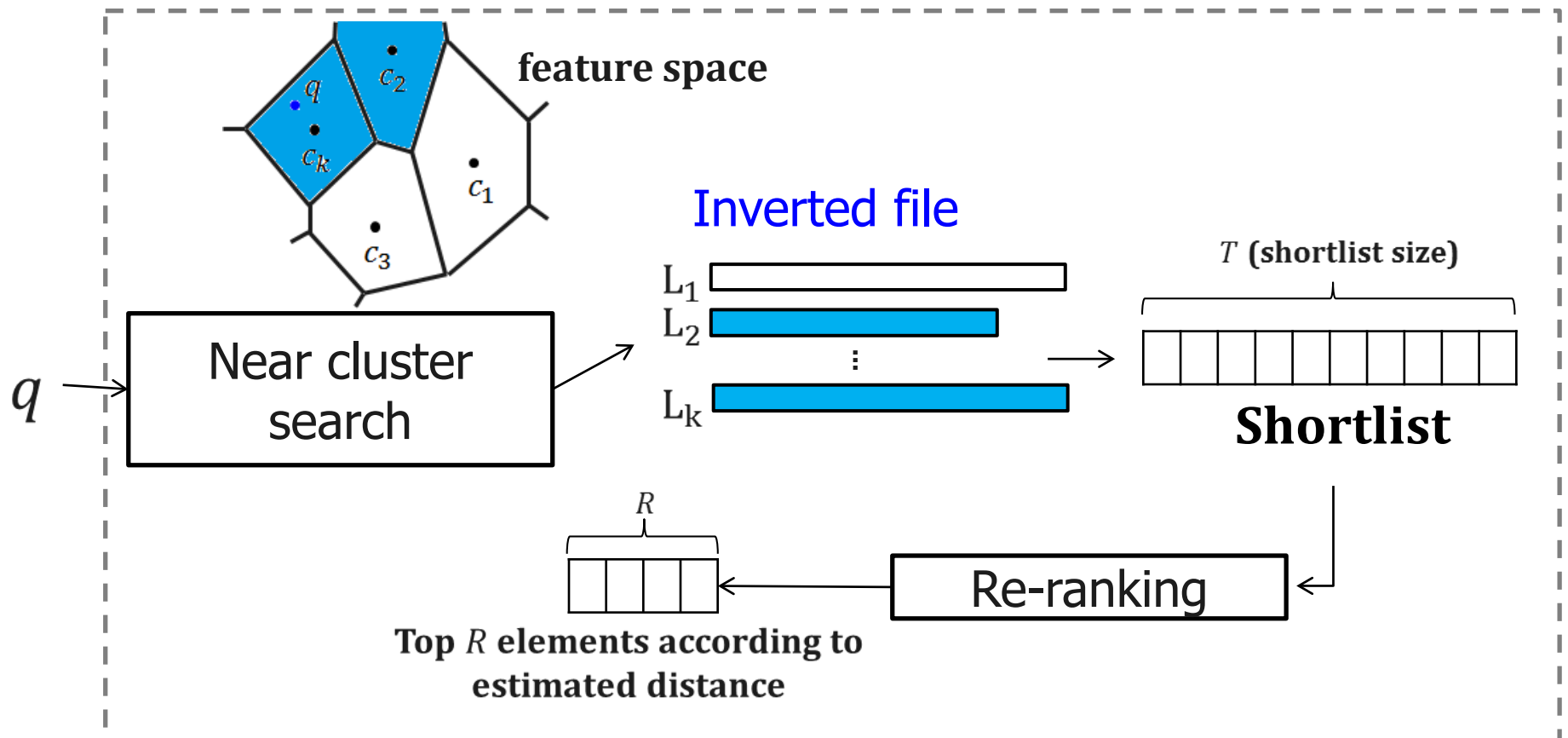


# Class Objectives

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- **Understand the basic hashing techniques based on hyperplanes**
  - **Unsupervised approach**
- **Semantic hashing using deep learning**
  
- **At the last class:**
  - **Discussed re-ranking methods: spatial verification and query expansion**
  - **Talked about inverted index**

# Review of Basic Image Search



# Image Search

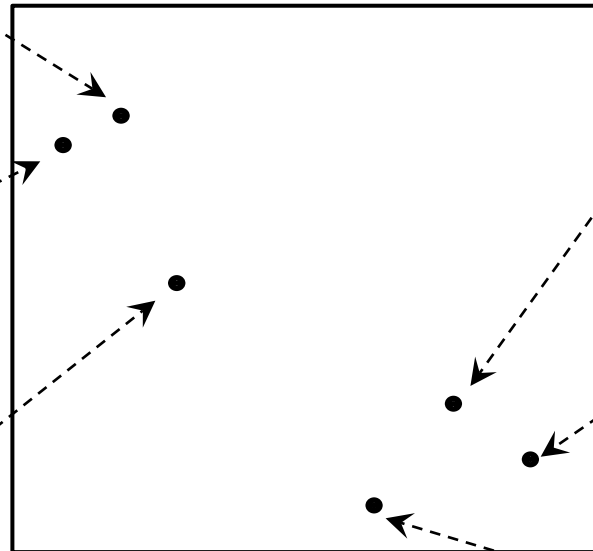
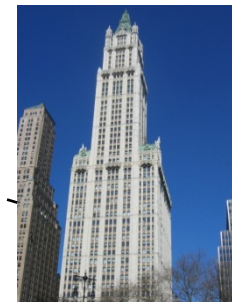
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## Finding visually similar images



# Image Descriptor

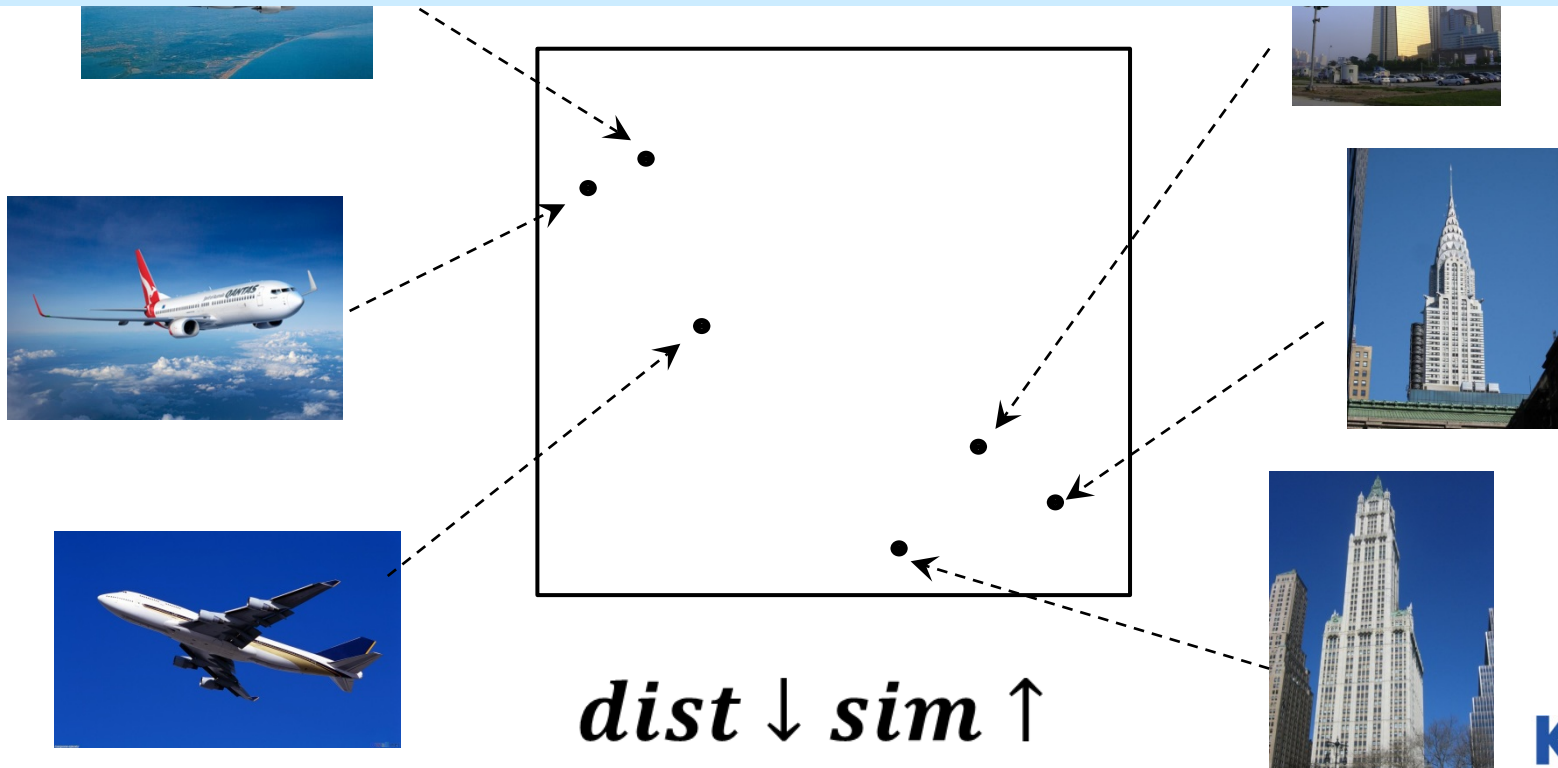
High dimensional point  
(BoW, GIST, Color Histogram, etc.)



