

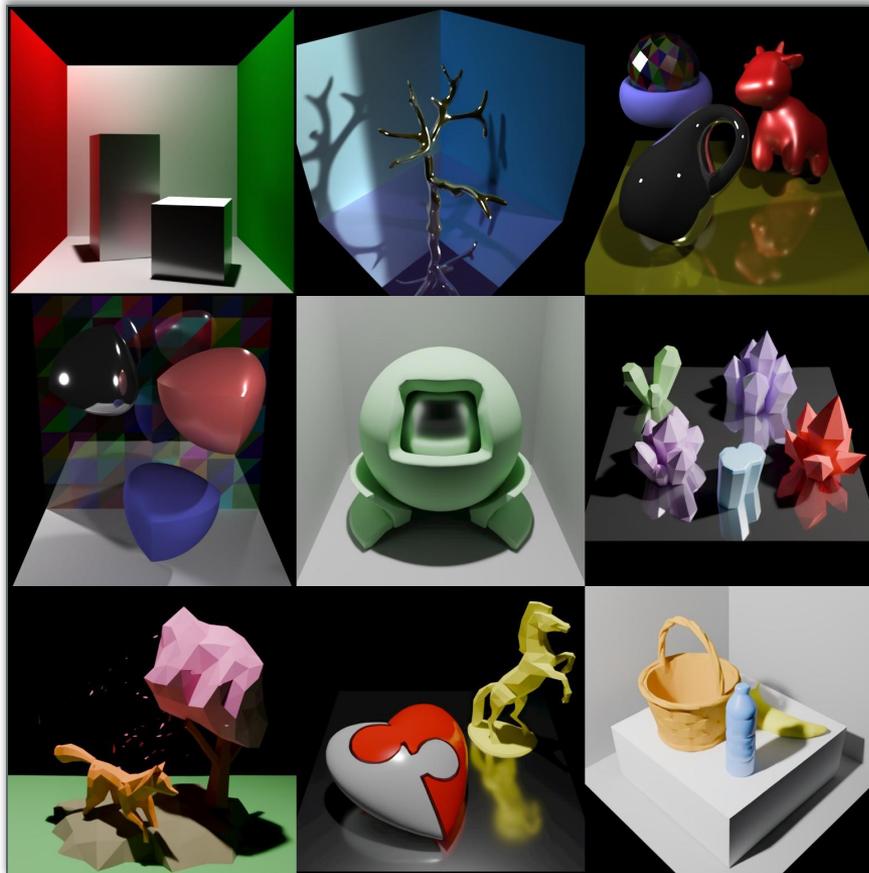
RenderFormer

Mid-term Project Presentation

10th Oct, 2025

Team 4

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Outline

- Related Work & their Problems
- Overview of RenderFormer
- Limitations of RenderFormer
- Our Plan to Overcome One Limitation

Related Work & Their Limitations

Solving the Rendering Equation

$$L_r(x \rightarrow \Theta) = \int_{\Psi} L(x \leftarrow \Psi) f_r(x, \Psi \rightarrow \Theta) \cos \theta_x d\omega_{\Psi}$$

Monte Carlo Estimation of Path Integral

- Path Tracing
- Monte Carlo
- Path Guiding
- Multiple Importance Sampling
- ...

Recursive

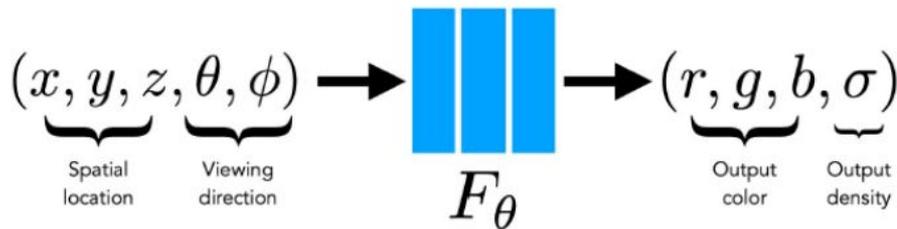
Radiosity Techniques (Finite Elements Methods)

- Pre-computation
- Per-scene Training
- Precomputed Radiance Transfer (PRT)
- ...

3D Inductive Bias (Representation Level)

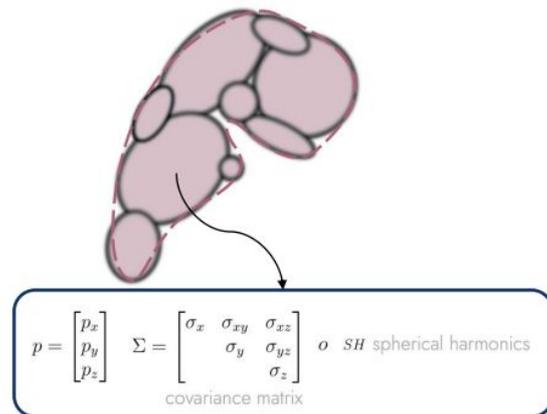
NeRF

Continuous Volumetric Field: Assumes the scene can be represented as a continuous 5D function.



3DGS

Gaussian Primitives: Scenes are composed of fuzzy blobs (Gaussians) that can be combined



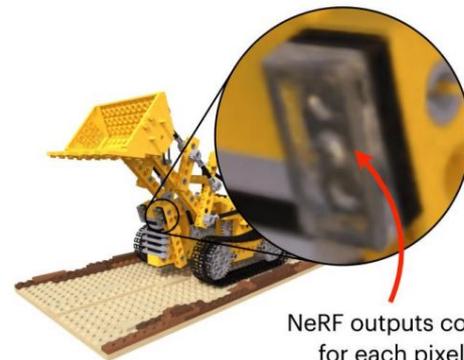
3D Inductive Bias

Why 3D Inductive Biases Are Good

1. **Efficiency:** Reduce the learning space.
2. **Sample efficiency:** With strong priors, models can generalize from fewer examples

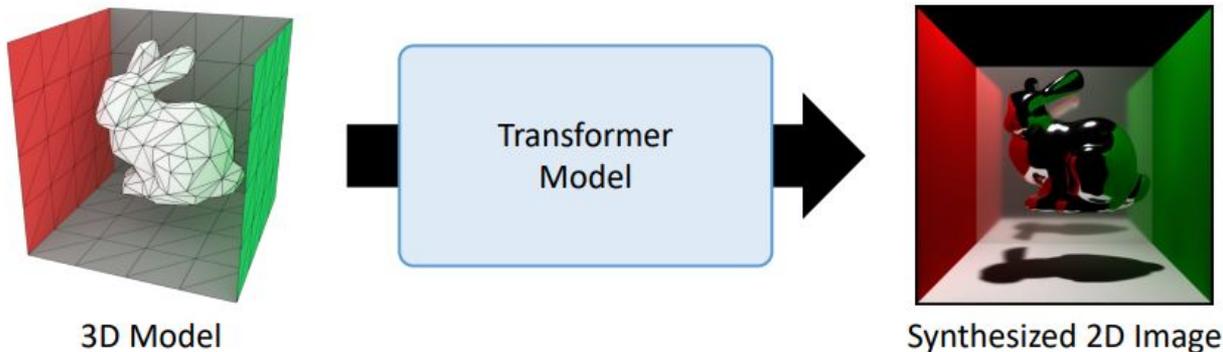
Why 3D Inductive Biases Are Bad

1. **Limited flexibility:** Real-world scenarios may not match the built-in assumptions.
2. **Poor generalization:** A model designed for one type of object/geometry might fail on other types of objects/geometries.



