



Playing with Collisions

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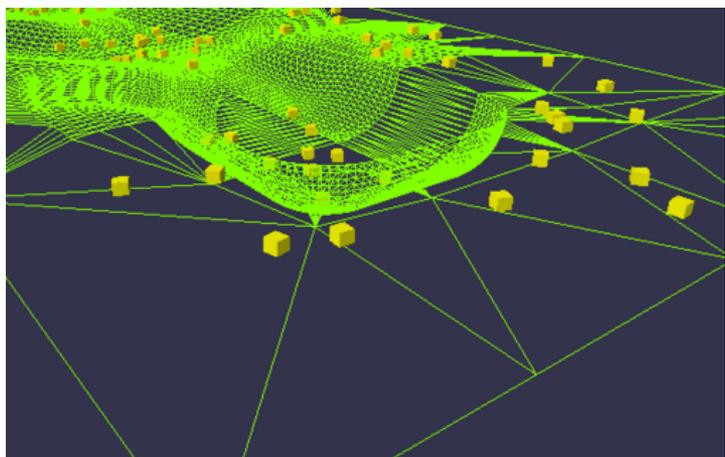
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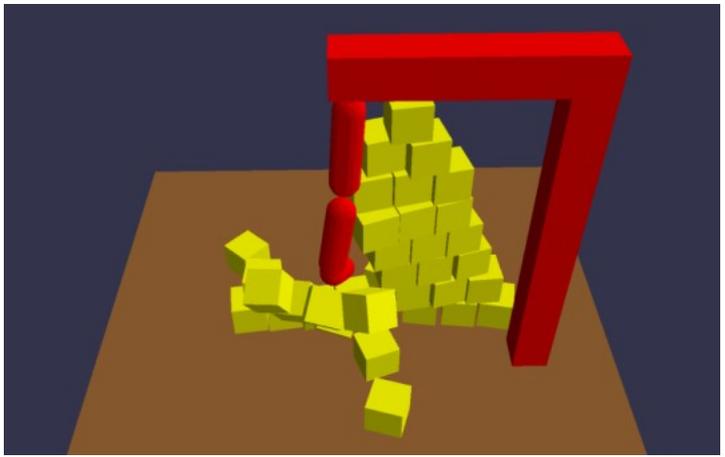
Current Game Physics



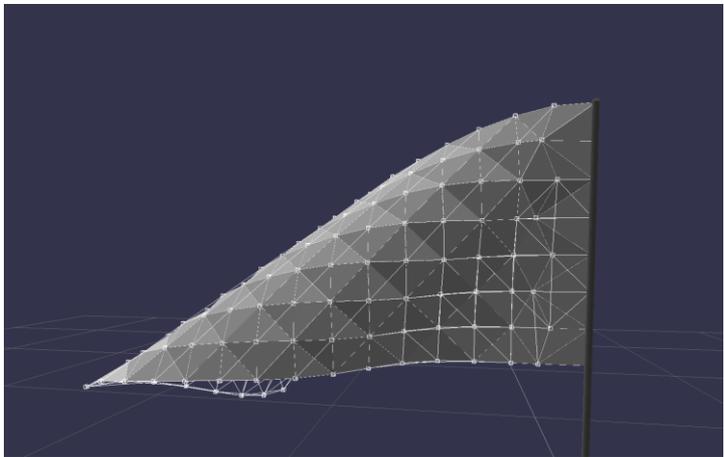
Avoiding Interpenetration



Object Motion



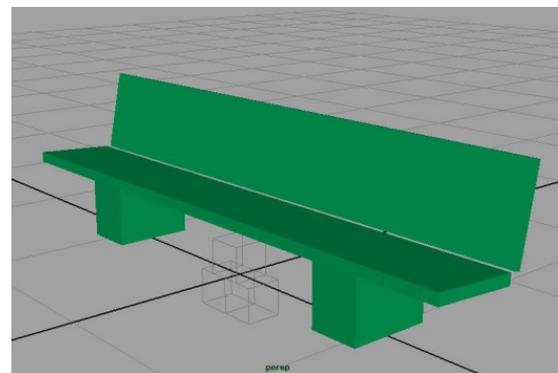
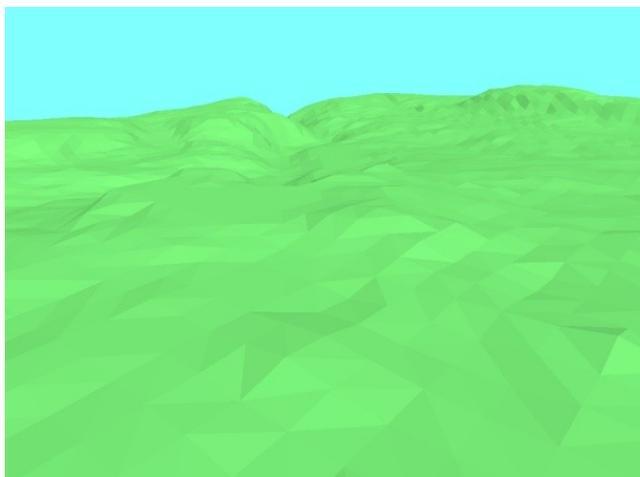
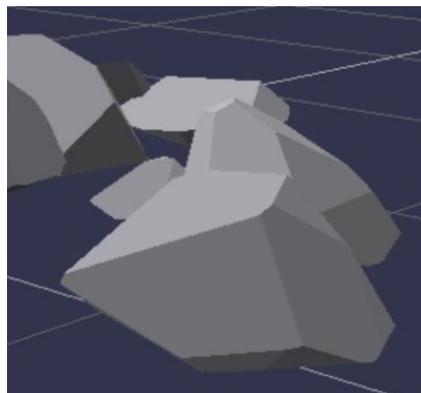
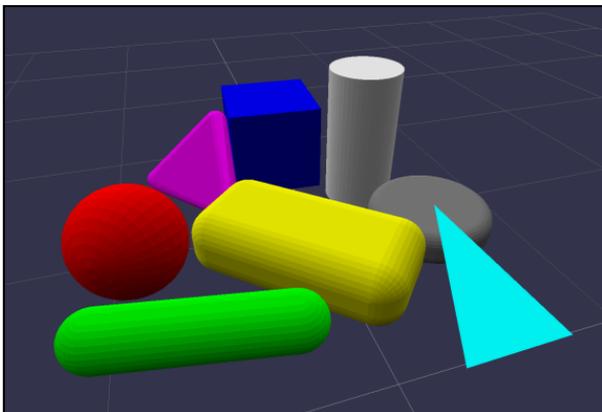
Simulate Stacking and Joints