*dist* ↓ *sim* ↑

# Image Descriptor

High dimensional point  
Nearest neighbor search (NNS)  
in high dimensional space



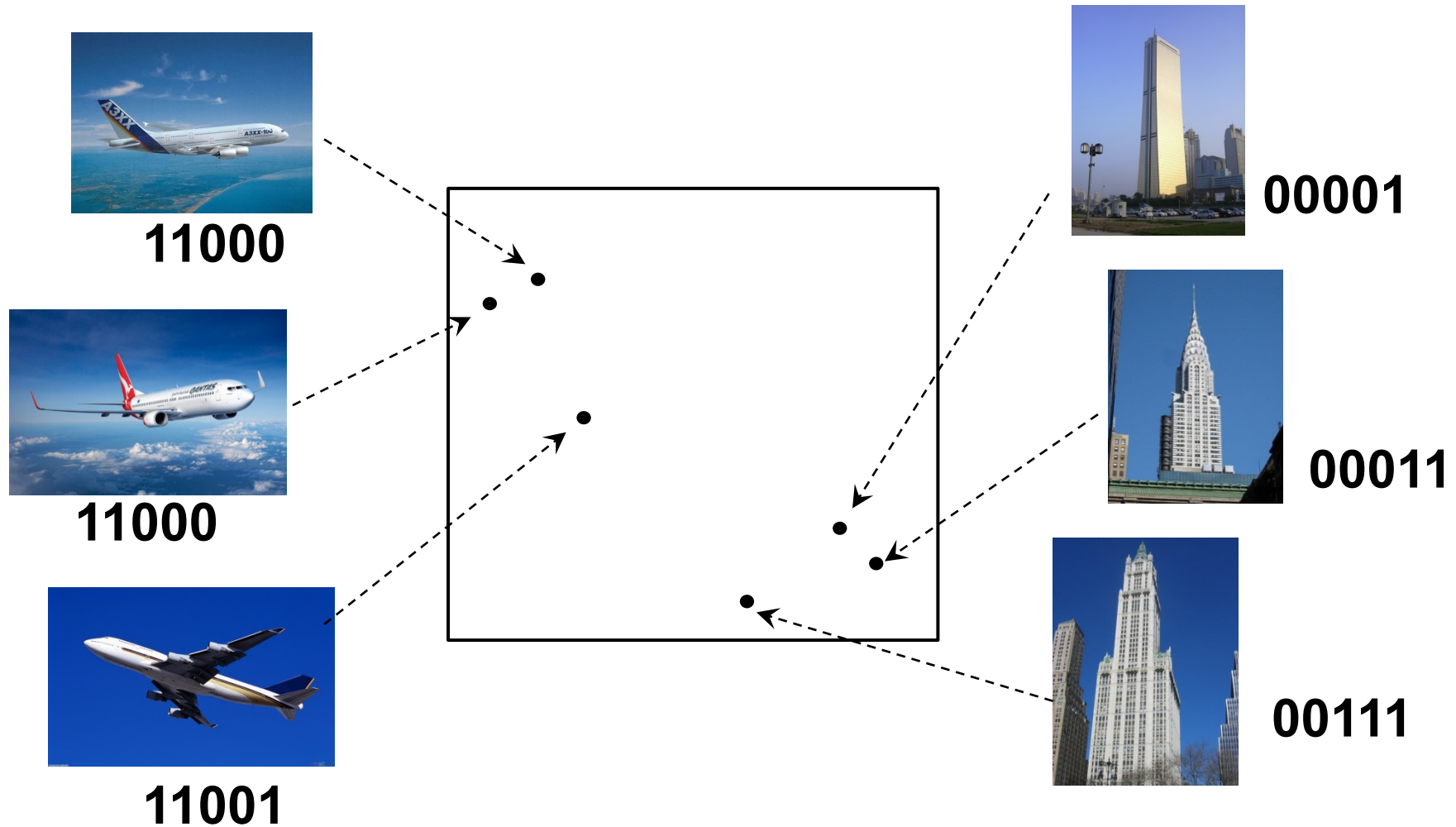
# Challenge

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	<b>BoW</b>	<b>CNN</b>
<b>Dimensions</b>	<b>1000+</b>	<b>4000+</b>
<b>1 image</b>	<b>4 KB+</b>	<b>16 KB+</b>
<b>1B images</b>	<b>4 TB+</b>	<b>16 TB+</b>

$$\frac{144 \text{ GB memory}}{1 \text{ billion images}} \approx \frac{128 \text{ bits}}{1 \text{ image}}$$

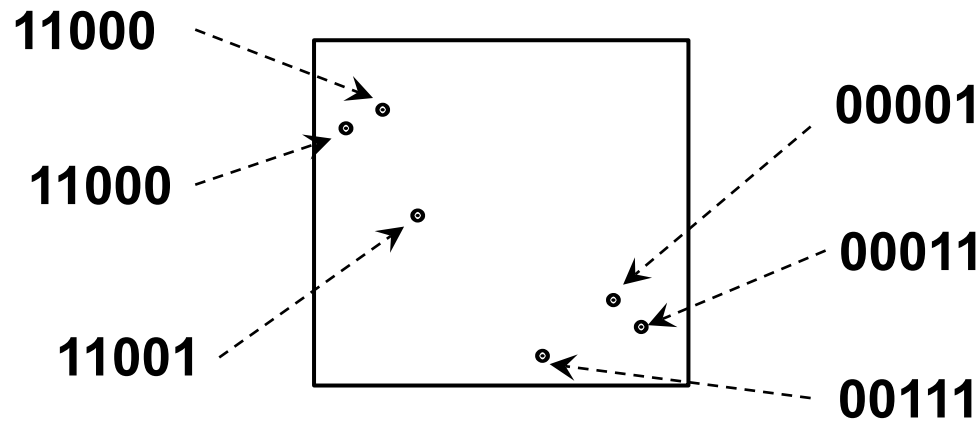
# Binary Code





# Binary Code

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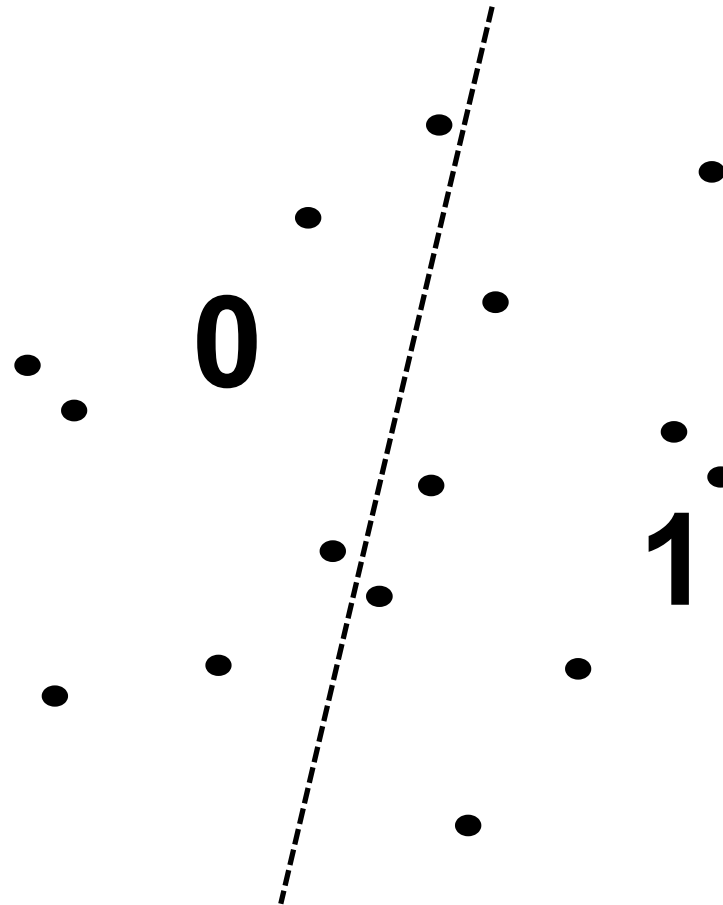