NeRF outputs color
for each pixel

RenderFormer: A Fully Transformer Rendering Pipeline



✓ End-to-end with Raw 3D Input

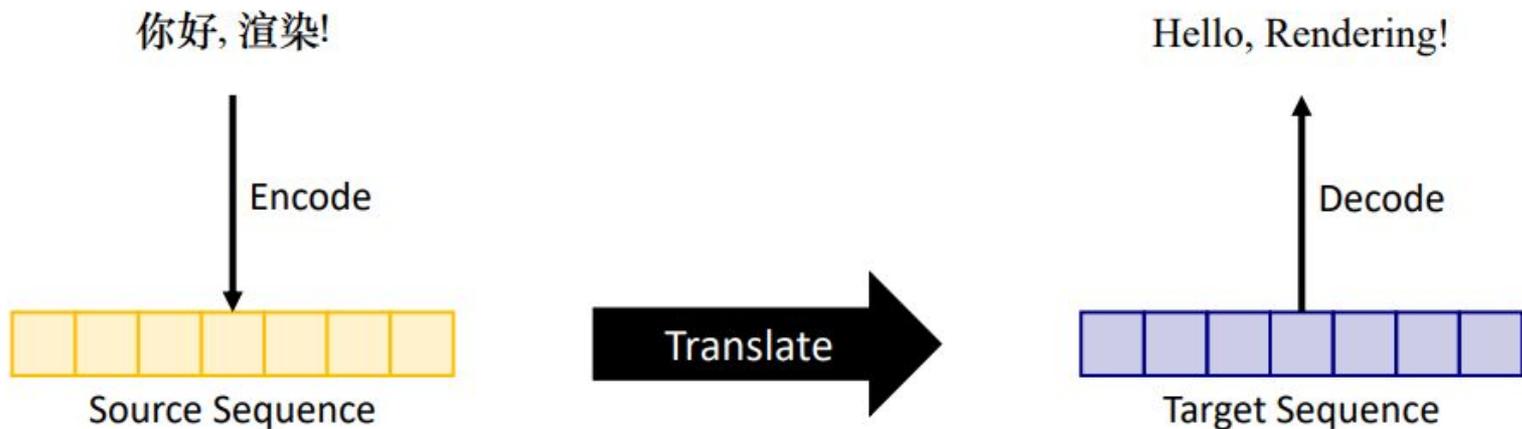
✓ Minimal Prior Constraints

✓ No Per-scene Training

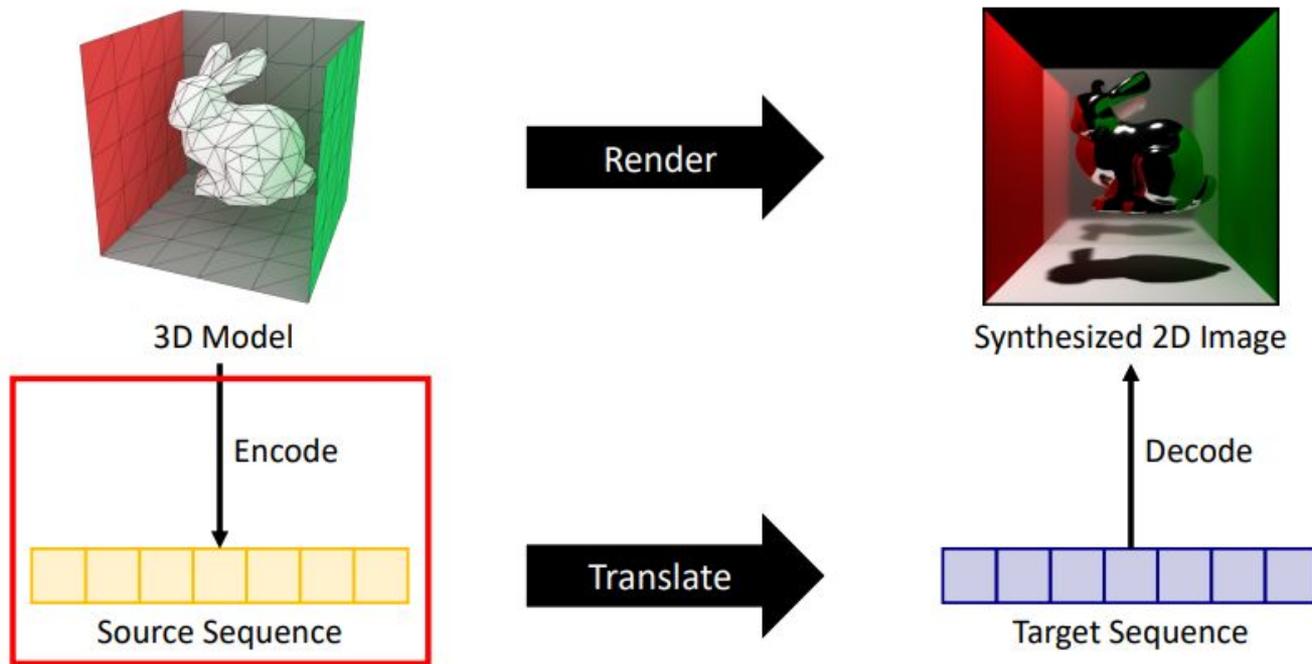
✓ Full Global Illumination Effects

Overview of RenderFormer

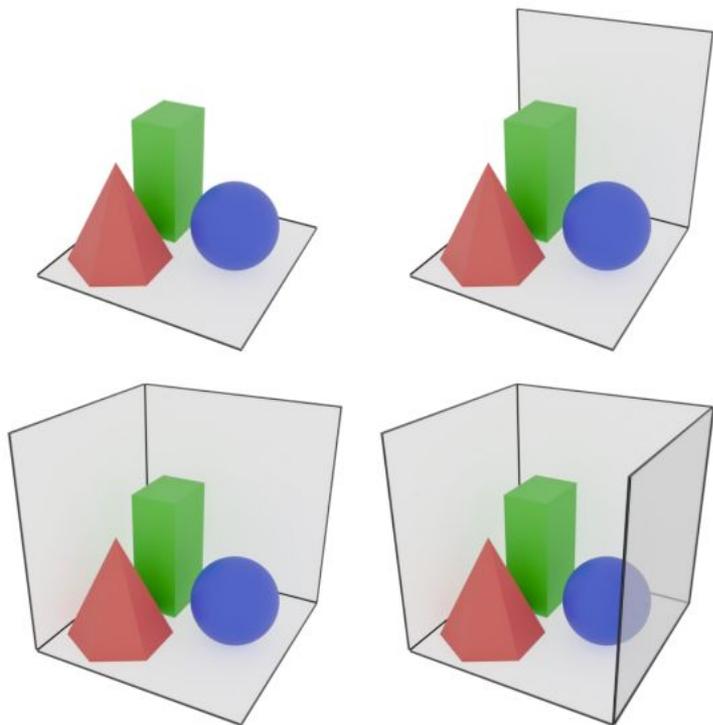
Sequence-to-Sequence Machine Translation