Cloth and Clothing

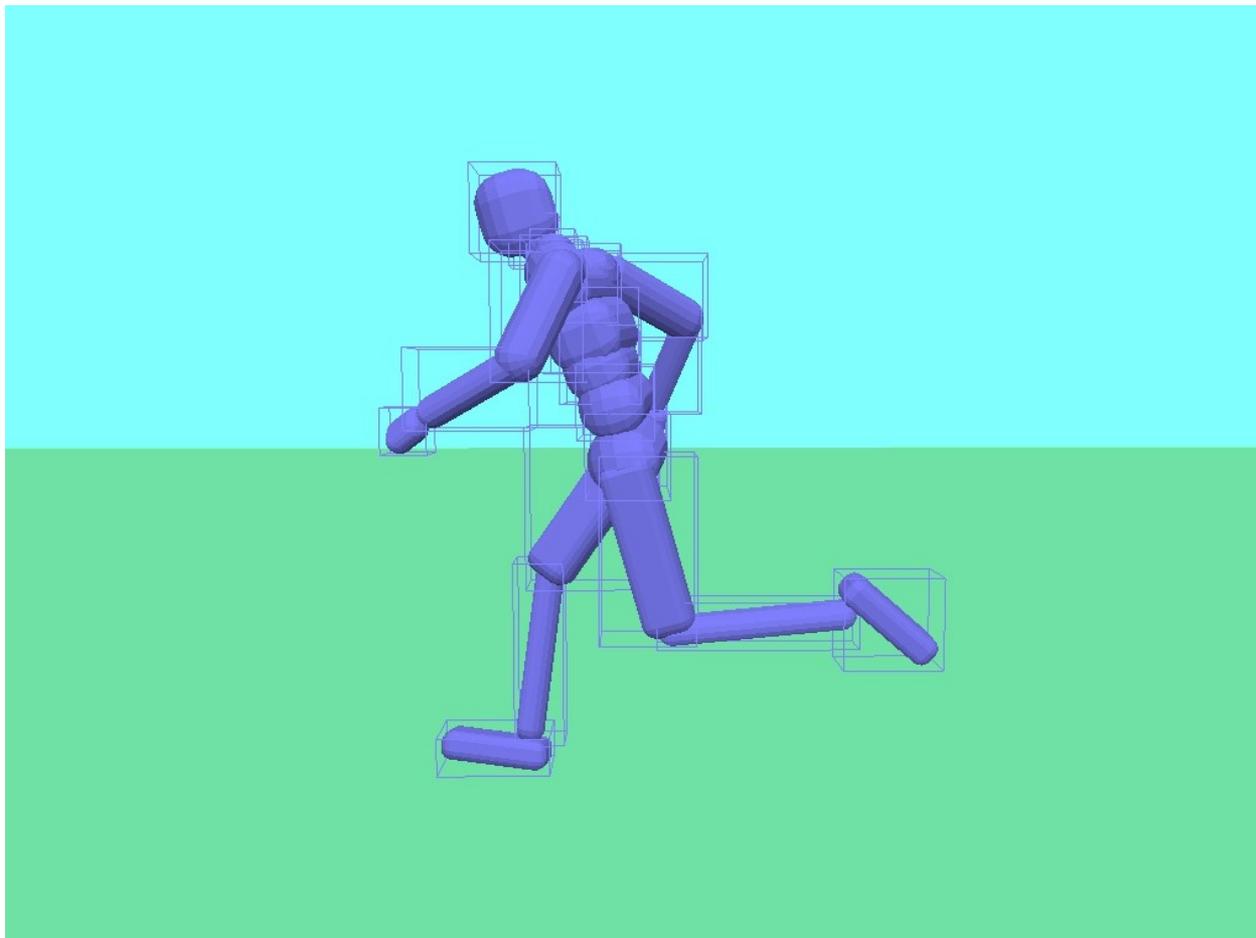


Collision Shapes



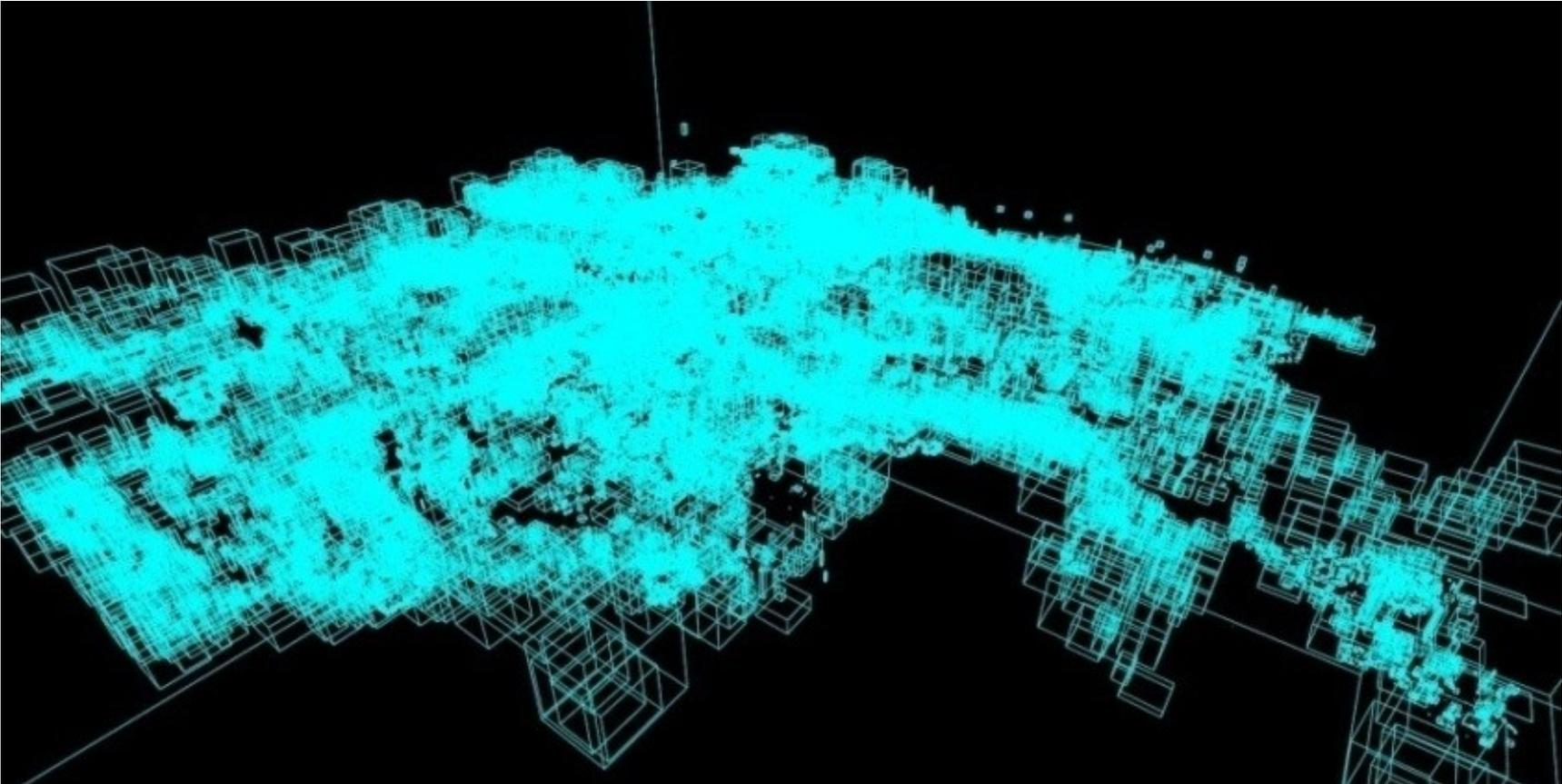


Bounding Volumes



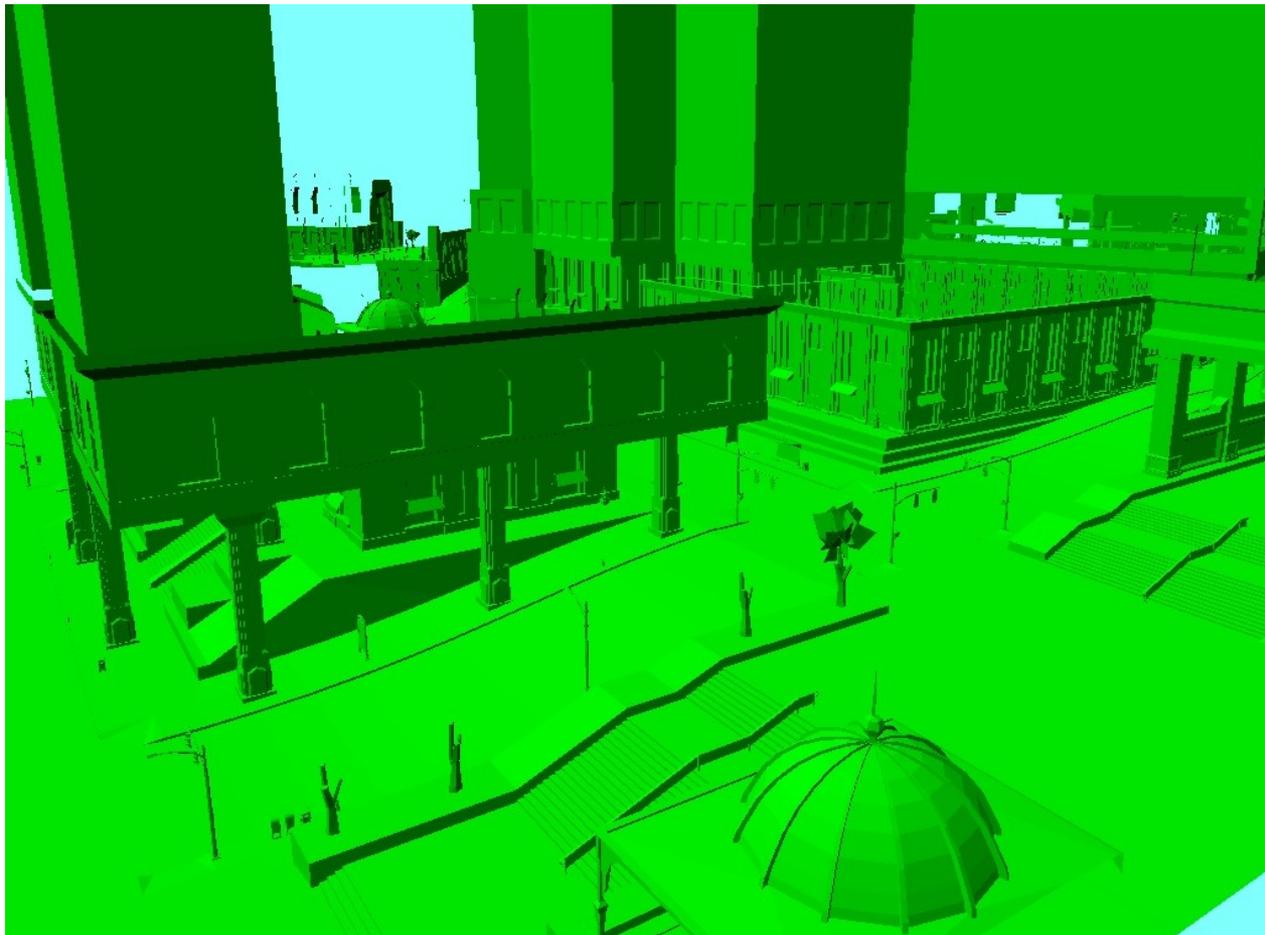


Broad Phase



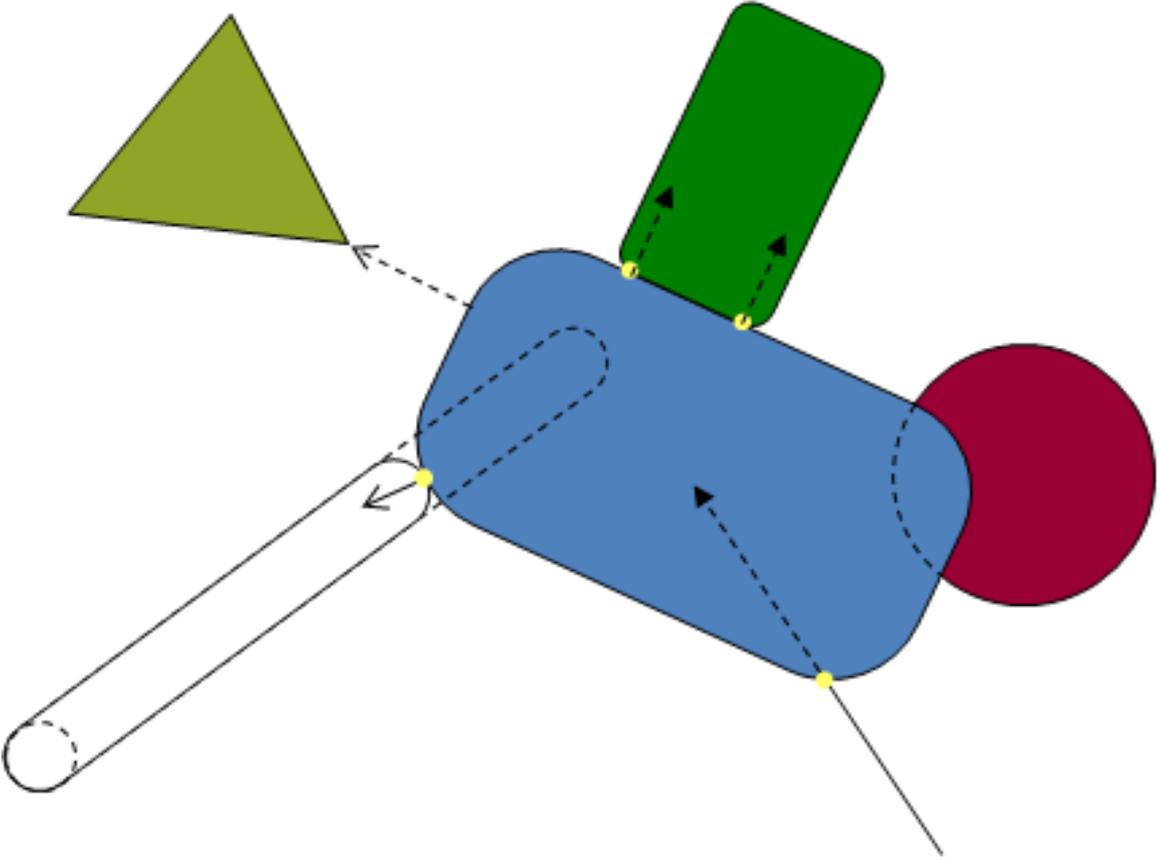


Mid Phase



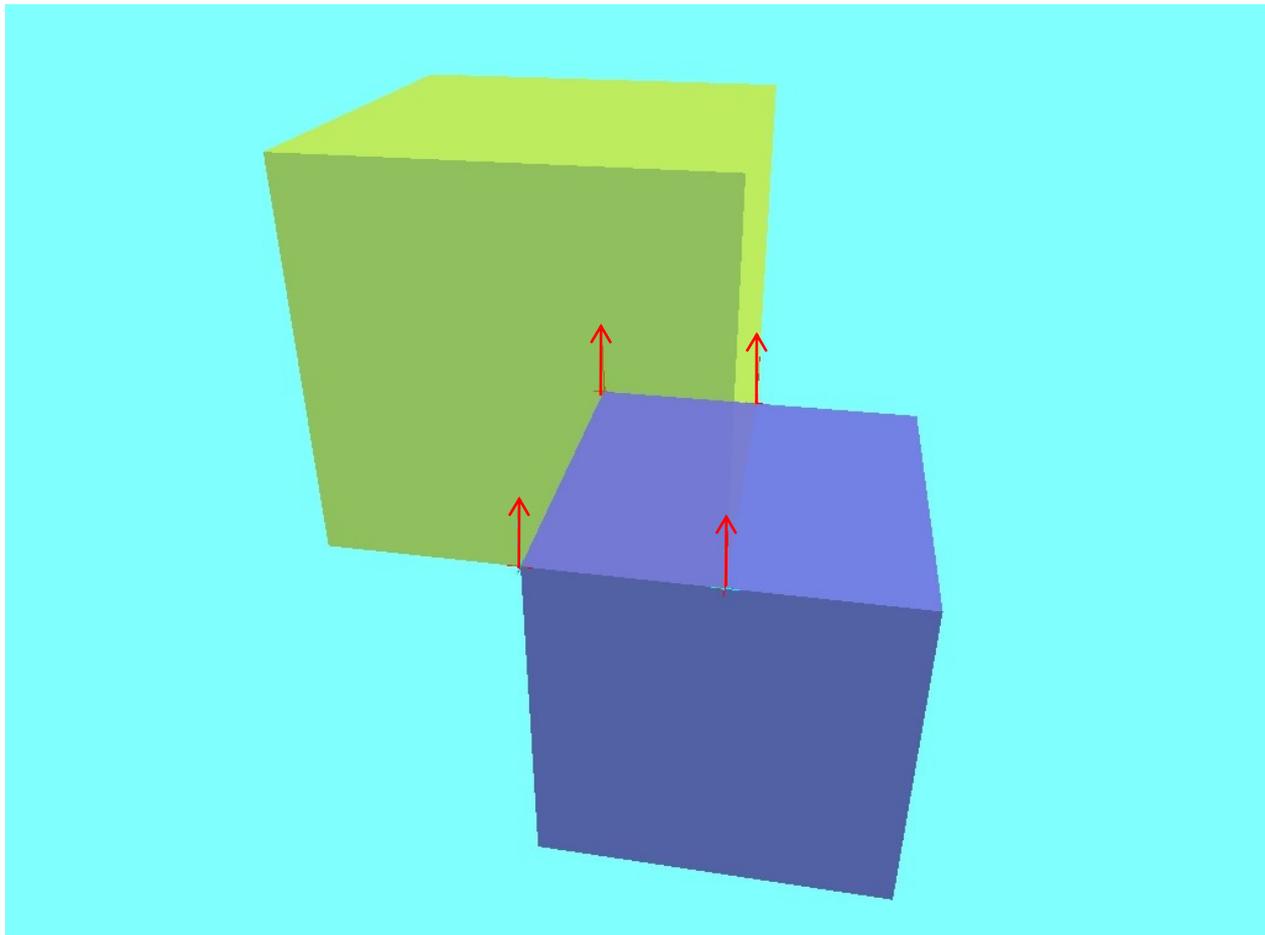


Narrow Phase



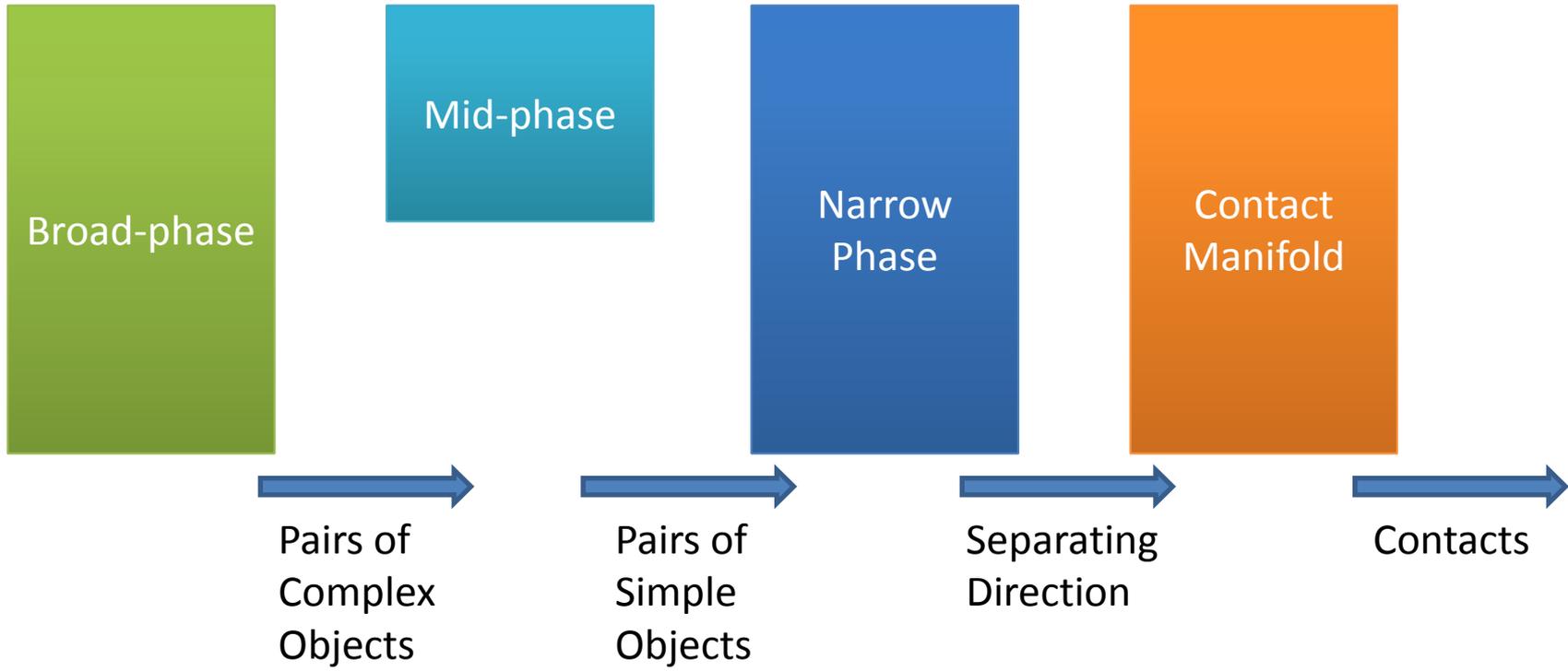