## \* Benefits

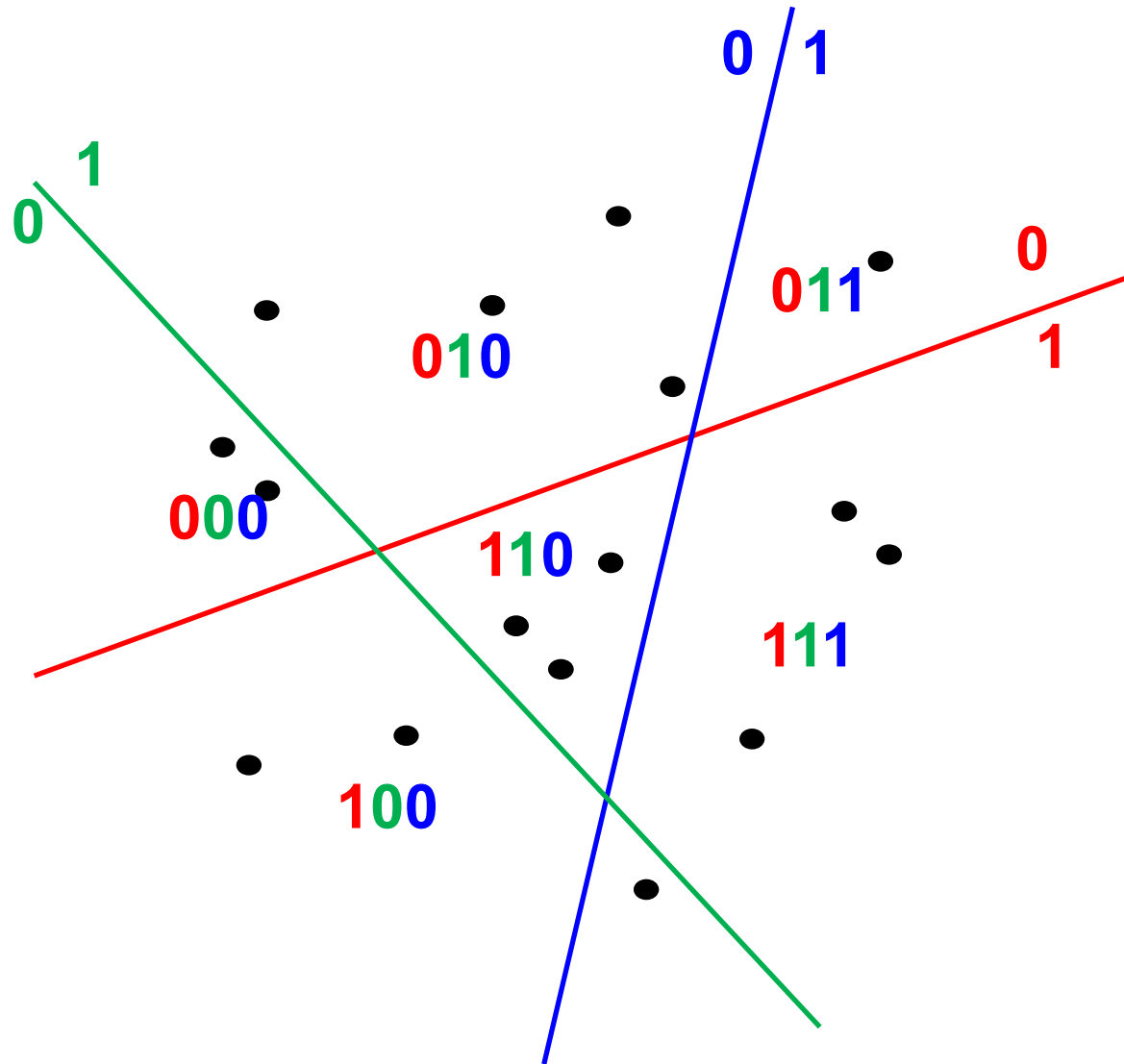
- Compression
- Very fast distance computation (Hamming Distance, XOR)

# Hyper-Plane based Binary Coding

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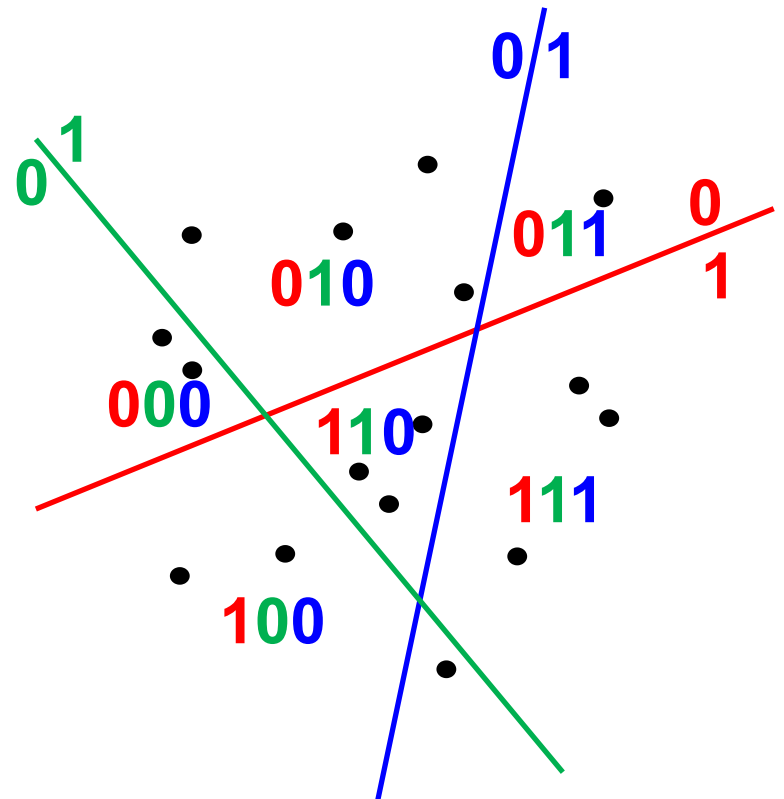
# Hyper-Plane based Binary Coding



# Distance between Two Points

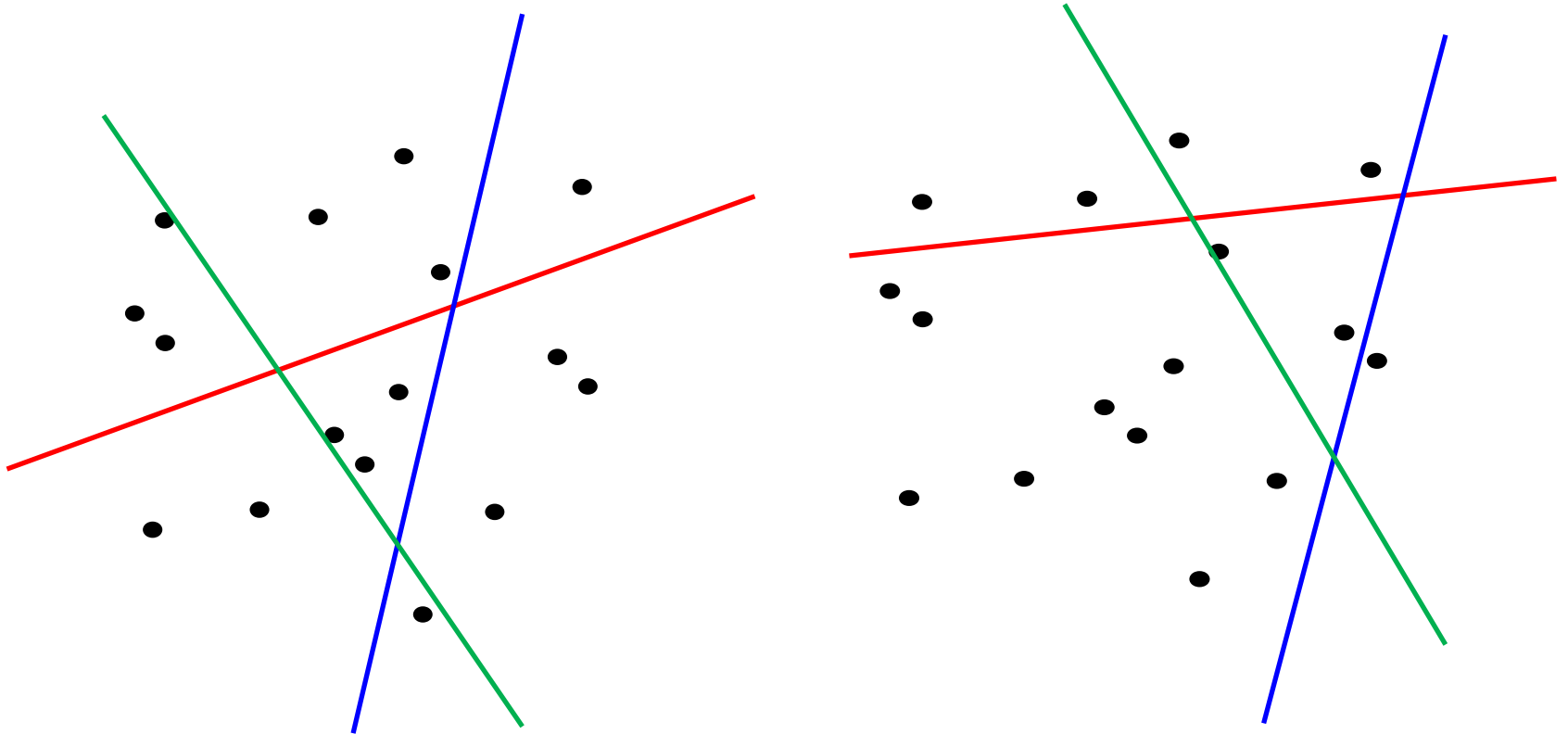
- Measured by bit differences, known as Hamming distance
- Efficiently computed by XOR bit operations

$$d_{hd}(b_i, b_j) = |b_i \oplus b_j|$$



# Good and Bad Hyper-Planes

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**Previous work focused on  
how to determine good hyper-planes**