Idea: 3D Rendering = Translating 3D to 2D



Training Data – Template-based Scene Generation



4,096

Max #Triangles

0.01-1.0

Roughness Range

8

Max #Lights

2.1-2.7

Light Distance

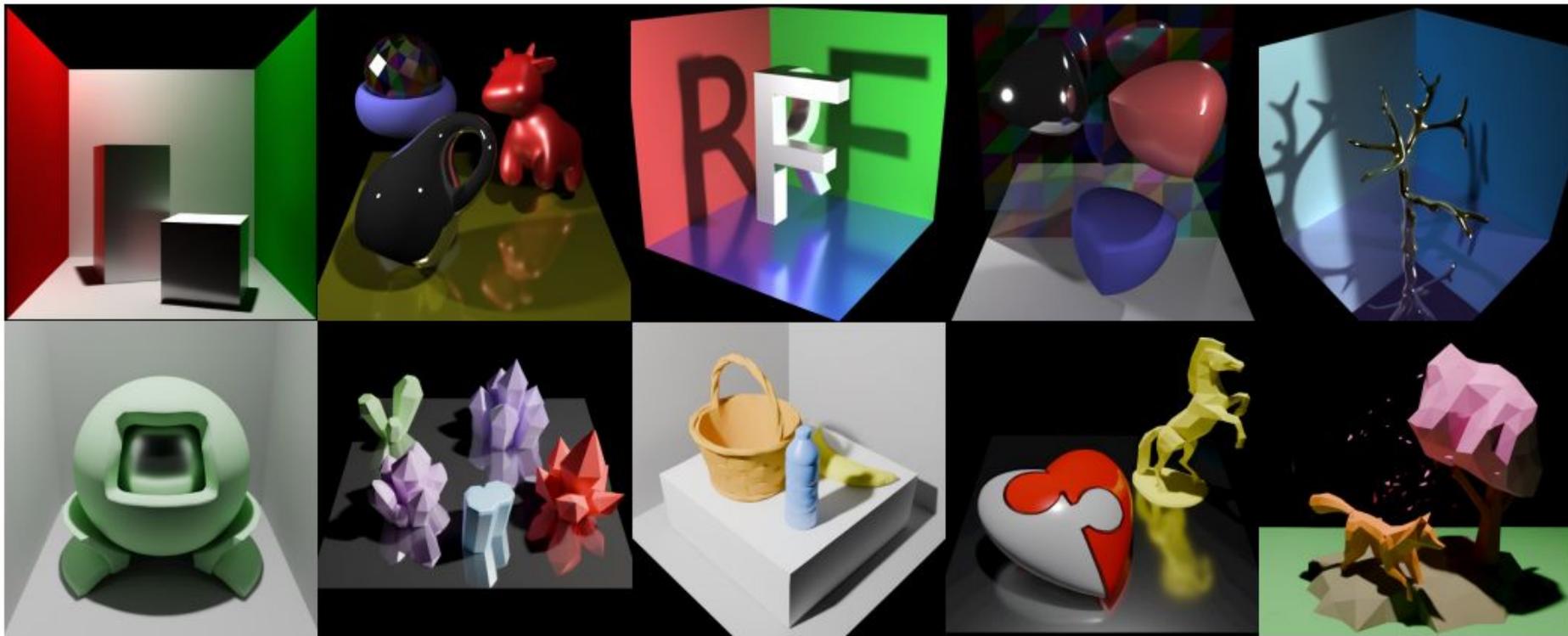
30-60

Camera FOV

1.5-2.0

Camera Distance

Visual Results – Static Scene Rendering



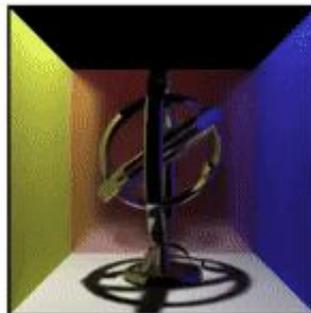
Visual Results – Dynamic Scene Rendering