Contact Manifolds





Typical Pipeline





Typical Pipeline

Sweep &
Prune

Kd-Tree

GJK

Incremental
Manifold

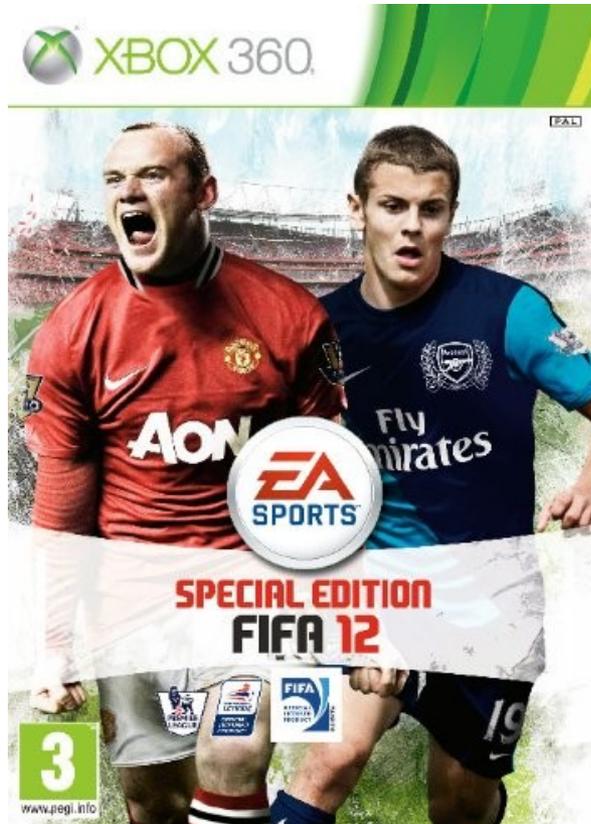


Typical Pipeline





FIFA Example



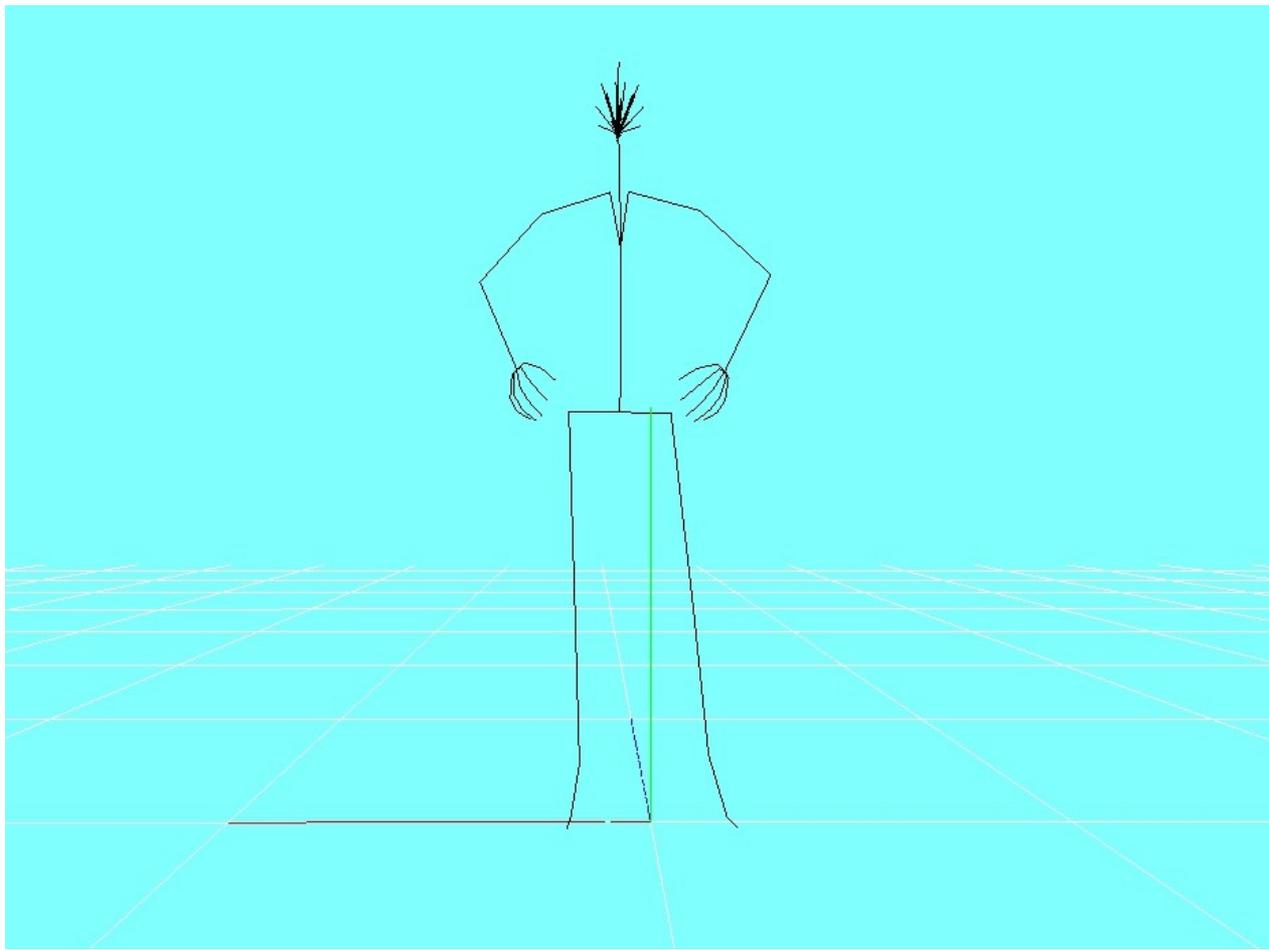


FIFA Example

- Small number of players
- Simple environment
- High level of detail in simulation