# Components of Spherical Hashing

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- Spherical hashing
- Hyper-sphere setting strategy
- Spherical Hamming distance

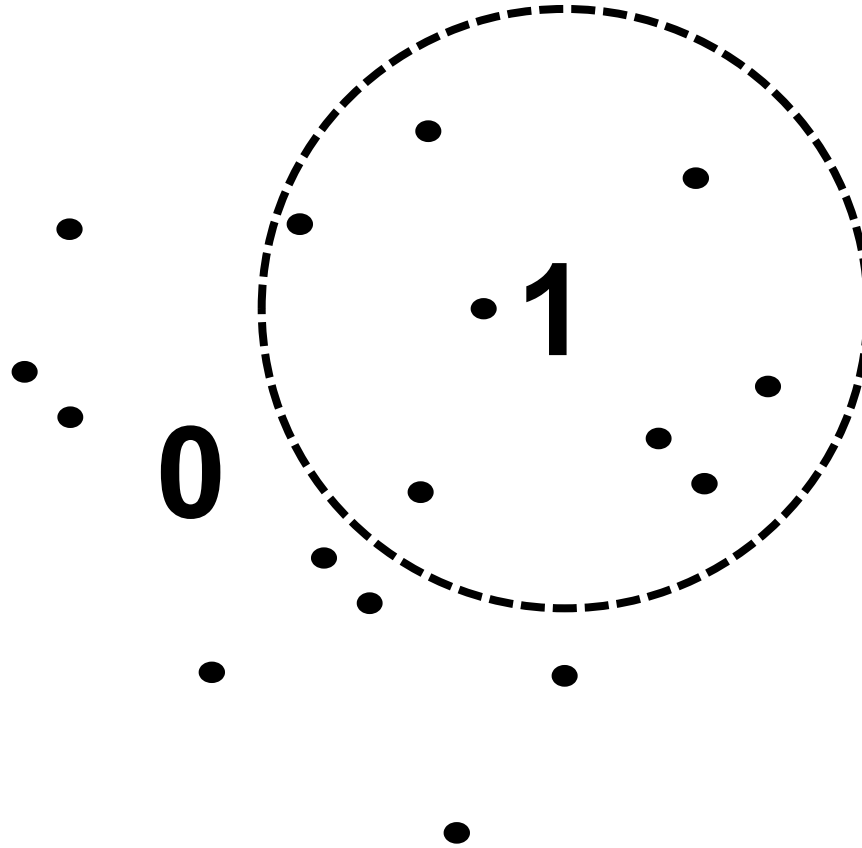
# Components of Spherical Hashing

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- **Spherical hashing**
- Hyper-sphere setting strategy
- Spherical Hamming distance

# Spherical Hashing [Heo et al., CVPR 12]

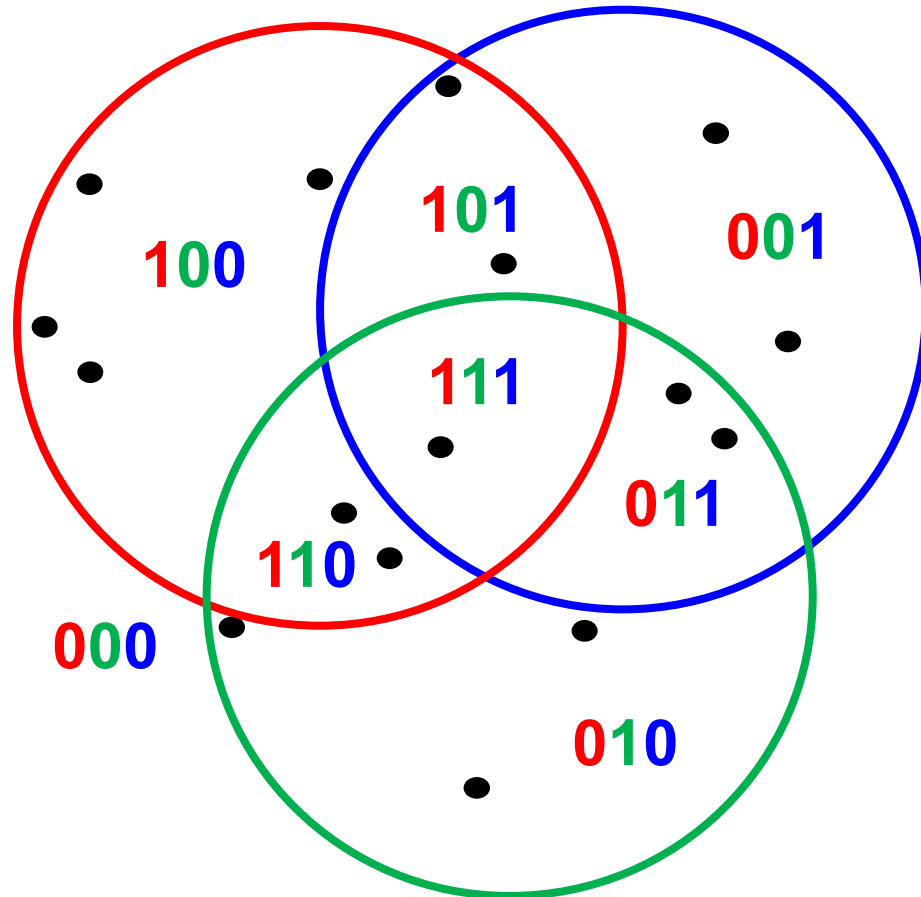
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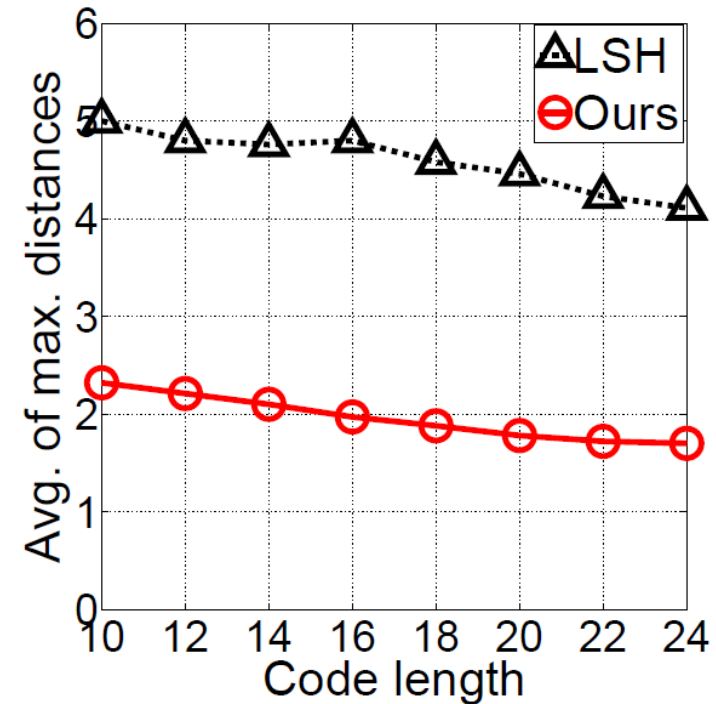
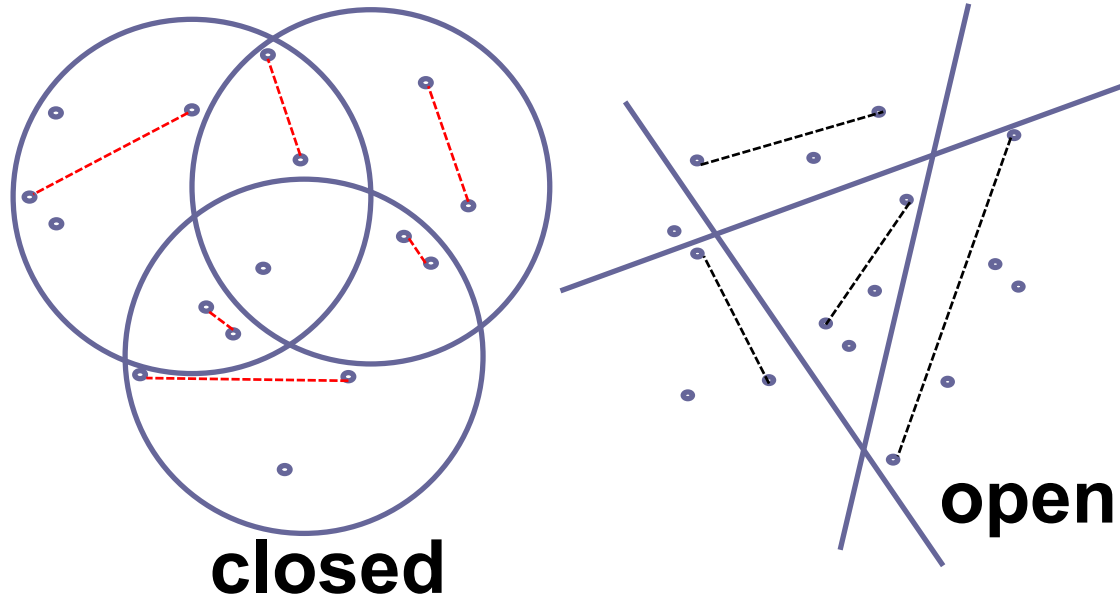