Cascade Cube Animation
Tycho Magnetic Anomaly



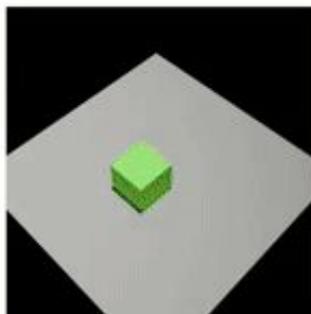
Animated Crab
Bohdan Lvov



Gyroscope Motion
redification



Animated Character
mortaleiros

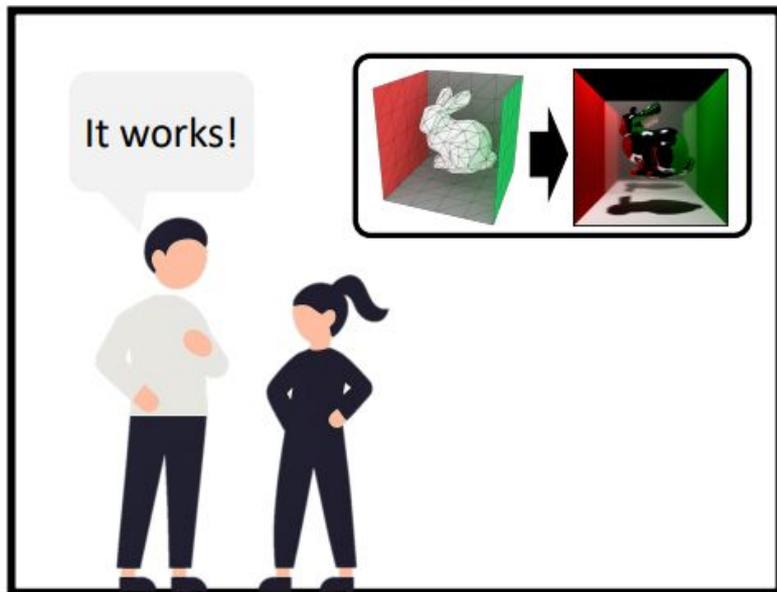


Marching Cubes Animation
Tycho Magnetic Anomaly

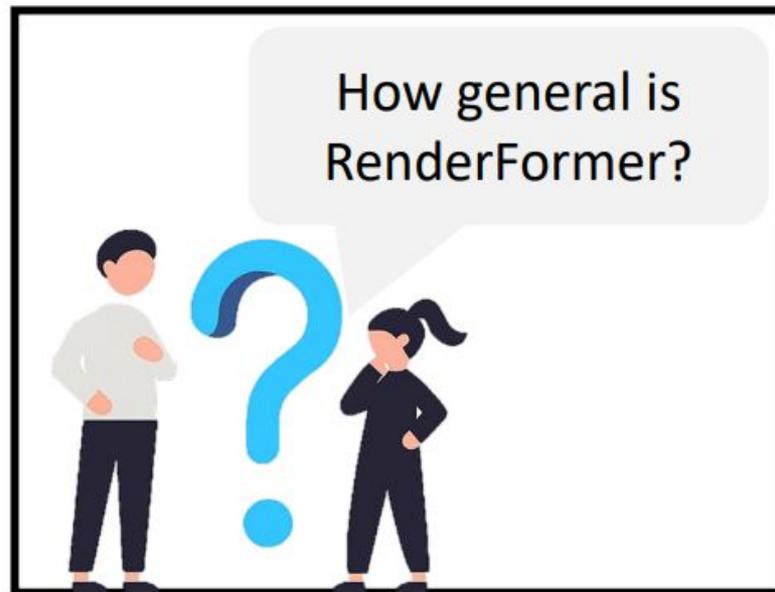


Robot Animation
Gouhadbuker

YES,

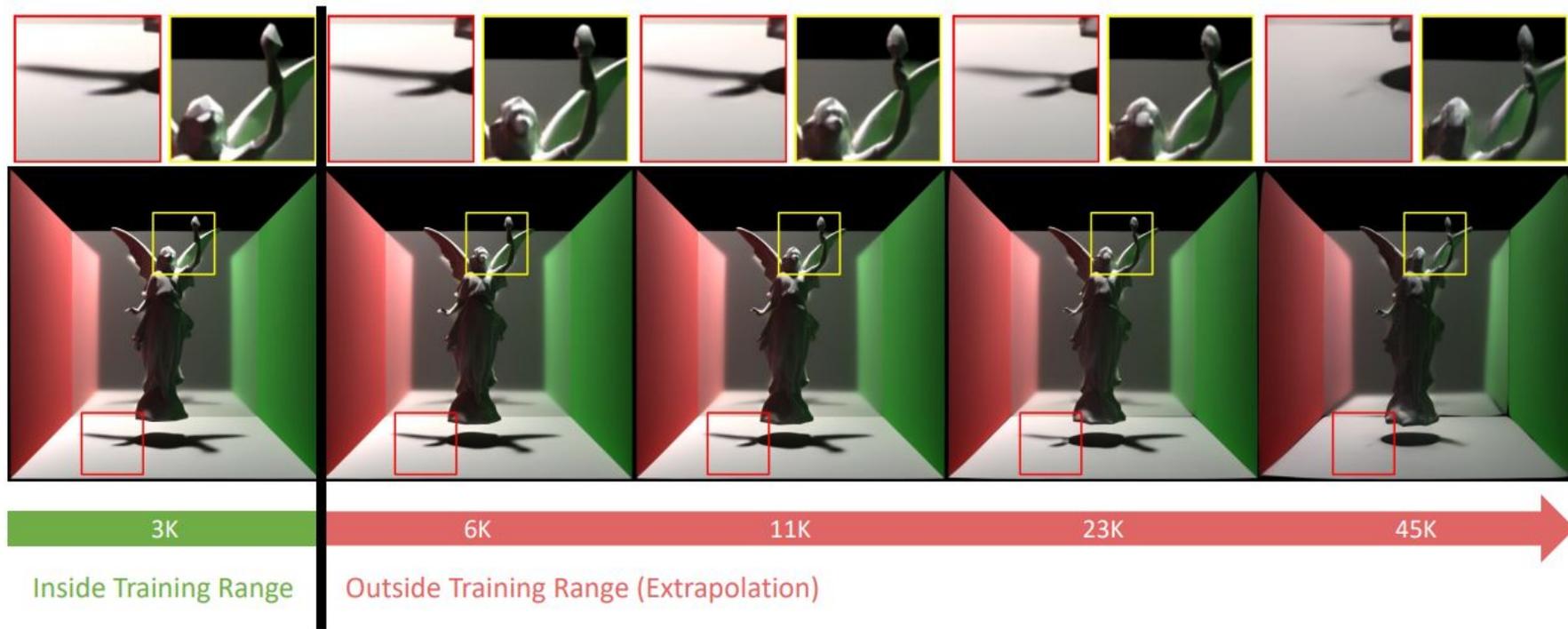


BUT

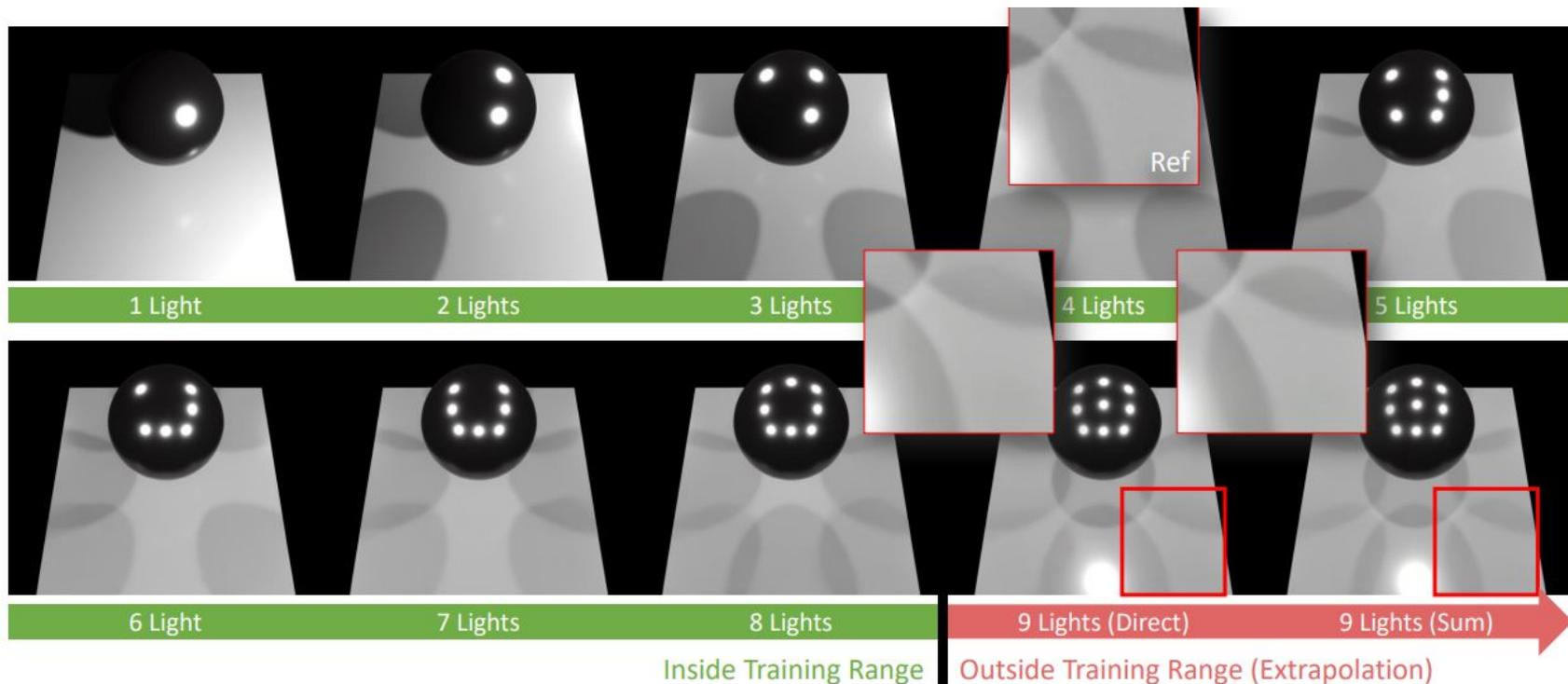


Limitations of RenderFormer