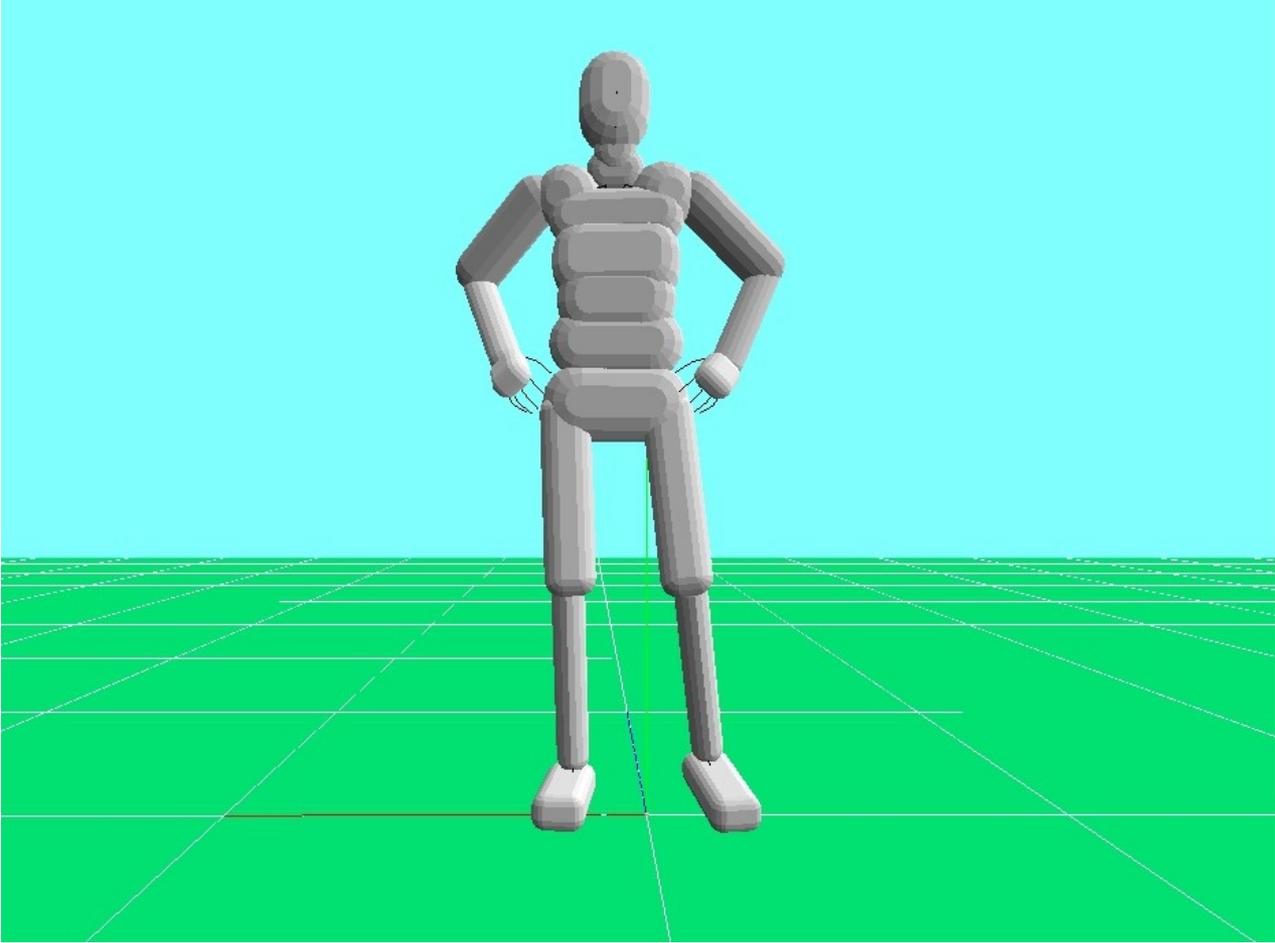


Animation Skeleton



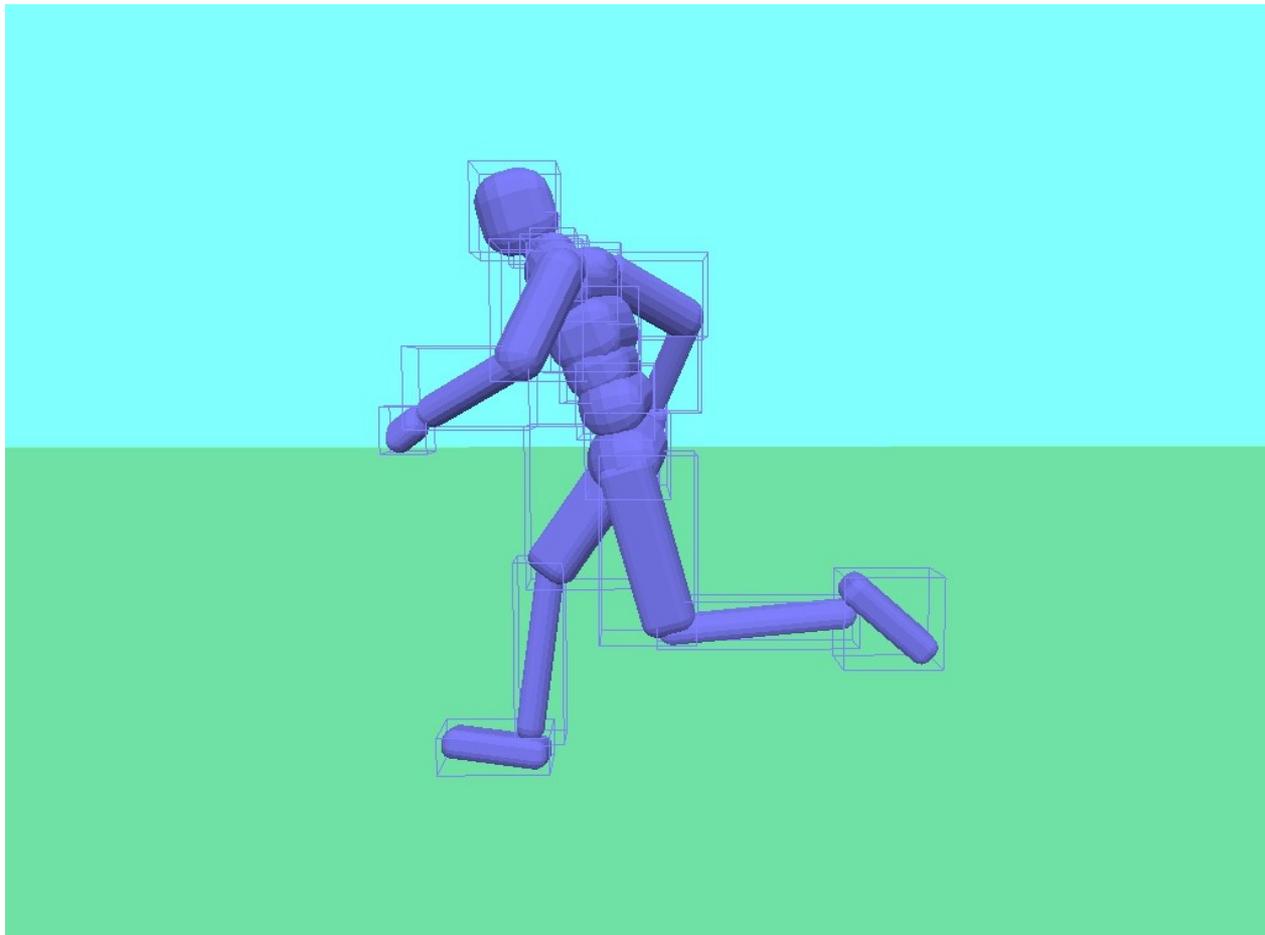


Ragdoll



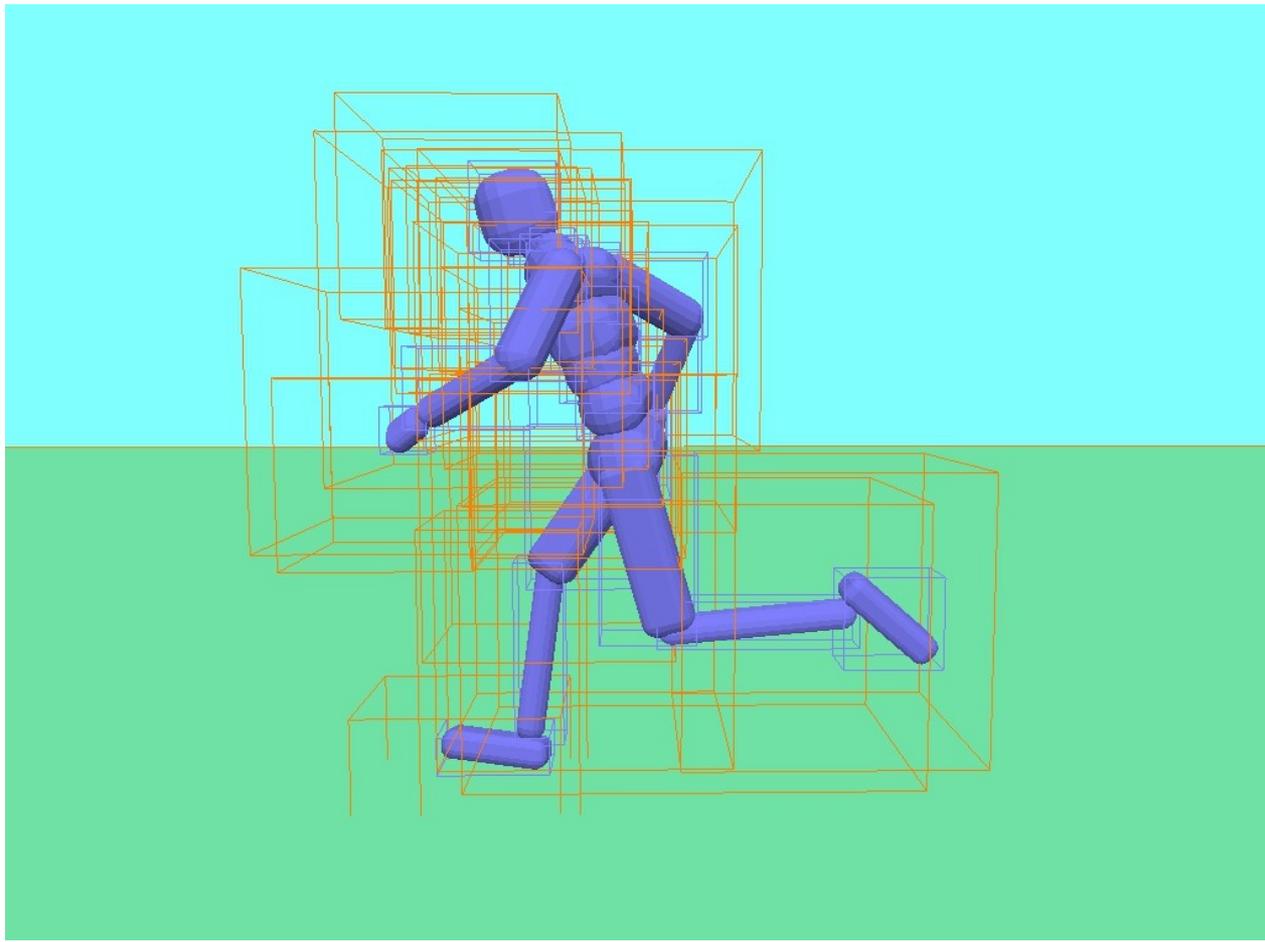


BBoxes



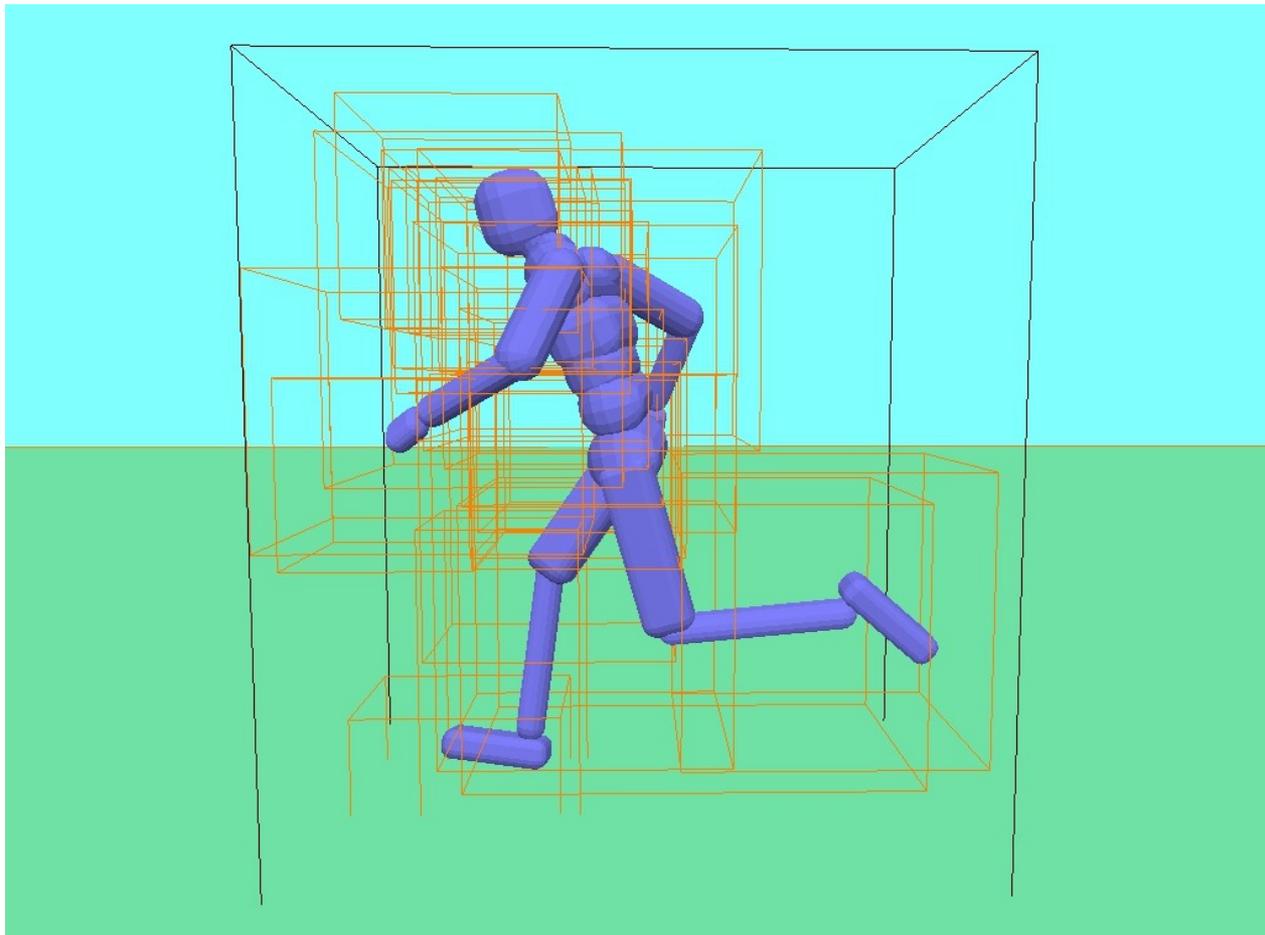


Padding





Clumps





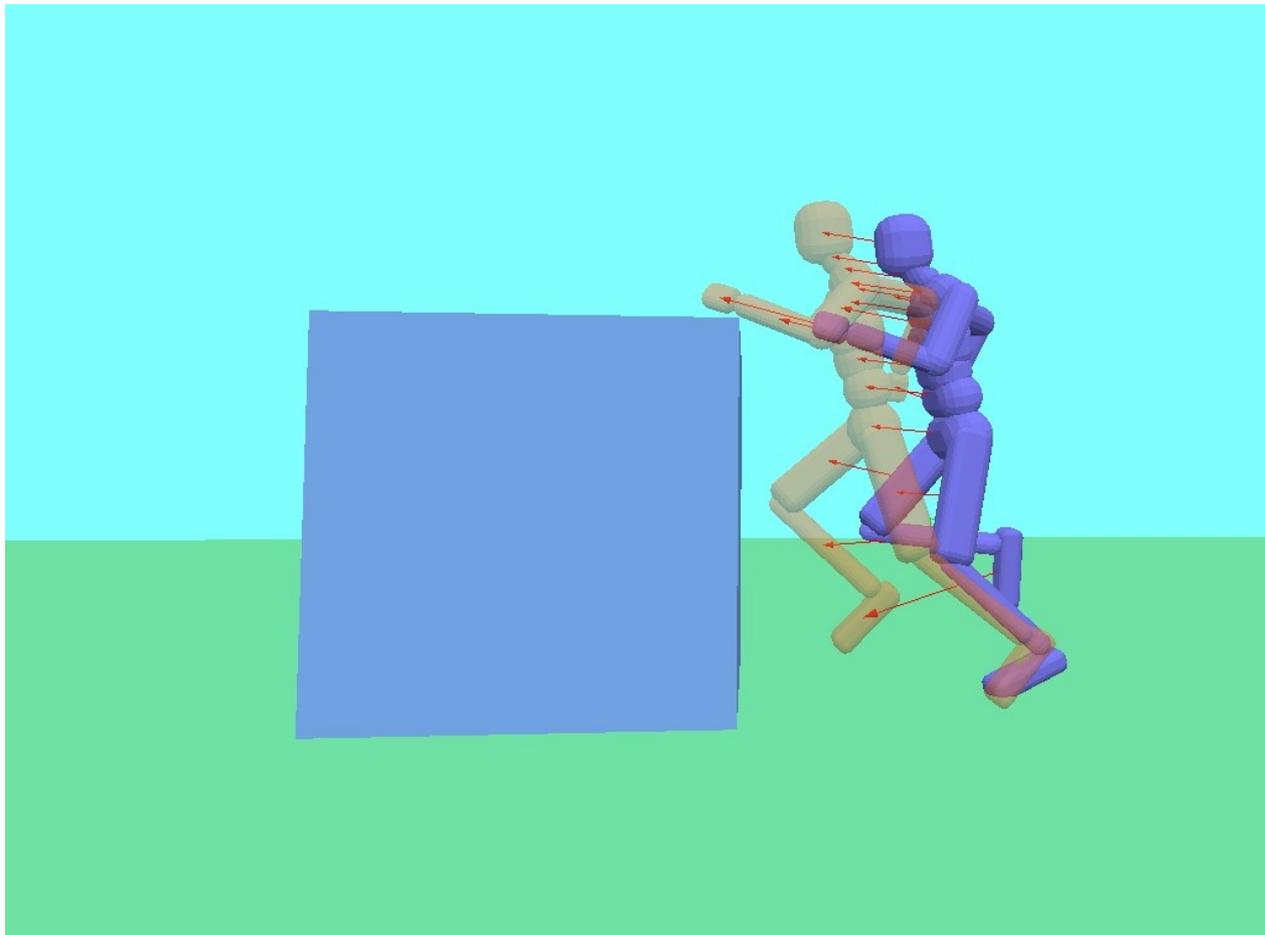
Brute Force

	1	2	3	4	5	6	7	8	9
1				X					
2									
3						X	X		
4									
5									
6							X		
7									
8									
9									

$(N^2 - N) / 2$ ok as long as $N \ll 100$



Swept Queries





Contact Generation

- Simple primitives
- Frames of change are key points of interest
- No stacking
- Contacts tend to be transitory



FIFA Pipeline

Clumped
Brute Force

Swept
Queries

Primitive
SAT

Full
Manifold



FIFA Video

- <http://www.youtube.com/watch?v=xVYnjMc1Z9k>



Challenges

- Many contacts in ragdoll-ragdoll collision
- Padded contacts/TOI make it even harder



SSX Example





SSX Example

- Lots of ray casting
- Flying carpet of terrain
- Multiple meshes: trees, rocks etc.