# Spherical Hashing [Heo et al., CVPR 12]

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# Hyper-Sphere vs Hyper-Plane



**Average of maximum distances within a partition:**  
- Hyper-spheres gives tighter bound!

# Components of Spherical Hashing

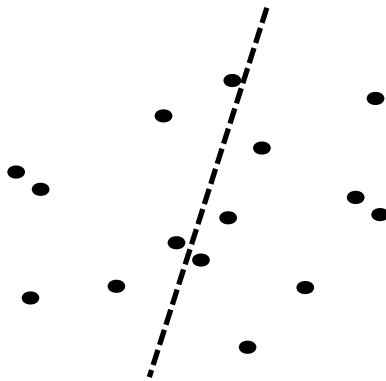
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- Spherical hashing
- **Hyper-sphere setting strategy**
- Spherical Hamming distance

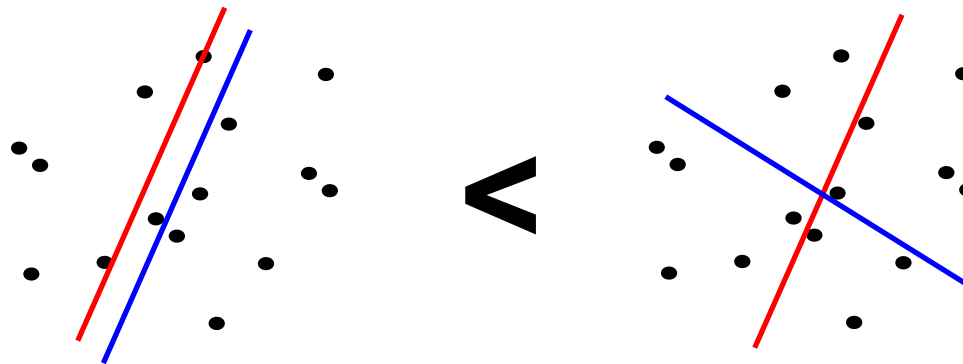
# Good Binary Coding [Yeiss 2008, He 2011]

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## 1. Balanced partitioning

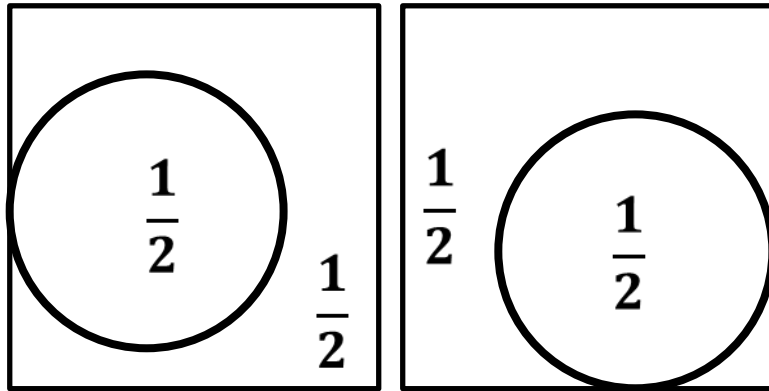


## 2. Independence

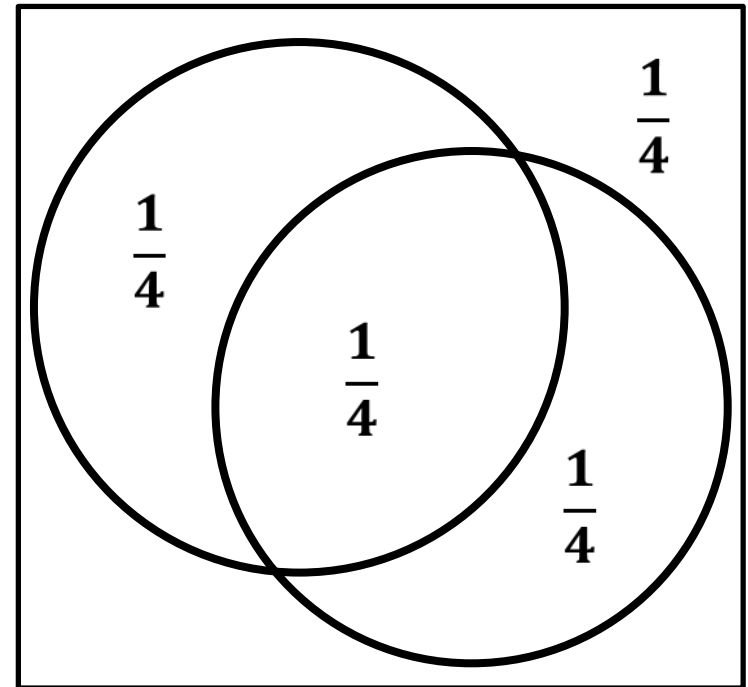


# Intuition of Hyper-Sphere Setting

## 1. Balance



## 2. Independence

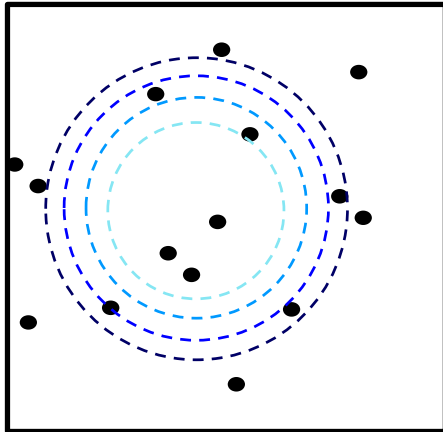


# Hyper-Sphere Setting Process

## 1. Balance

- by controlling radius

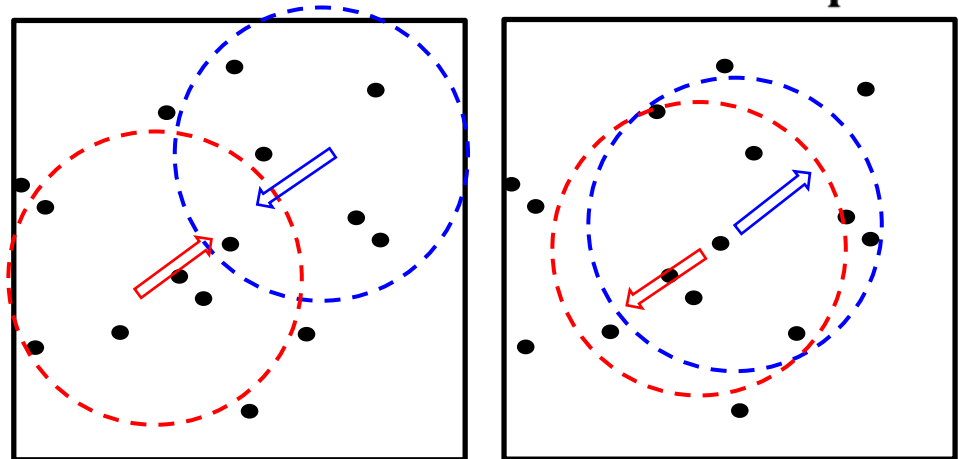
$$\text{for } n(S) = \frac{N}{2}$$



## 2. Independence

- by moving two hyper-spheres

$$\text{for } n(S_1 \cap S_2) = \frac{N}{4}$$



**Iteratively repeat step 1, 2 until convergence.**

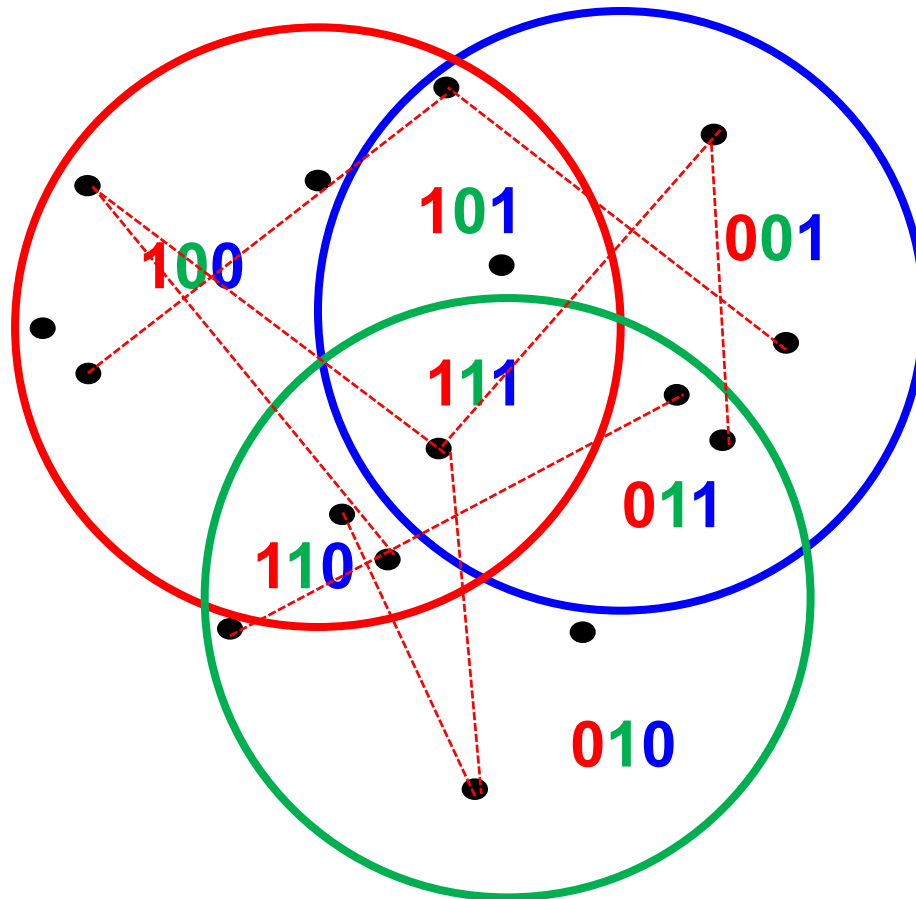
# Components of Spherical Hashing

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- Spherical hashing
- Hyper-sphere setting strategy
- **Spherical Hamming distance**