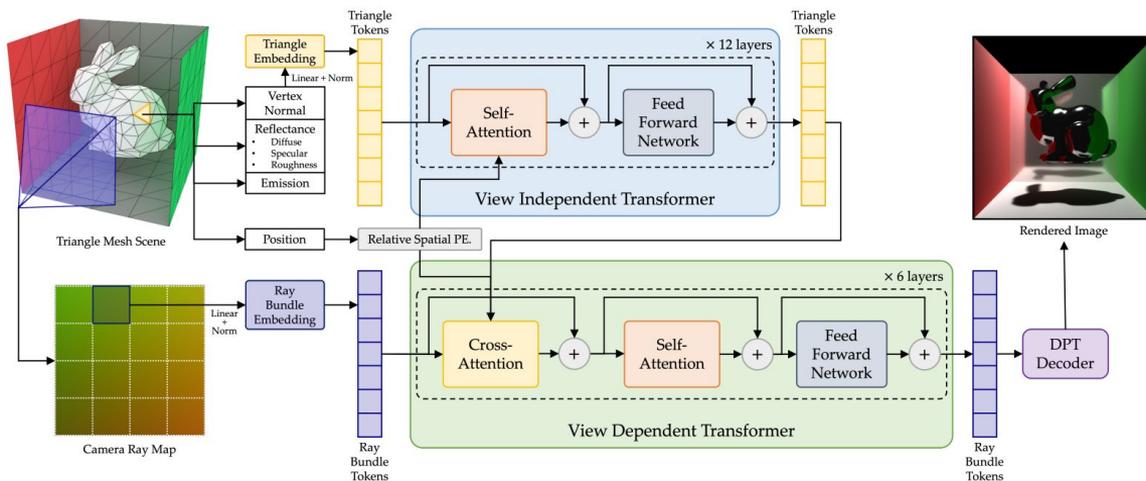
1. Generalization (# Triangles)



1. Generalization (# light resources)



2. Time complexity of Attention



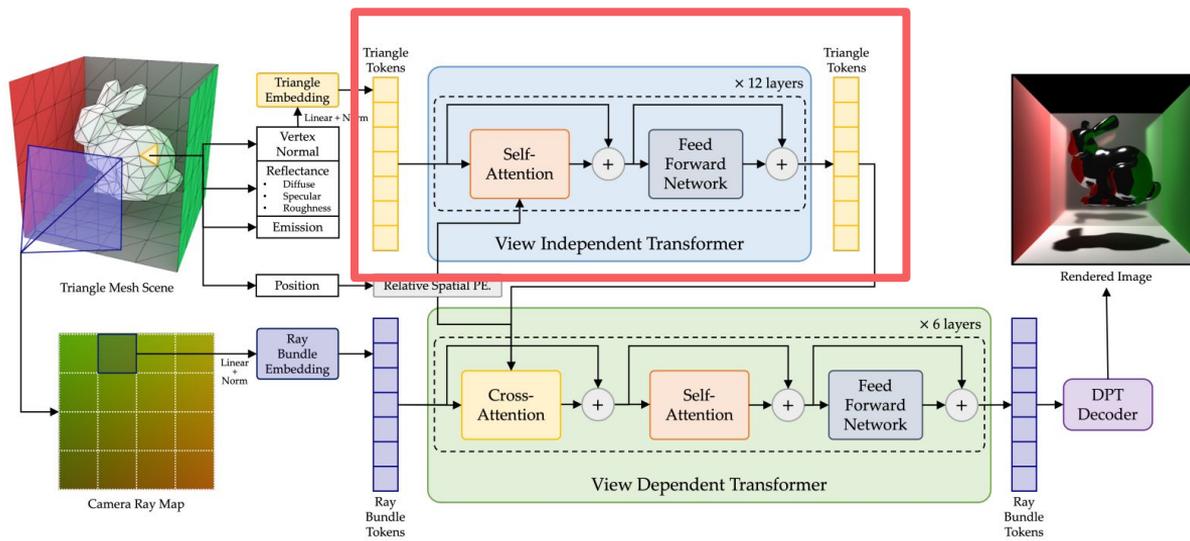
Layer Type	Complexity per Layer	Sequential Operations	Maximum Path Length
Self-Attention	$O(n^2 \cdot d)$	$O(1)$	$O(1)$
Recurrent	$O(n \cdot d^2)$	$O(n)$	$O(n)$
Convolutional	$O(k \cdot n \cdot d^2)$	$O(1)$	$O(\log_k(n))$
Self-Attention (restricted)	$O(r \cdot n \cdot d)$	$O(1)$	$O(n/r)$