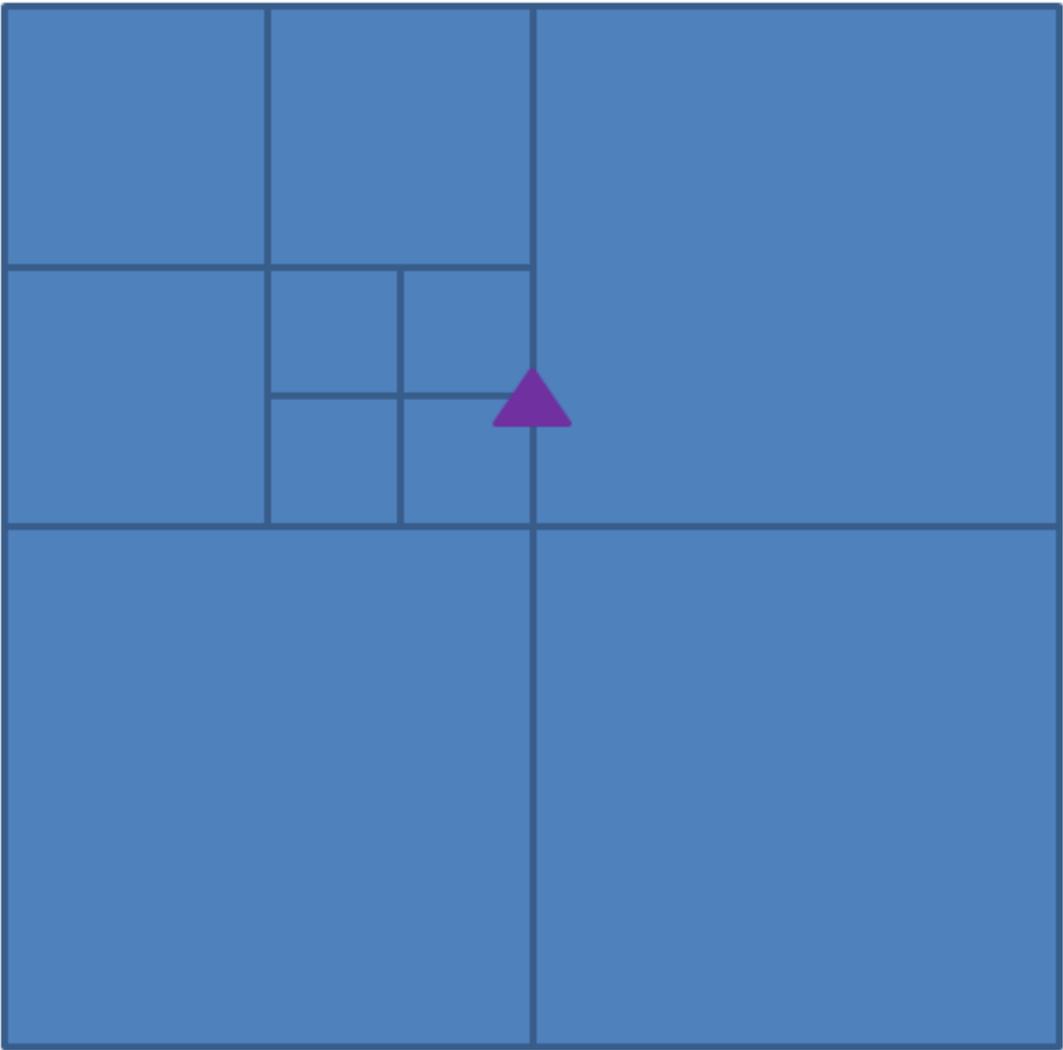


Octree Broad Phase

- Game Programming Gems 1
 - Thatcher Ulrich (2000)
- Add & remove is quick
- AABBBox & Line queries supported