# Max Distance and Common '1'

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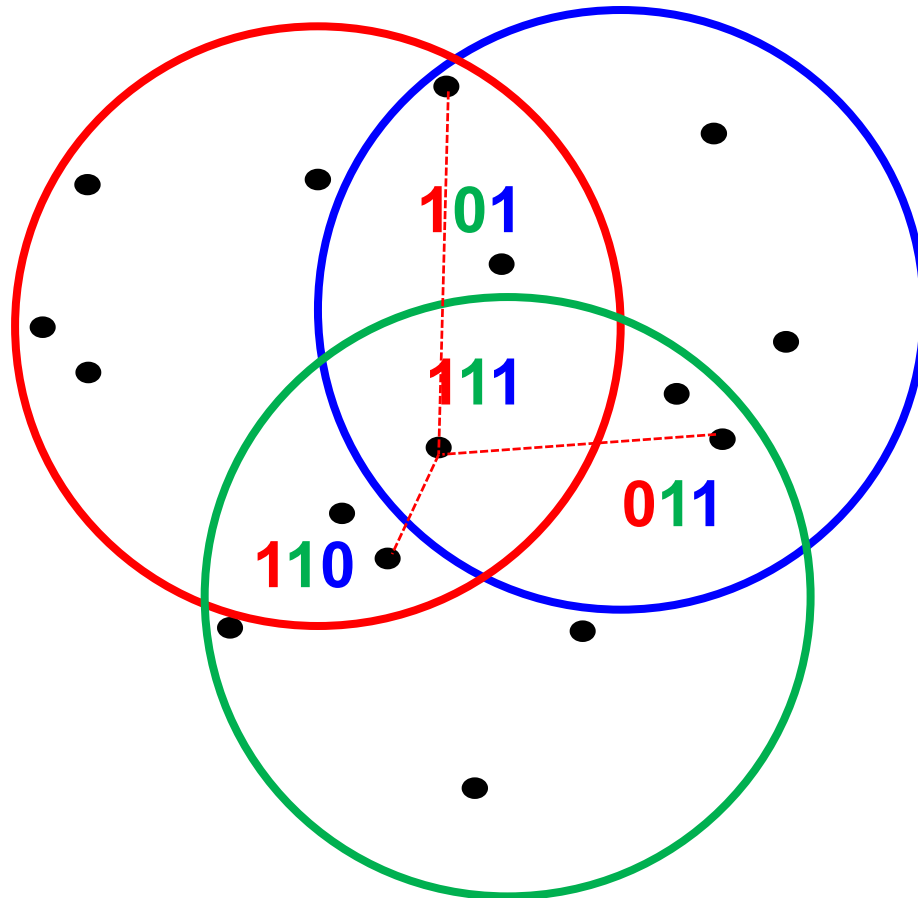


Common '1's  
: 1



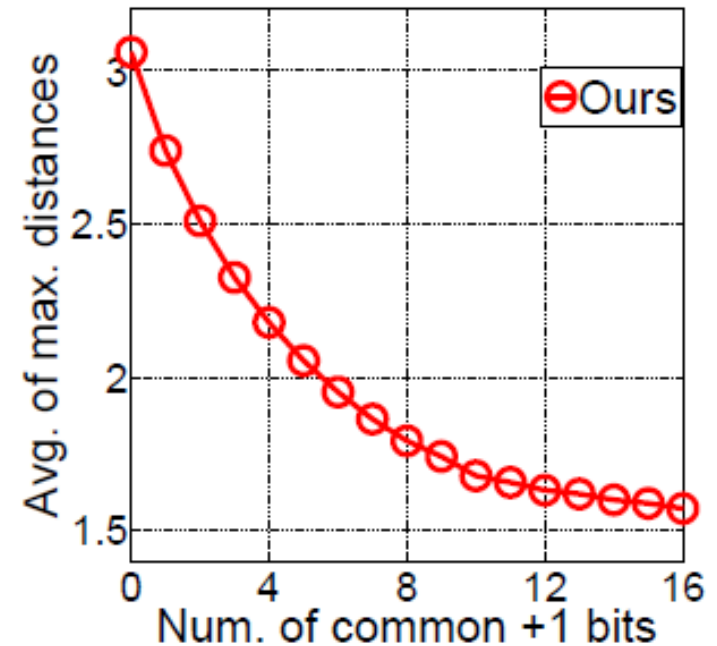
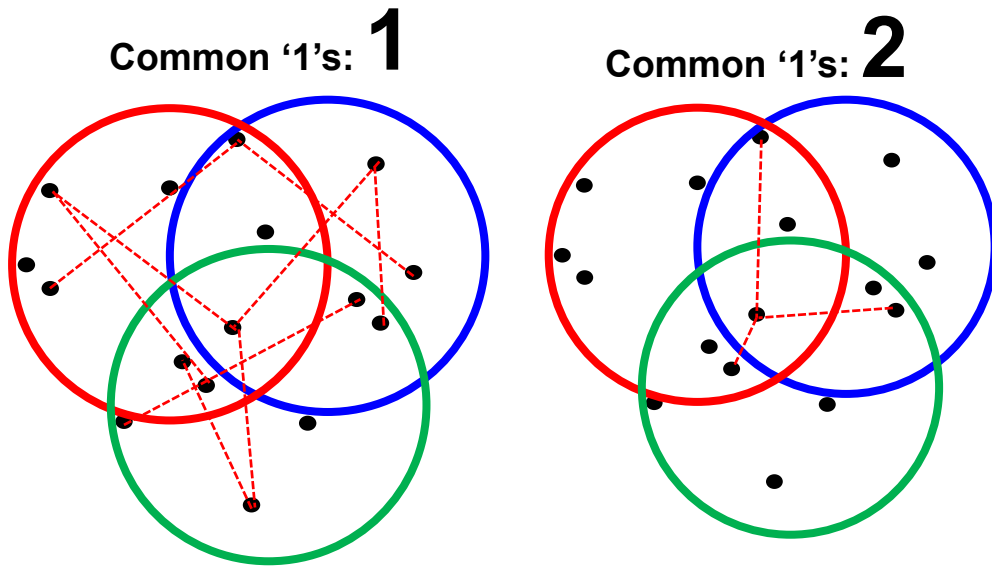
# Max Distance and Common '1'