n = sequence length

d = dimension

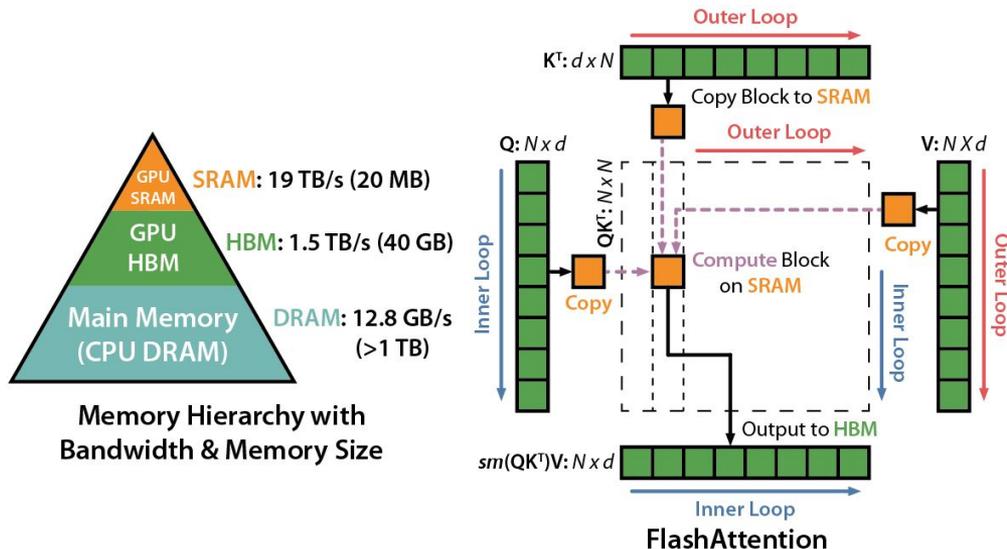
k = kernel size of convolutions

Time complexity of Renderformer



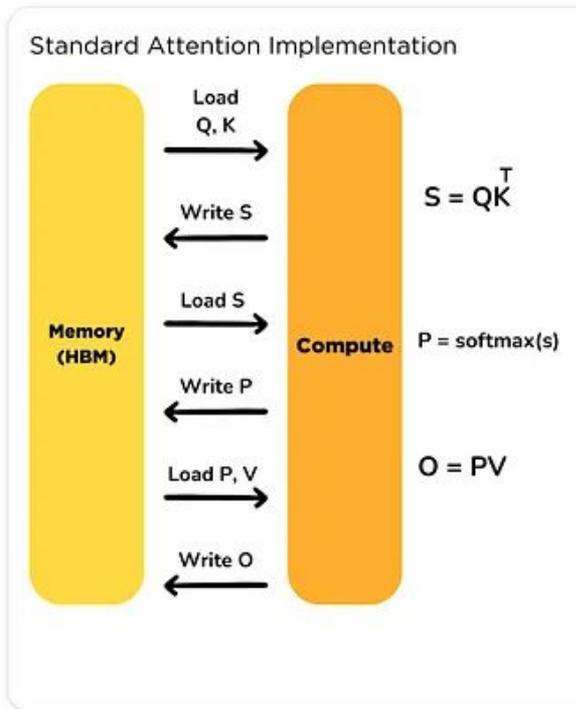
- The view-dependent stage's time complexity is roughly by $O(\#\text{Bundle}^2)$
- The view-independent stage's time complexity is roughly by $O(\#\text{tri}^2)$
- Because of this, limit the total number of triangles in scenes to 4,096

Actually, they used Flash Attention-2



- They used FA-2 which can help to reduce calculation time and memory usage.
- Flash attention is attention algorithm that tiles softmax-attention to on-chip SRAM.

How Flash Attention work?

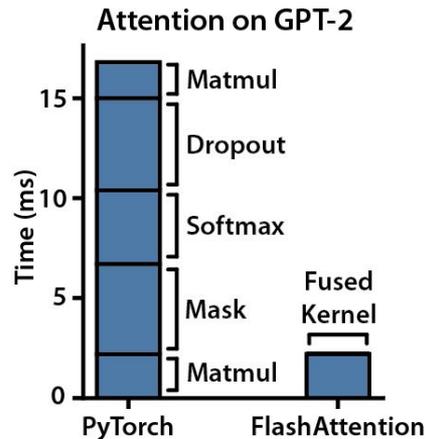
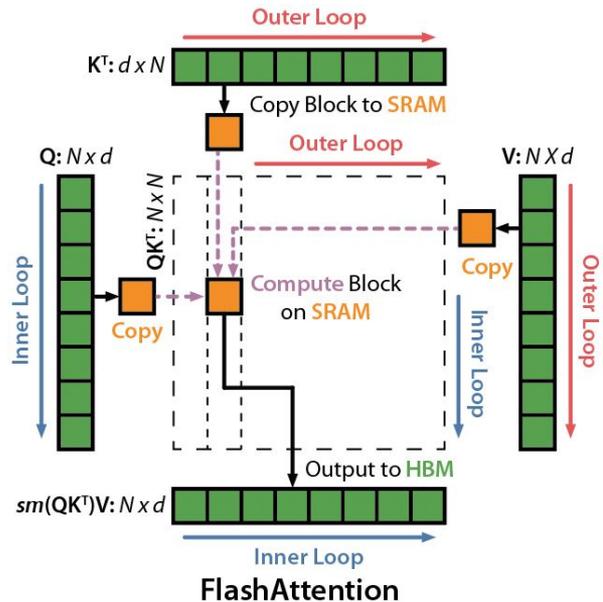
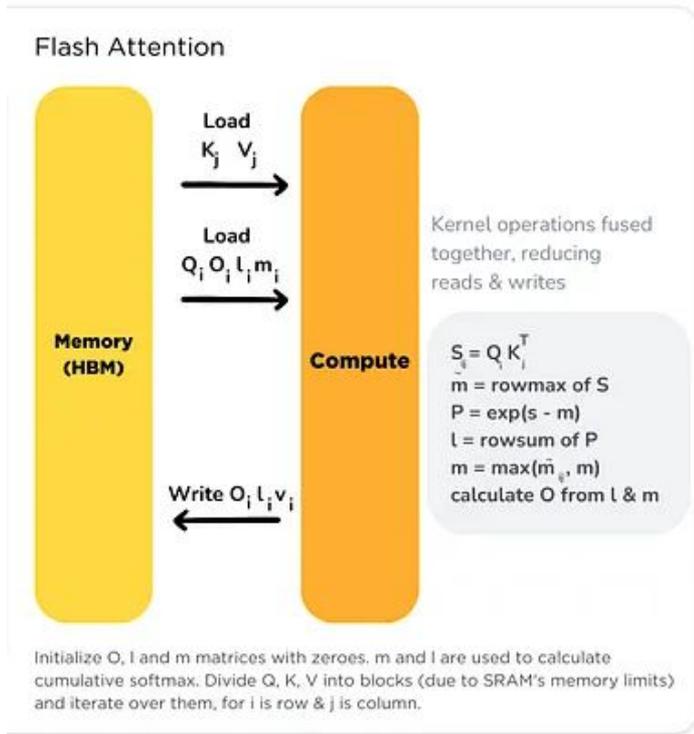


Algorithm 0 Standard Attention Implementation

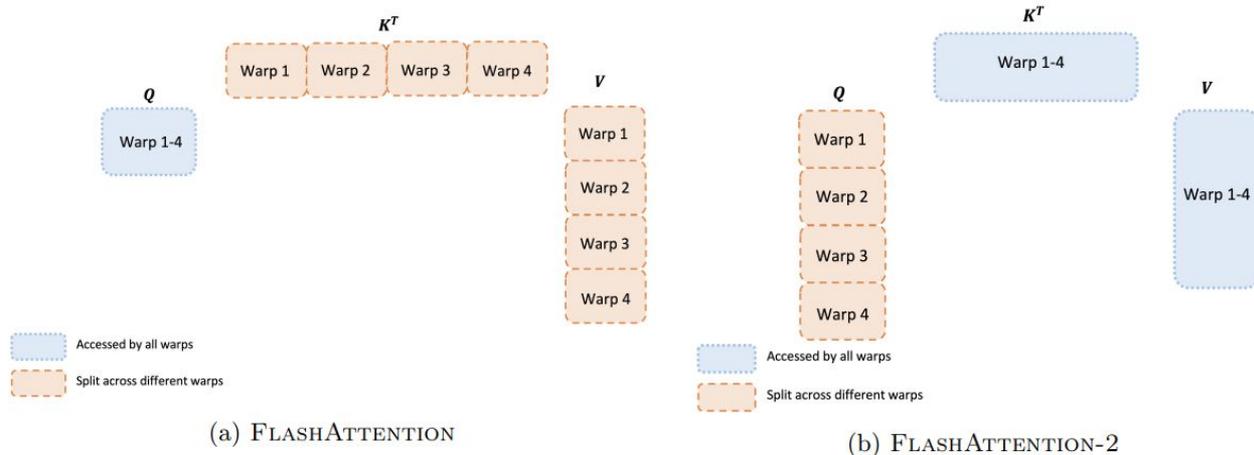
Require: Matrices $Q, K, V \in \mathbb{R}^{N \times d}$ in HBM.