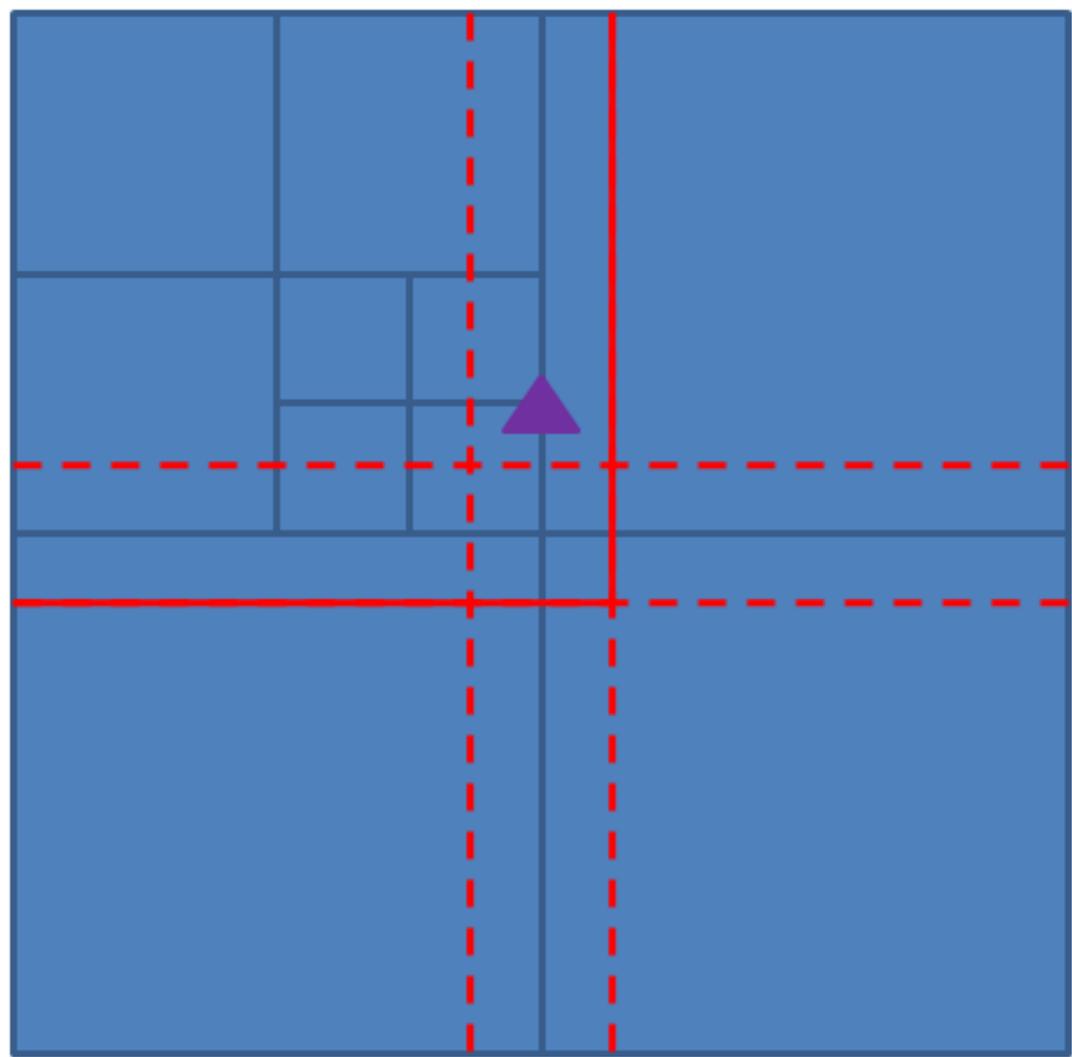


Octree Problem



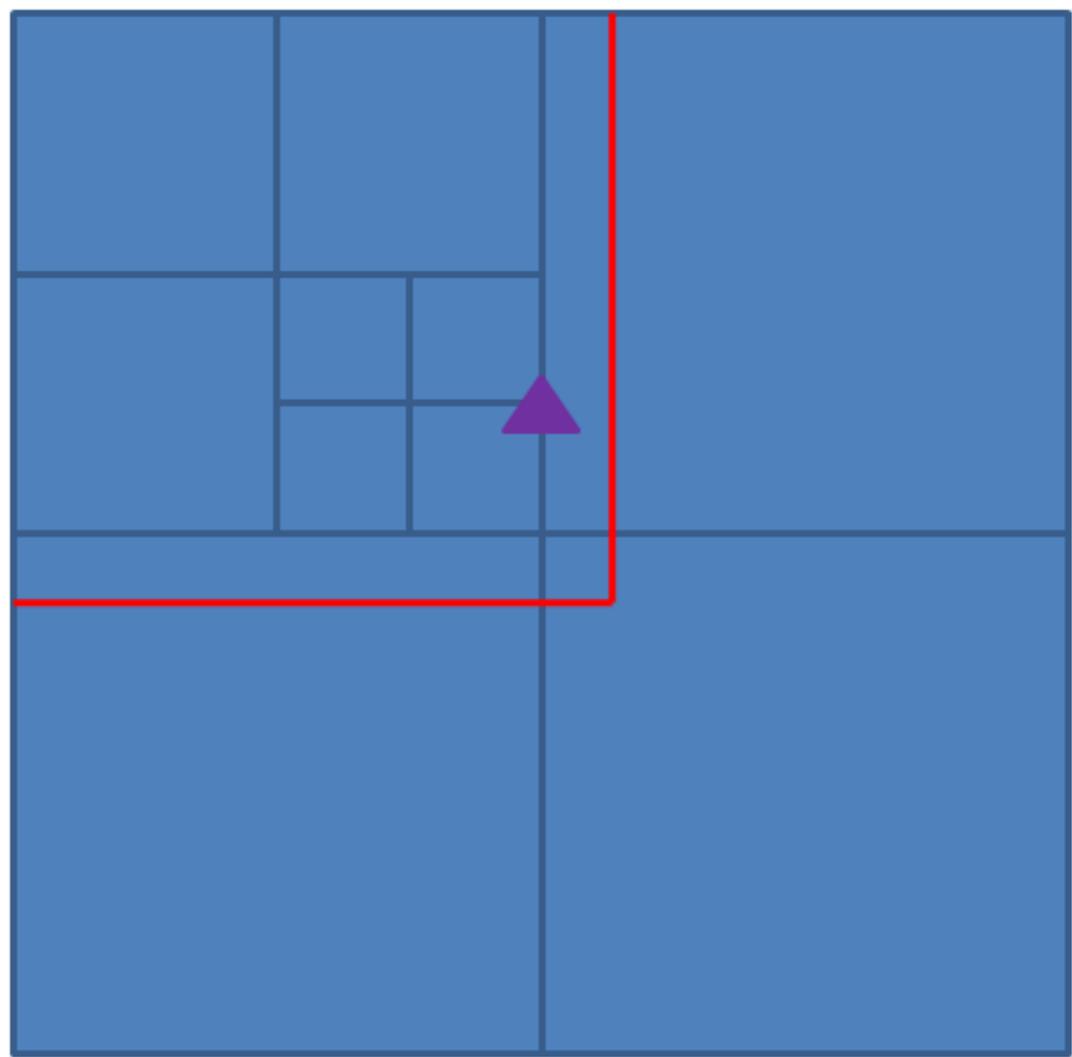


Loose Octree



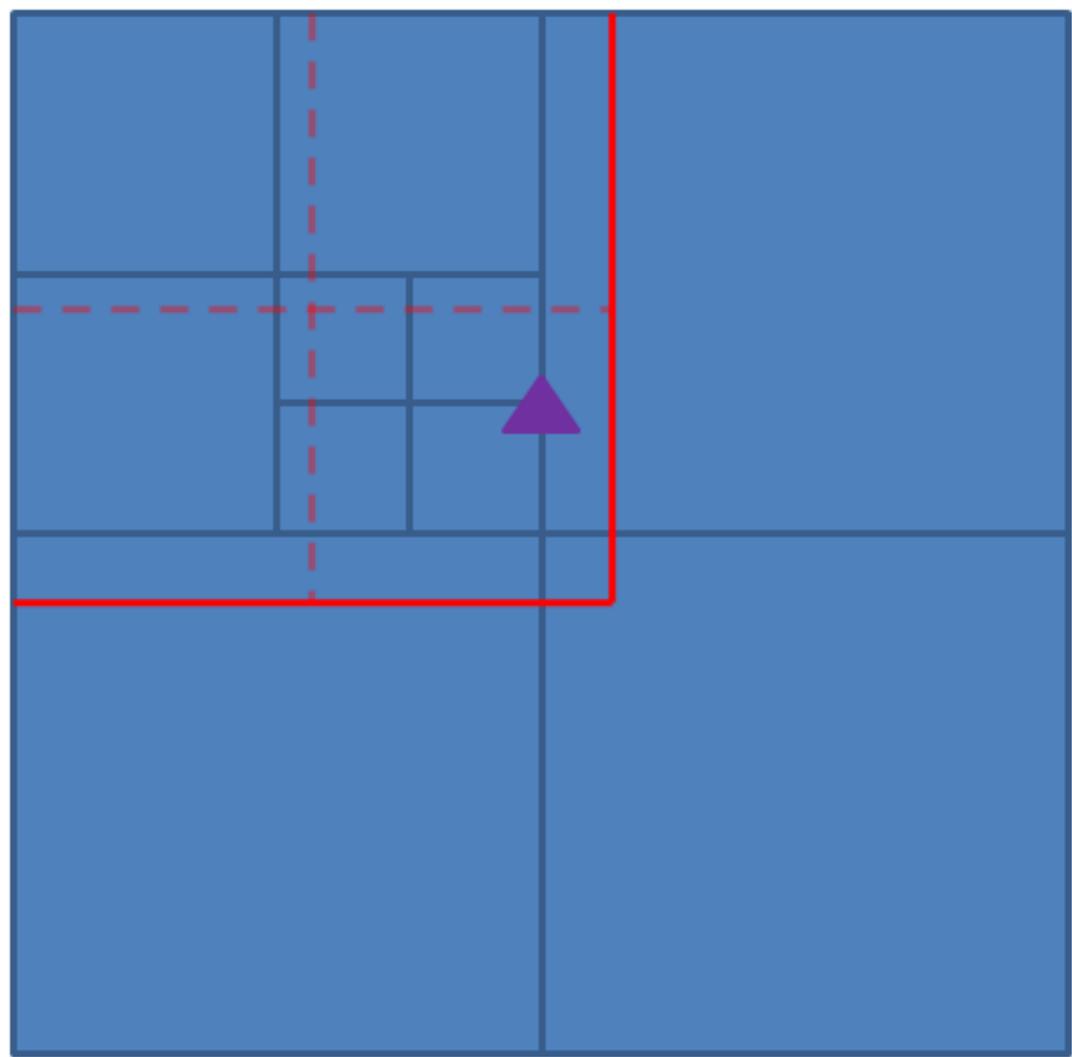


Loose Octree



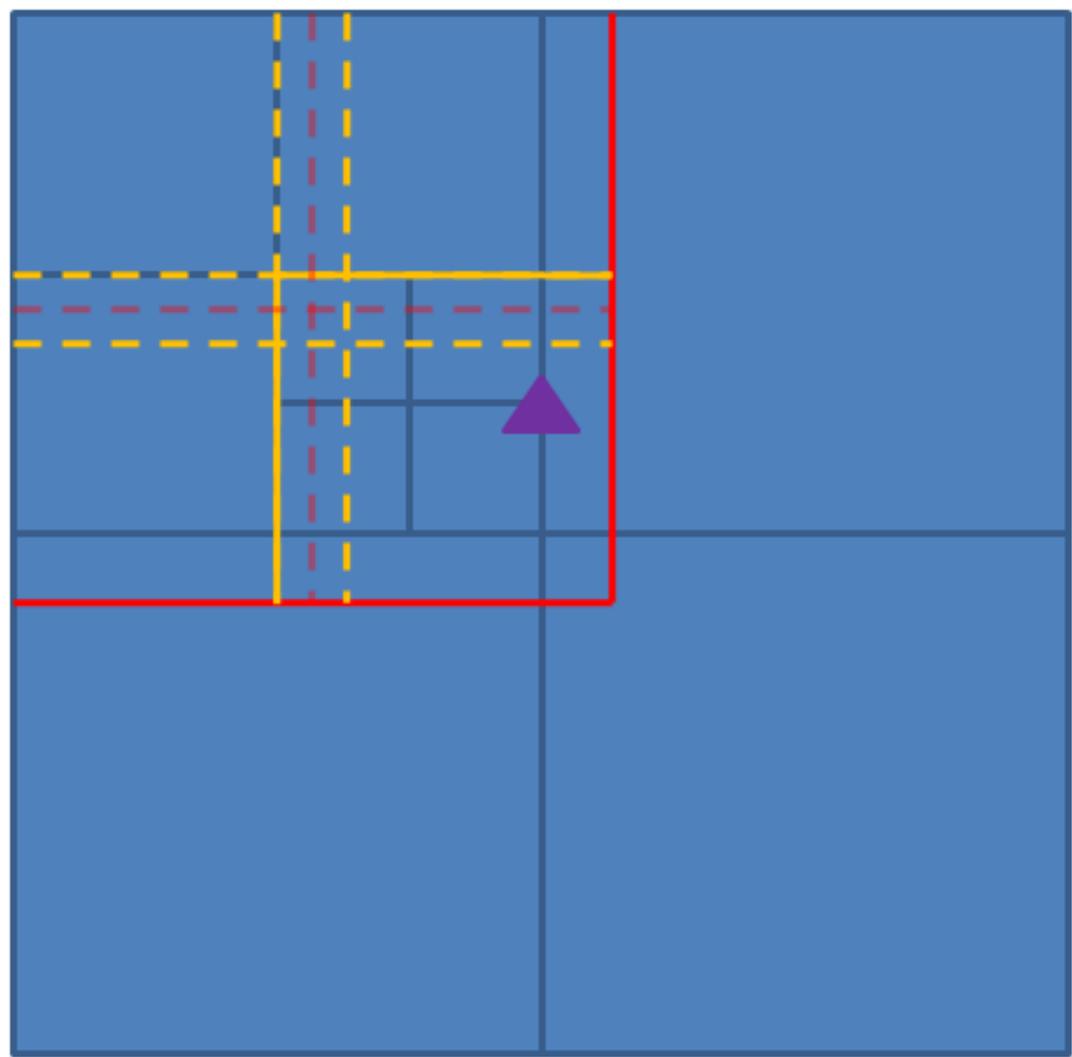


Loose Octree



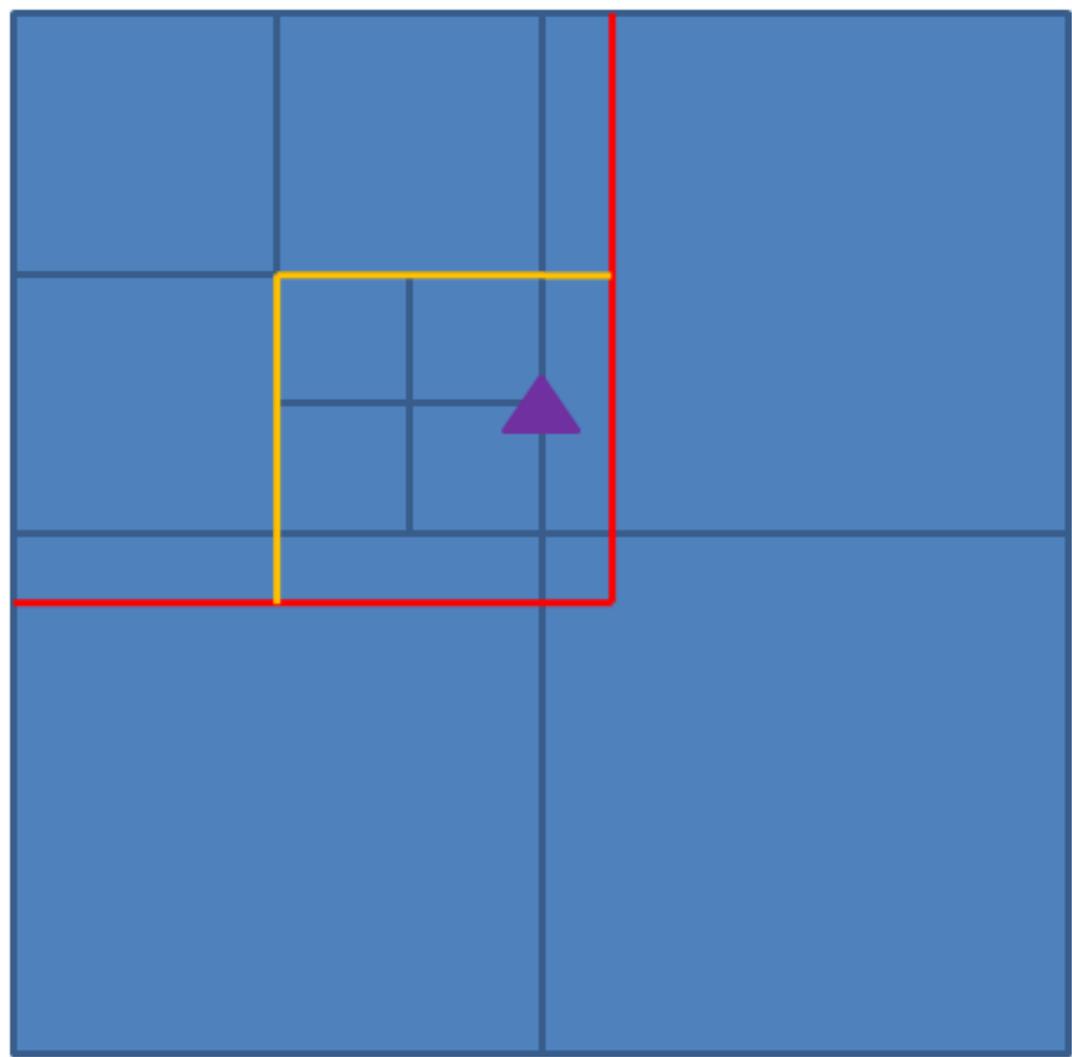