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Common '1's  
: **2**

# Max Distance and Common '1'



**Average of maximum distances between two partitions: decreases as number of common '1'**

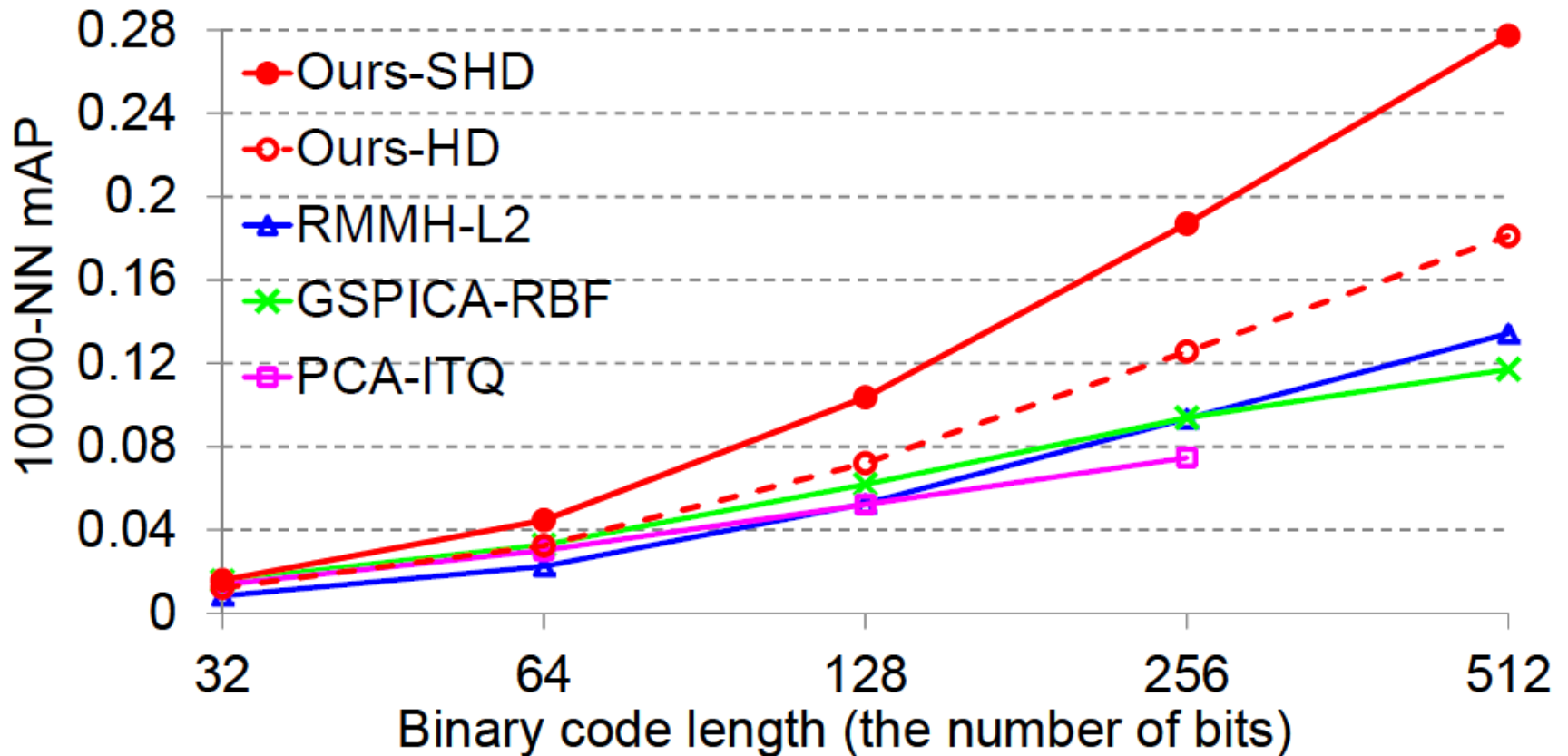
# Spherical Hamming Distance (SHD)

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$$d_{shd}(b_i, b_j) = \frac{|b_i \oplus b_j|}{|b_i \wedge b_j|}$$

**SHD: Hamming Distance** divided by the number of common '1's.

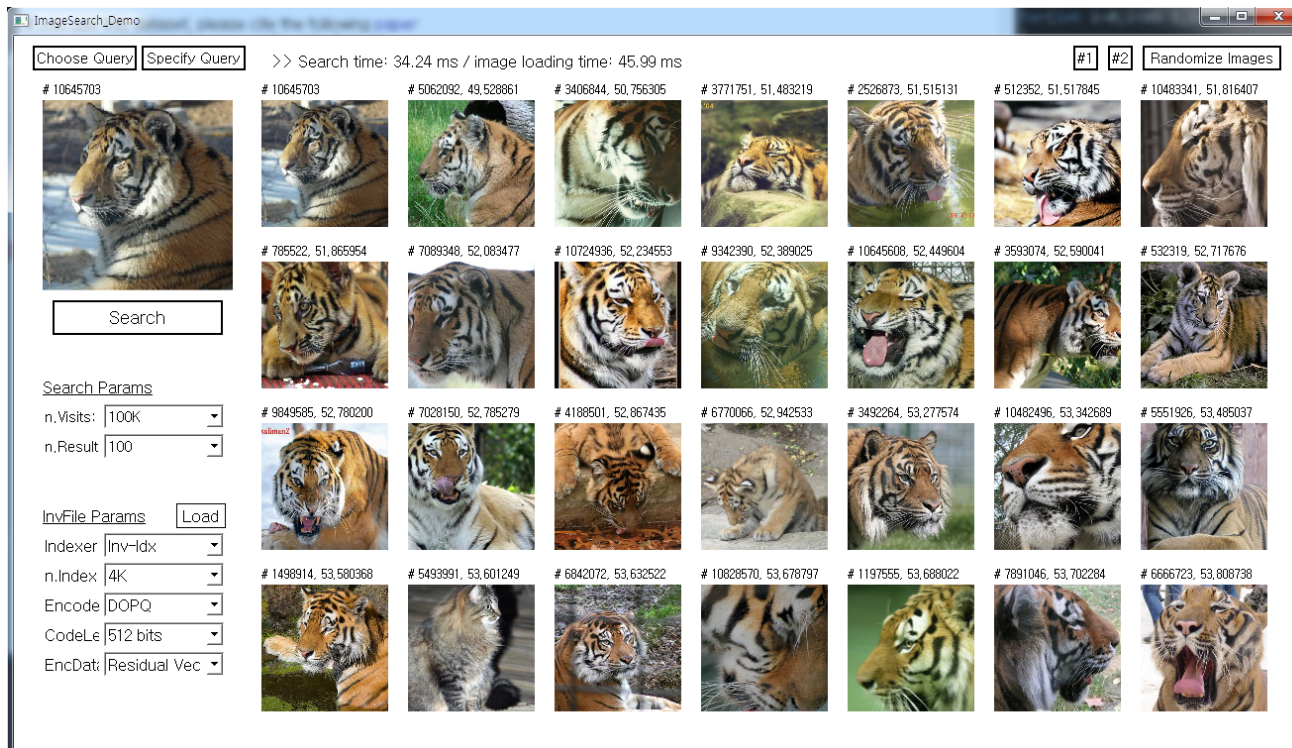
# Results



**384 dimensional 75 million GIST descriptors**

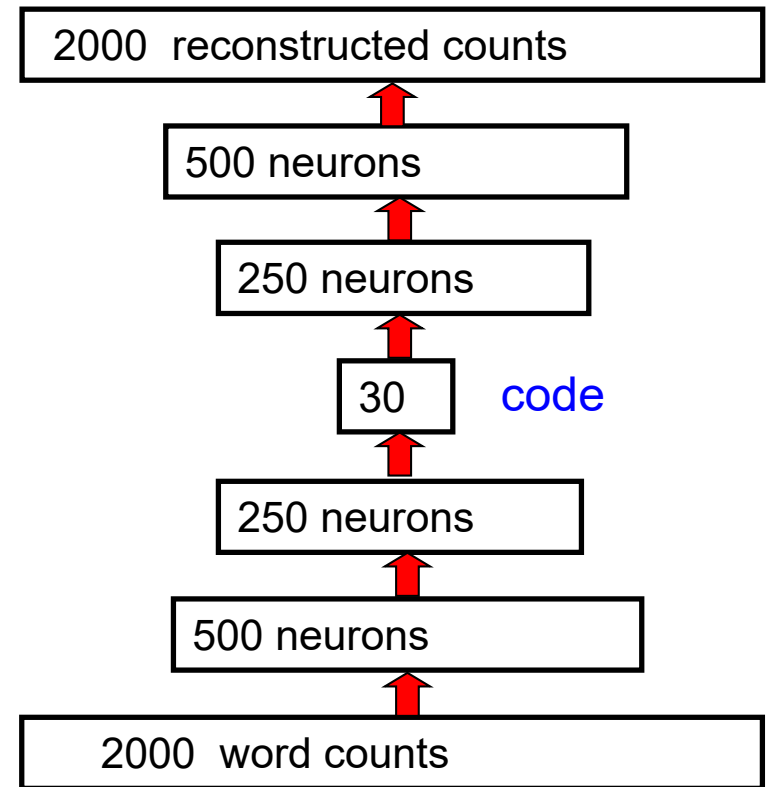
# Results of Image Retrieval

- Collaborated with Adobe
  - 11M images
  - Use deep neural nets for image representations
  - Spend only 35 ms for a single CPU thread