- 1: Load Q, K by blocks from HBM, compute $S = QK^T$, write S to HBM.
 - 2: Read S from HBM, compute $P = \text{softmax}(S)$, write P to HBM.
 - 3: Load P and V by blocks from HBM, compute $O = PV$, write O to HBM.
 - 4: Return O .
-

How Flash Attention work?

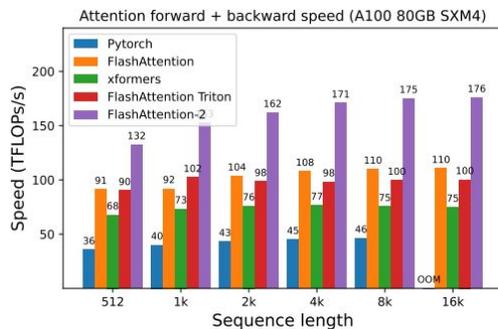


Improvement of Flash Attention-2

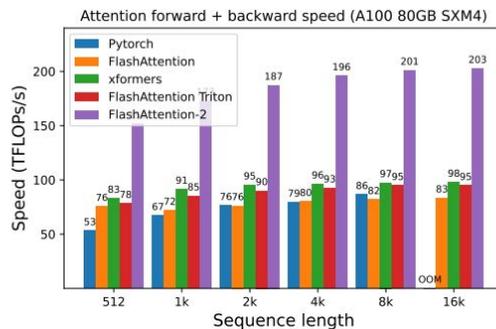


- Flash attention-2 make more fast speed by modifying the process to split Q and share K and V, eliminating the need for continuous synchronization of intermediate calculation results, instead of splitting K and V.

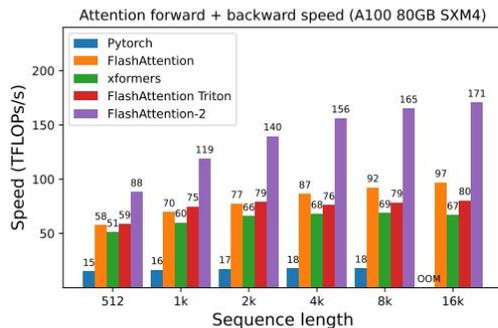
Result of Flash Attention-2



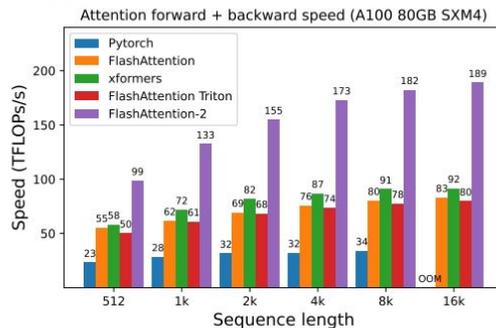
(a) Without causal mask, head dimension 64



(b) Without causal mask, head dimension 128



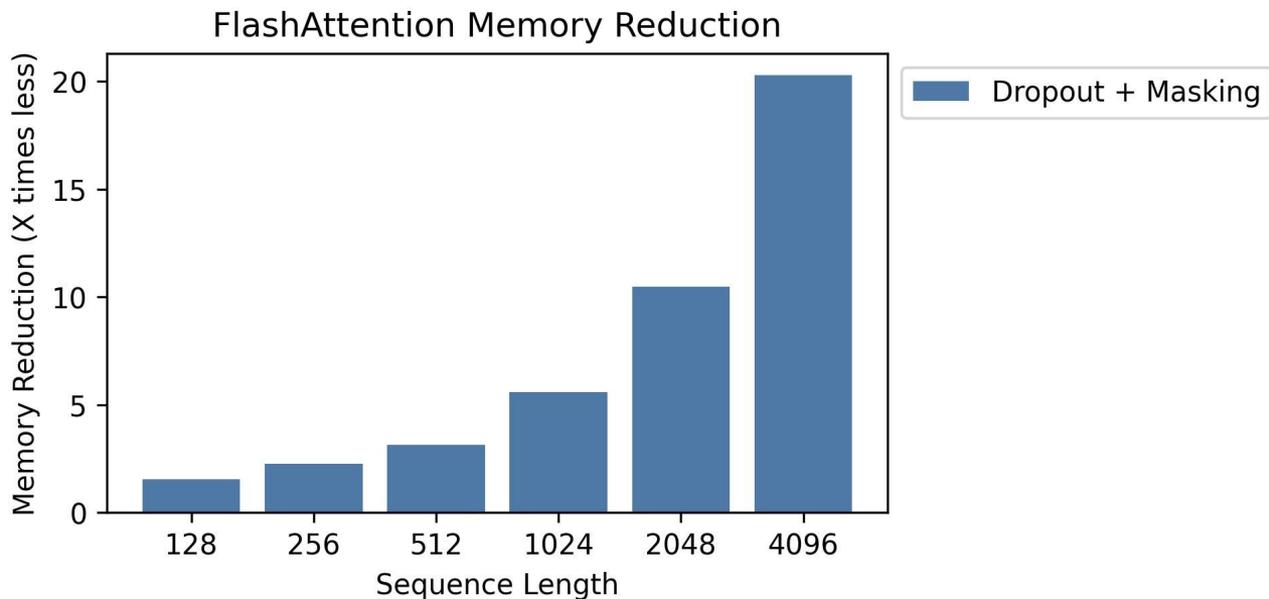
(c) With causal mask, head dimension 64



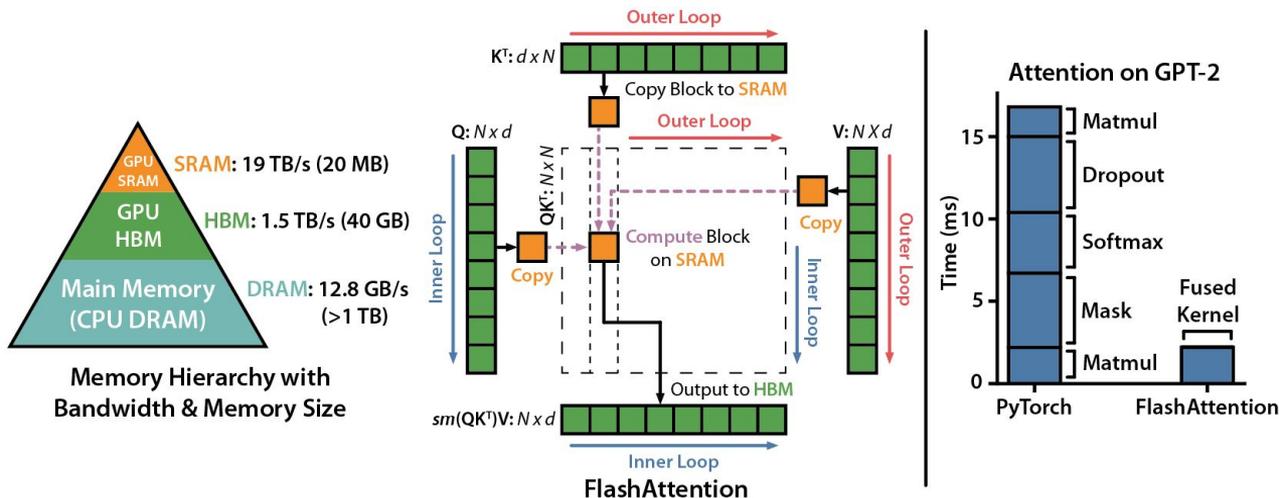
(d) With causal mask, head dimension 128