Loose Octree



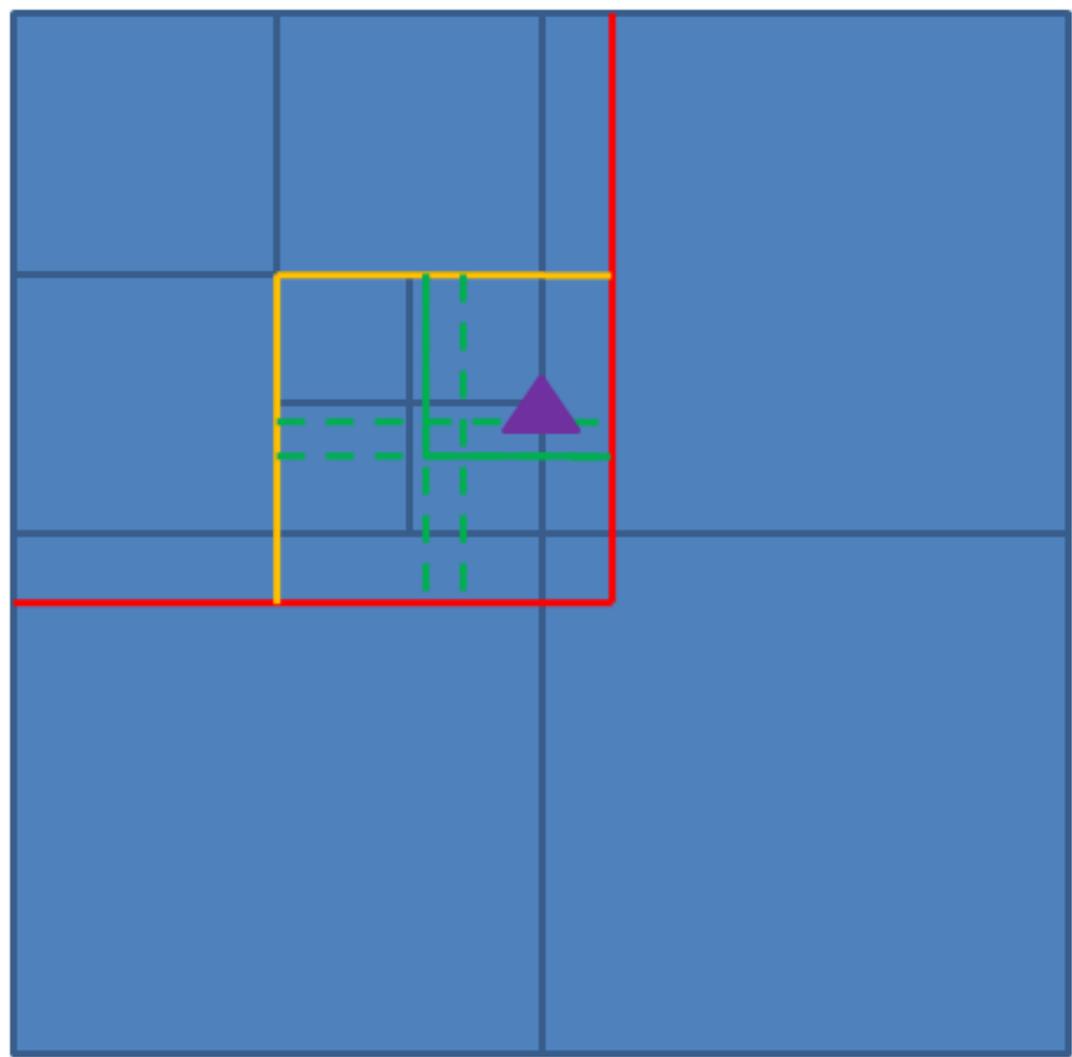


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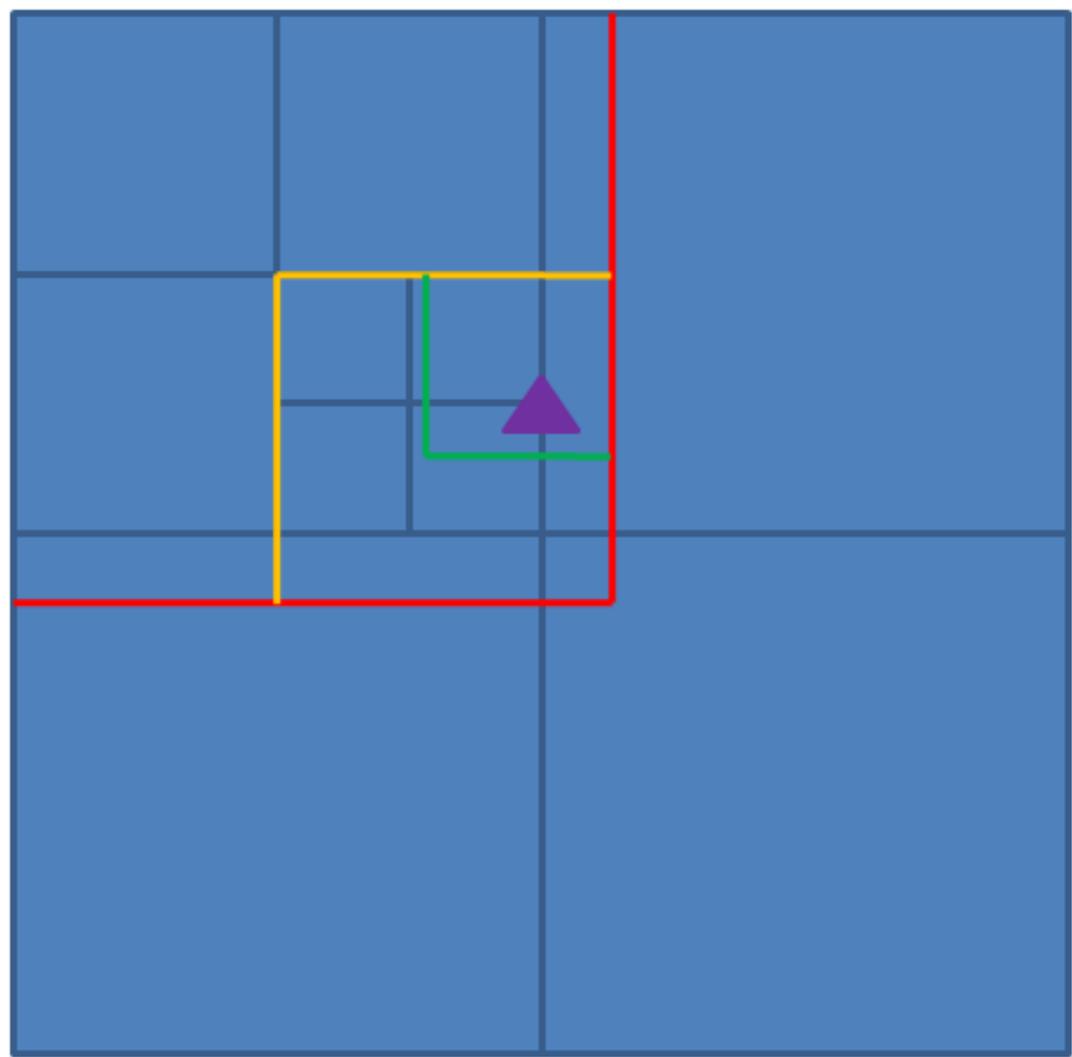


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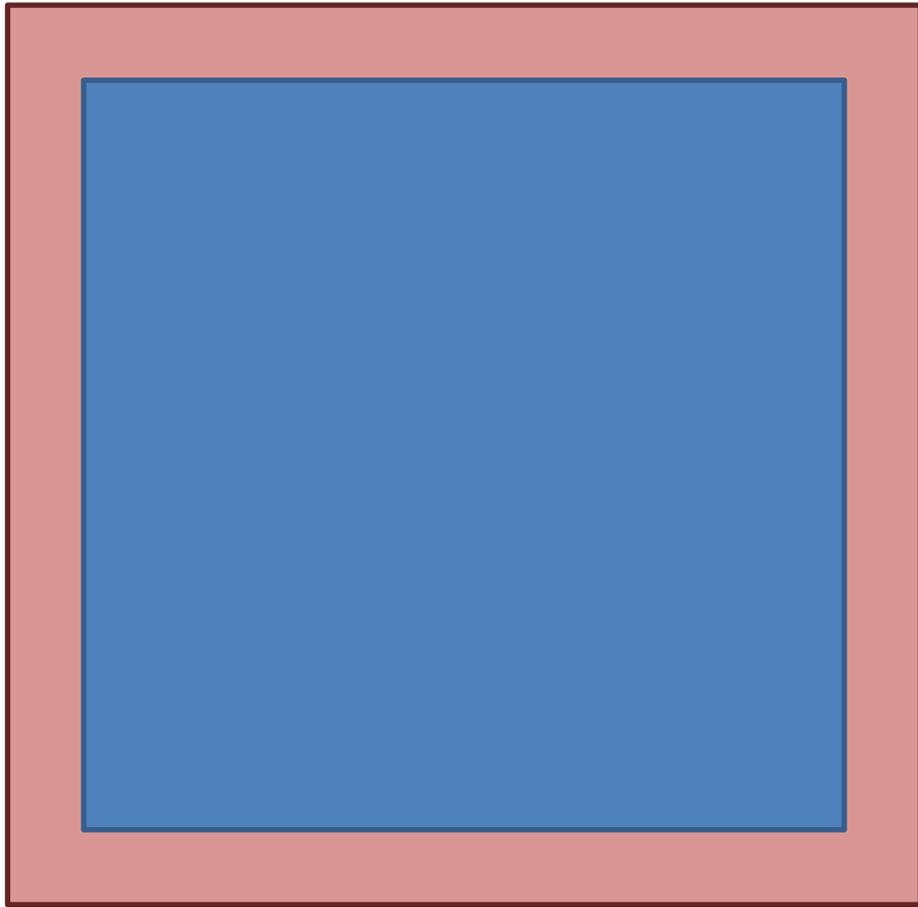