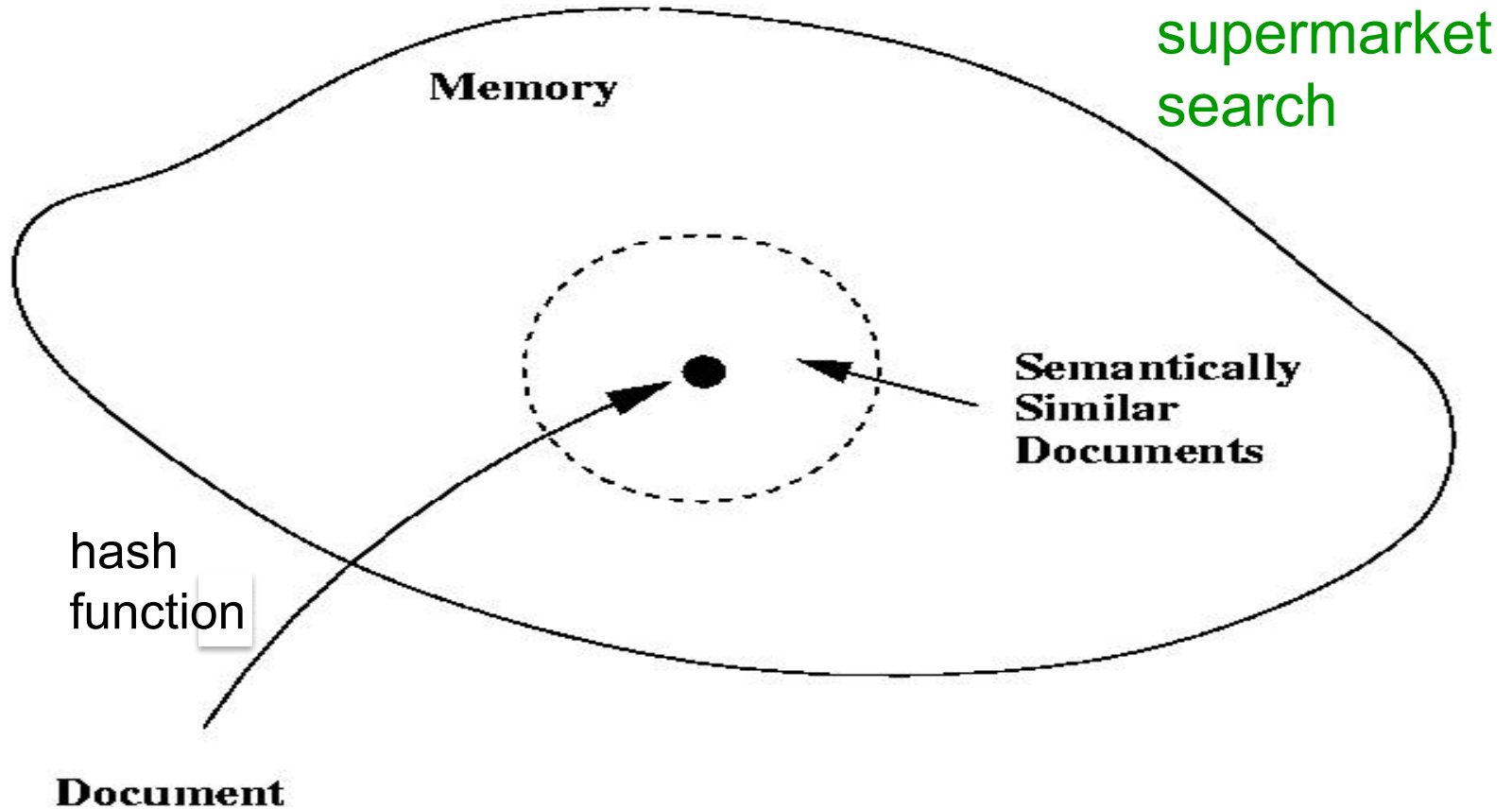
# Semantic Hashing: Finding binary codes for BoW model

- Train an auto-encoder using 30 logistic units for the code layer.
  - We simply threshold the activities of the 30 code units to get a binary code.



Ack. Hinton

Using a deep autoencoder as a hash-function for finding **approximate** matches



# Binary codes for image retrieval

- Maybe we should extract a real-valued vector that has information about the content?
  - Matching real-valued vectors in a big database is slow and requires a lot of storage.
- Short binary codes are very easy to store and match.



# A two-stage method

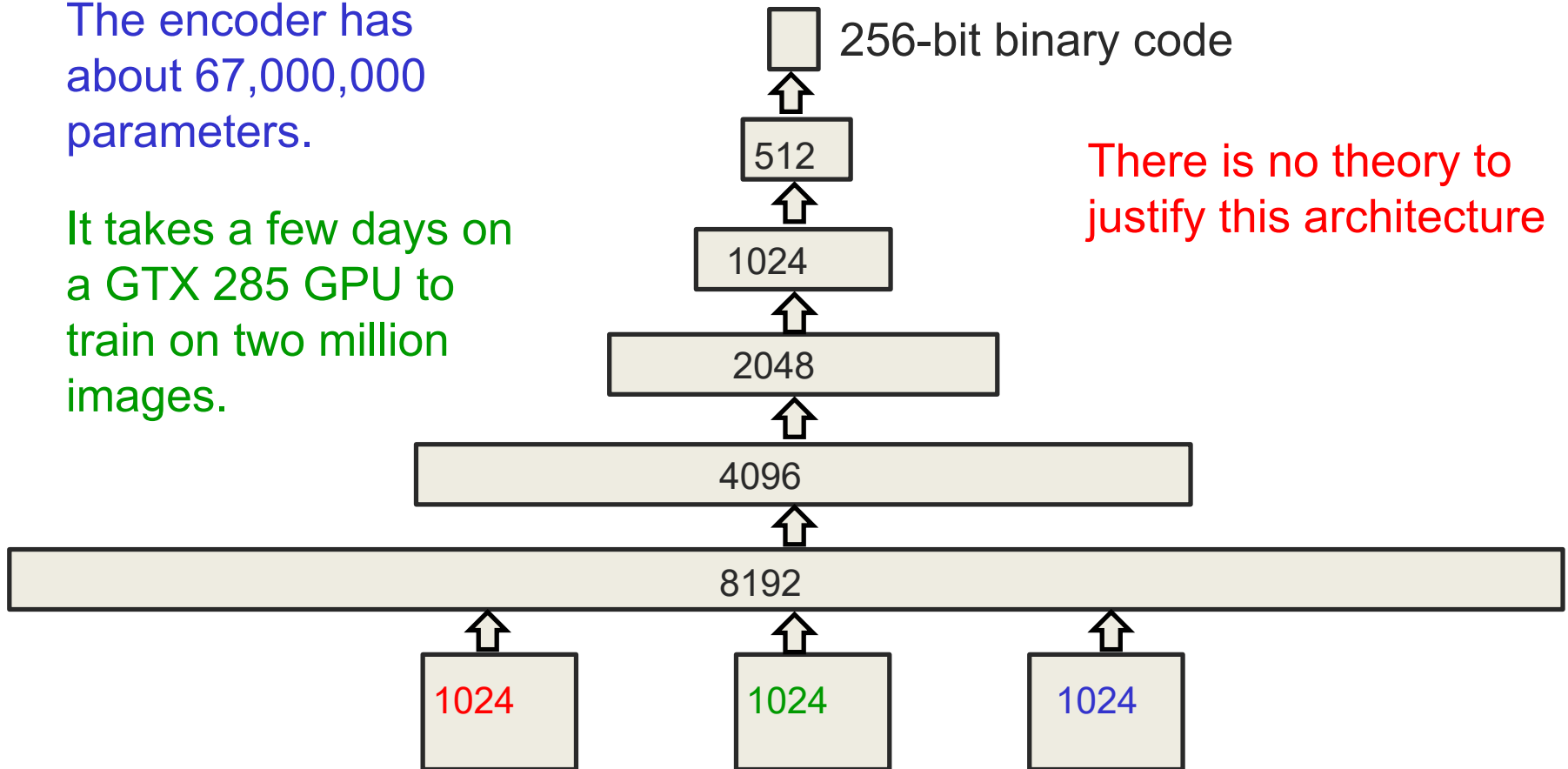
- First, use semantic hashing with 28-bit binary codes to get a long “shortlist” of promising images.
- Then use 256-bit binary codes to do a serial search for good matches.
  - This only requires a few words of storage per image and the serial search can be done using fast bit-operations.
- But how good are the 256-bit binary codes?
  - Do they find images that we think are similar?

# Krizhevsky's deep autoencoder

The encoder has about 67,000,000 parameters.

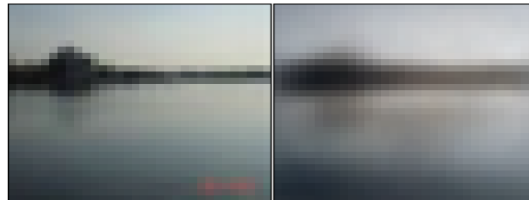
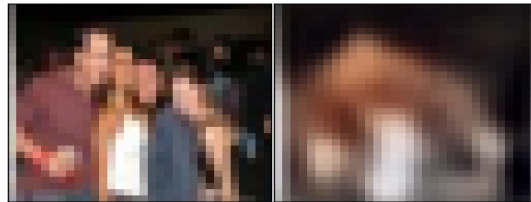
It takes a few days on a GTX 285 GPU to train on two million images.

There is no theory to justify this architecture



Start w/ 32 by 32 image patch

# Reconstructions of 32x32 color images from 256-bit codes



## retrieved using 256 bit codes



## retrieved using Euclidean distance in pixel intensity space



## retrieved using 256 bit codes



## retrieved using Euclidean distance in pixel intensity space



# Class Objectives were:

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- **Understand the basic hashing techniques based on hyperplanes**
  - **Unsupervised approach**
- **Semantic hashing**
- **Codes are available**

<http://sglab.kaist.ac.kr/software.htm>

# Homework for Every Class

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- **Go over the next lecture slides**
- **Come up with one question on what we have discussed today**
  - **Write questions three times**
- **Go over recent papers on image search, and submit their summary before Mon. class**

# Next Time...

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- **Person Re-Identification, Re-ID**