Figure 4: Attention forward + backward speed on A100 GPU

Result of Flash Attention-2



Limitation of Flash Attention-2

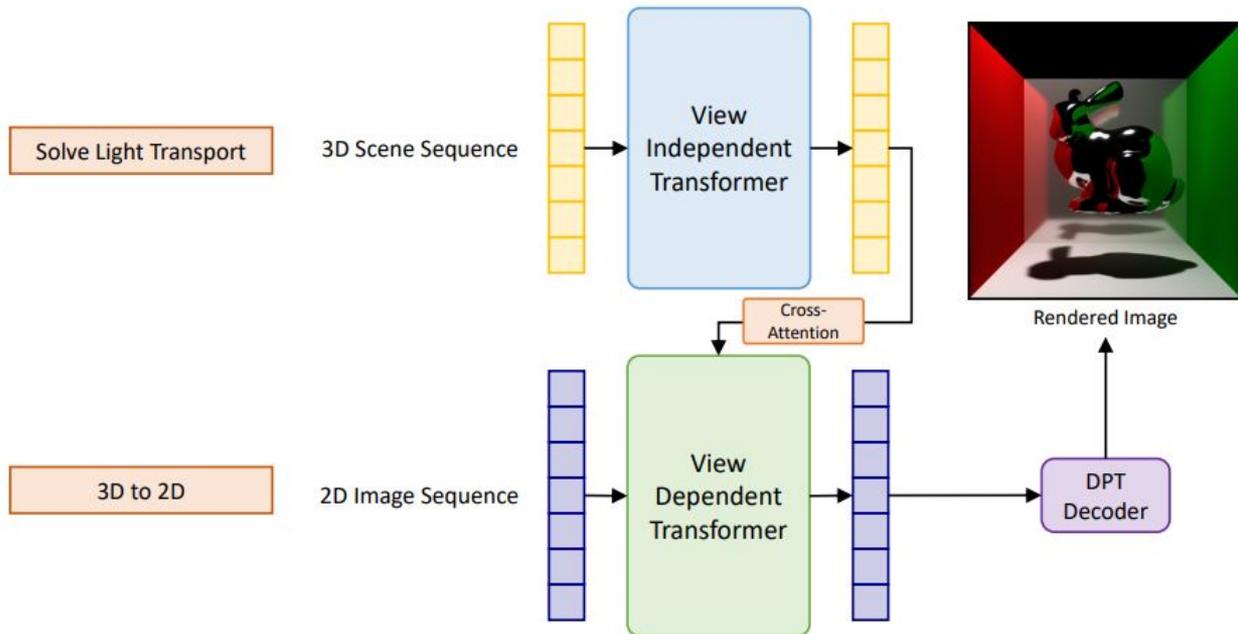


- Although they used FA-2 which can help to calculation time, its asymptotic time complexity is same.
- Thus, we need other approach for resolve this issue.

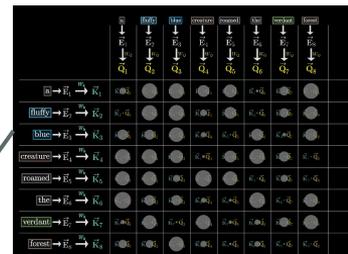
Our Plan

The Use of Original Transform Architecture

Both stages closely follow the original transformer architecture [Vaswani et al. 2017]



How Attention can be Computed Faster



$L \times L$

$L \times d$ $d \times L$ $L \times d$

$$\text{Attention}(Q, K, V) = \text{softmax} \left(\frac{Q \cdot K^T}{\sqrt{d_k}} \right) \cdot V$$

L - length of the sequence

d - # dimension of the sequence

How Attention can be Computed Faster

$$\text{Attention}(Q, K, V) = \text{softmax} \left(\frac{Q \cdot K^\top}{\sqrt{d_k}} \right) \cdot V$$

$L \times L$
 $L \times d \quad d \times L \quad L \times d$

- The view-independent stage scales roughly by $O(\#tris^2)$
- view-dependent layers scales by $O(\#bundles^2 + \#bundles \times \#tris)$.

How Attention can be Computed Faster

$$\text{Attention}(Q, K, V) = \text{softmax} \left(\frac{Q \cdot K^\top}{\sqrt{d_k}} \right) \cdot V$$

$L \times L$
 $L \times d \quad d \times L \quad L \times d$
 $d \times L \quad L \times d$
 $d \times d$



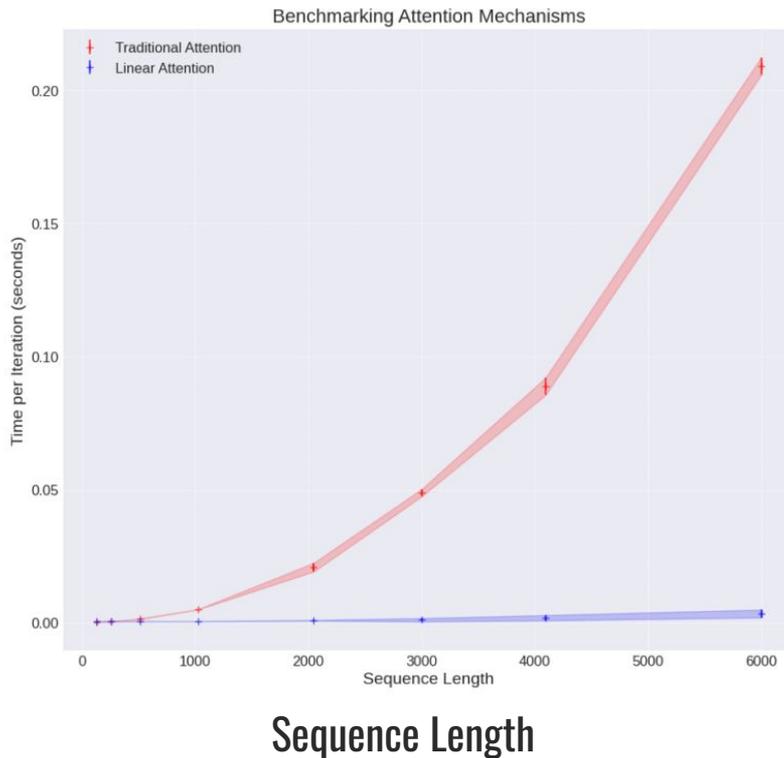
$d = 768$ (dimension of input sequence)

$L = 4,096$ (# triangles)

As long as $d \ll L$, significantly faster

Potential Speedup from Linear Attention

Time per Iteration (seconds)



1D sequences or 2D images



Our Plan

- Rewrite the **Inference** Part with Linear Attention or Performer
- Compare the Inference Speed and Rendering Result with the original
- Try **training** with Linear Attention or Performer
- Compare the Training Speed and Rendering Result with the original

Q&A

Quiz Time