Loose Octree



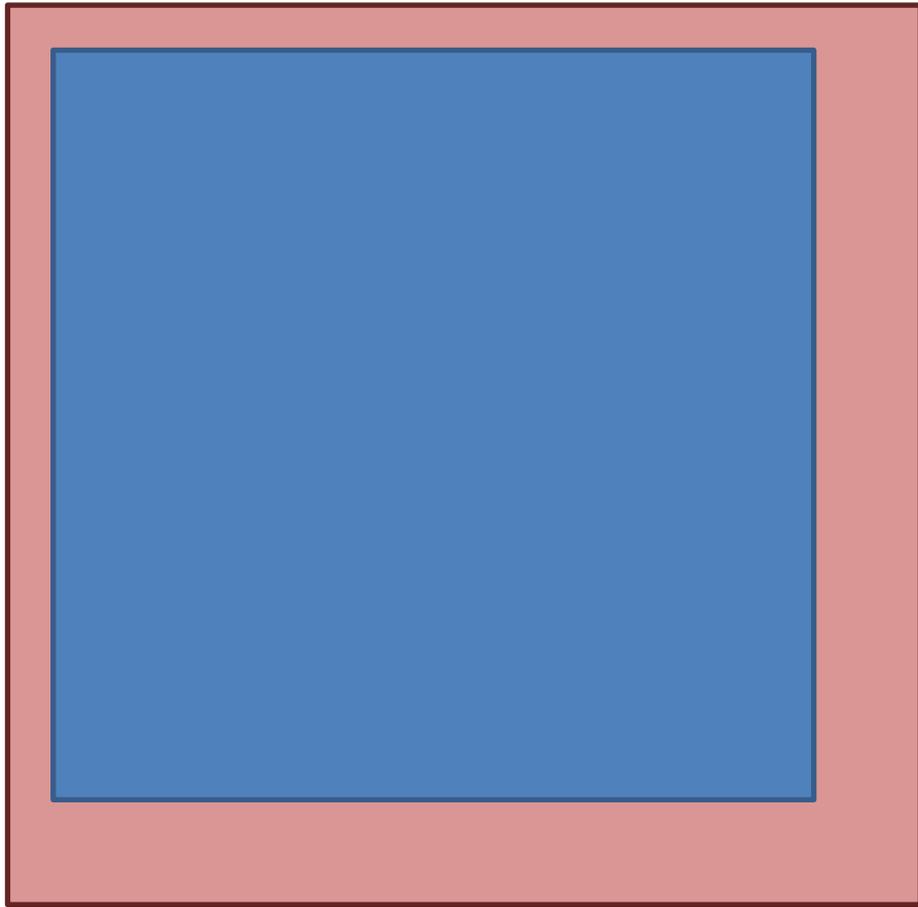


Padded BBox



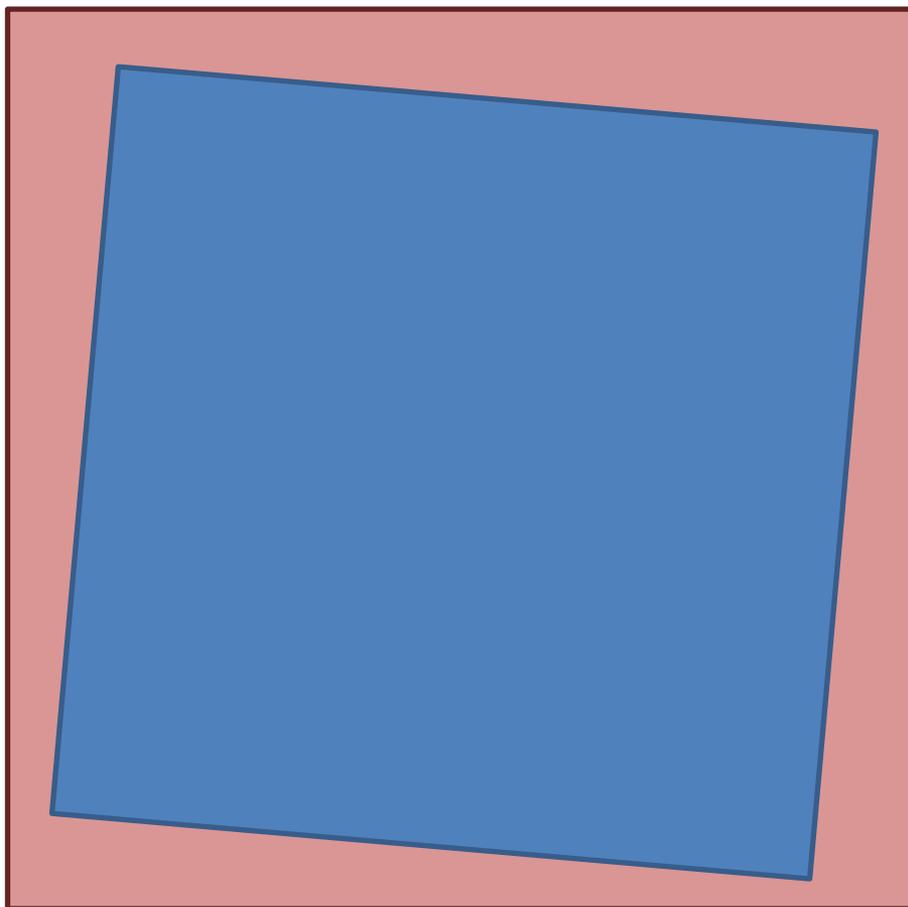


Padded BBox



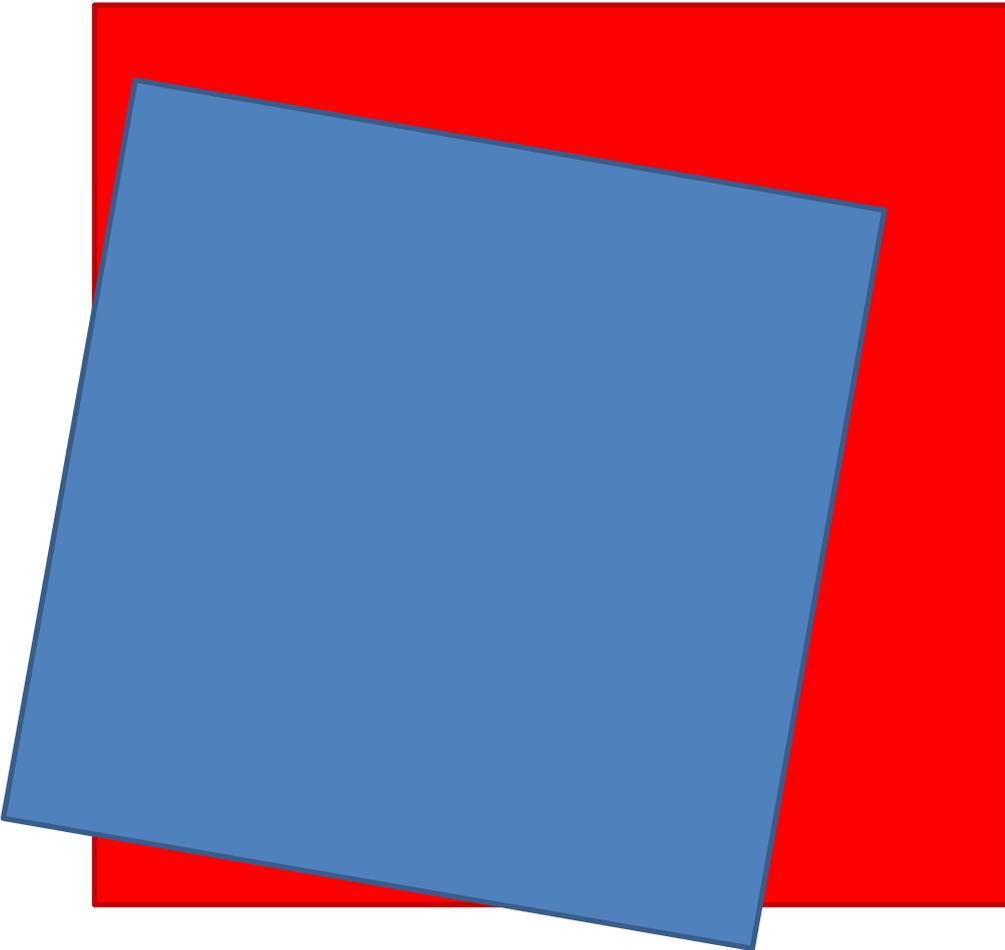


Padded BBox



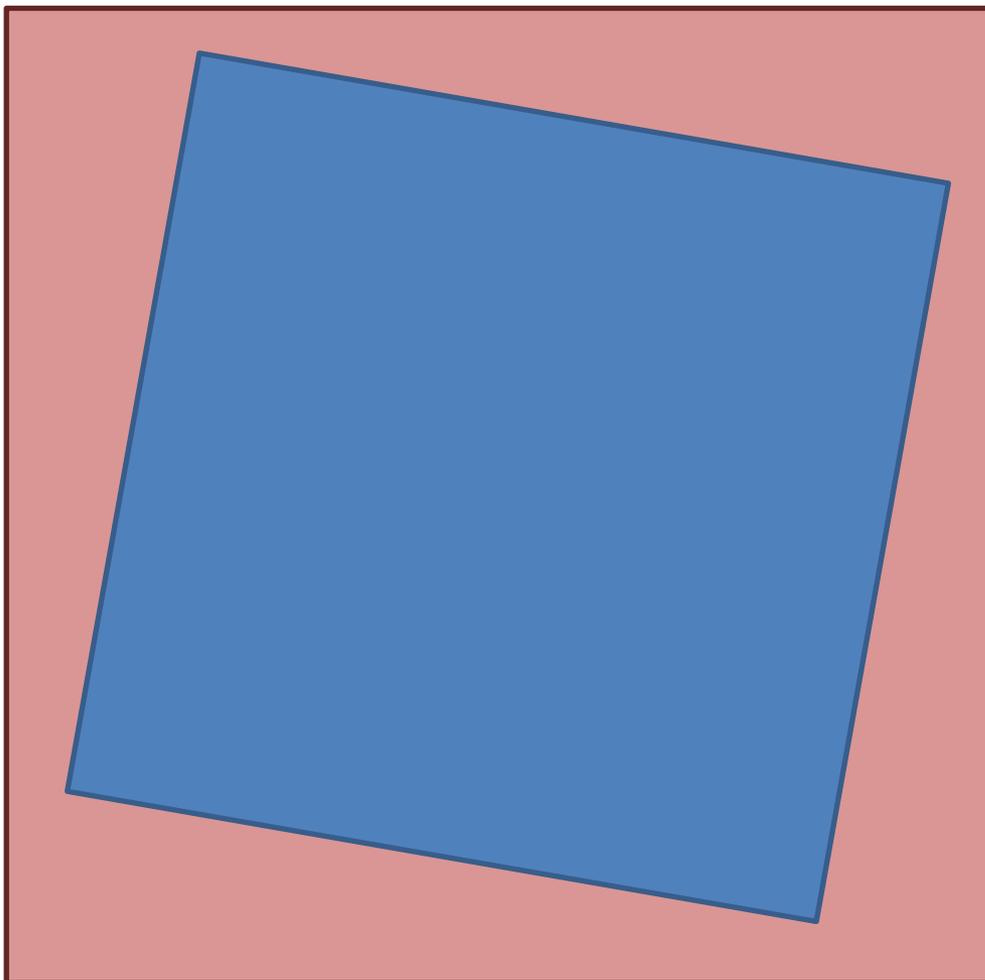


Padded BBox





Padded BBox



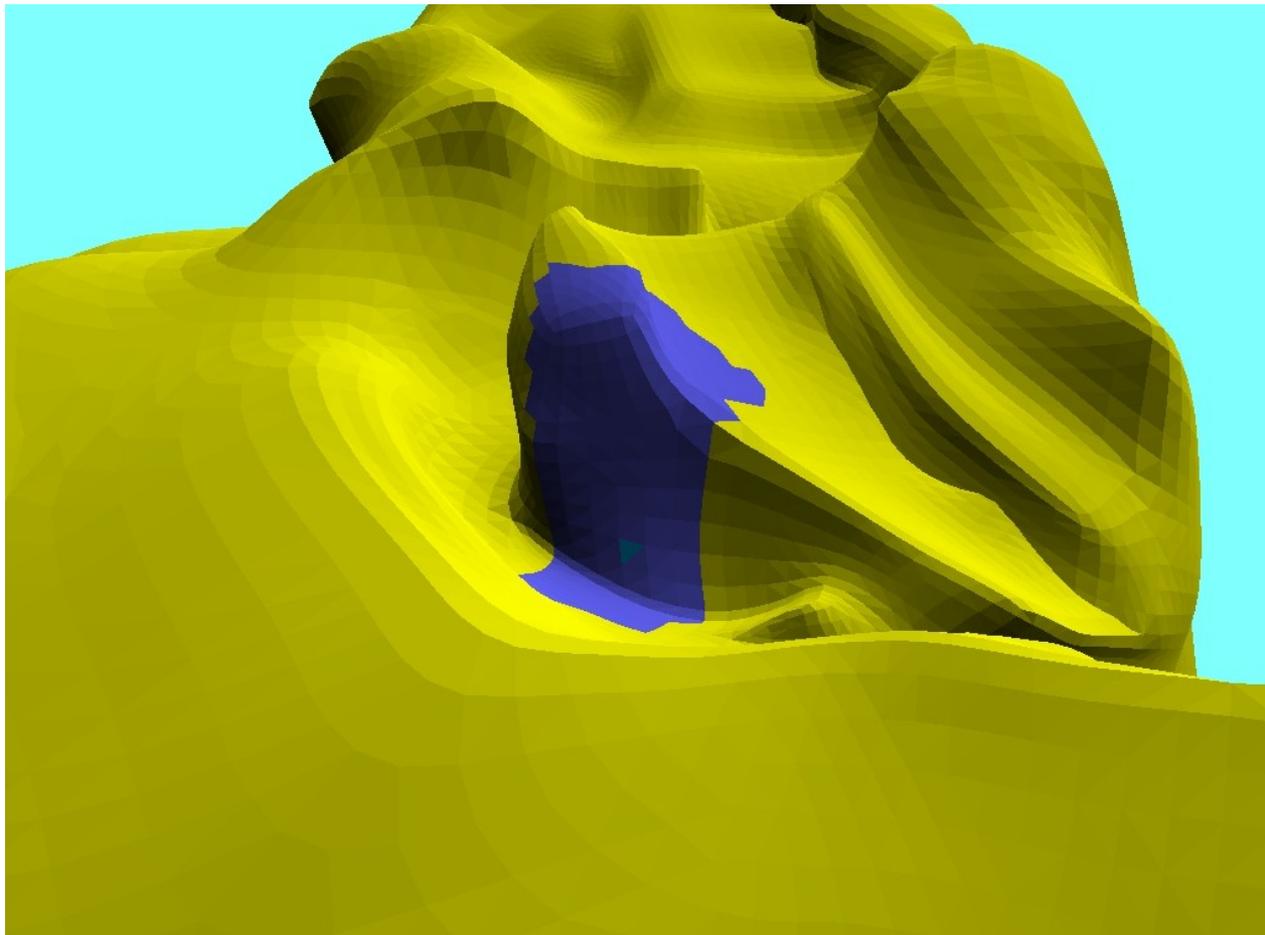


Meshes & Narrow Phase

- Clustering
- Spatial Indexing
- Edge Filtering



Clusters





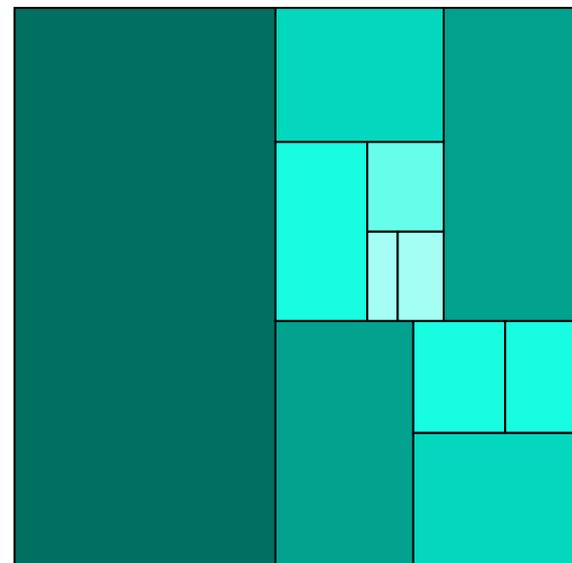
Quantization

- Local coordinate system
- Compress vertex positions
- Careful about degenerate triangles
- Need to account for this in kd-tree



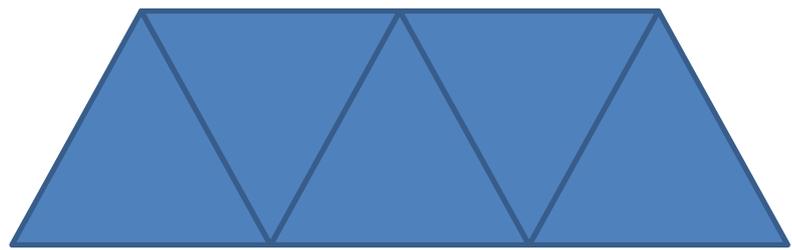
Kd-Tree

- “Loose kd-tree”
- Good for indexing static sets
- Use it to generate clusters



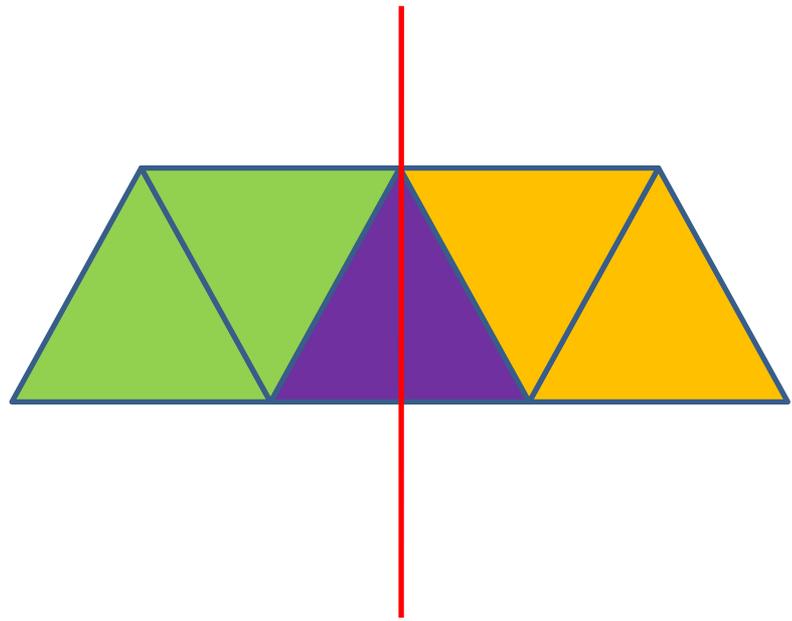


Kd-tree Split Problem



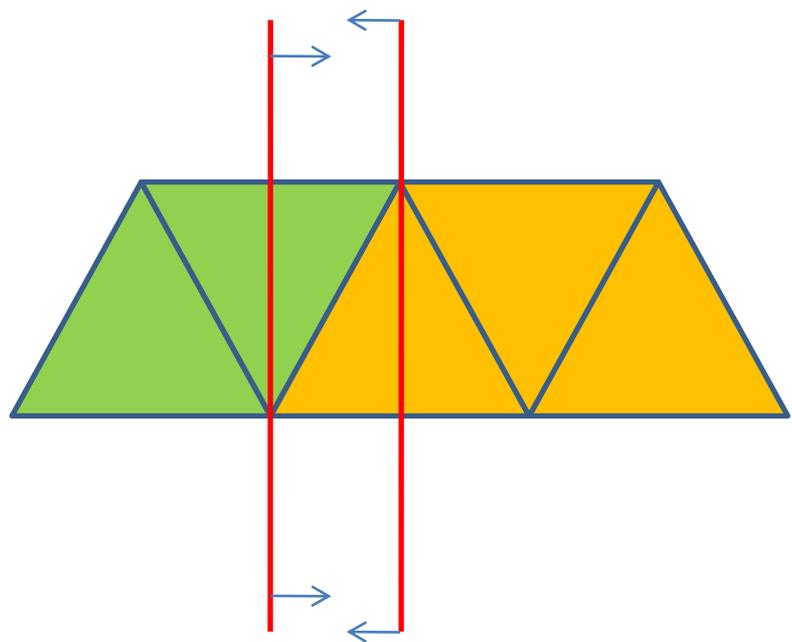


Kd-tree Split Problem



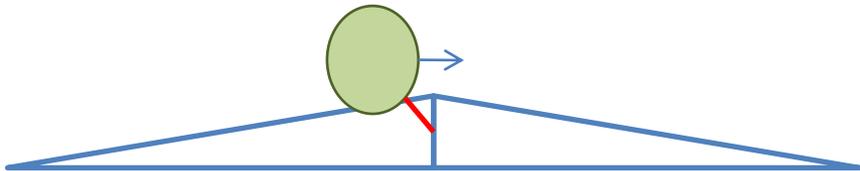
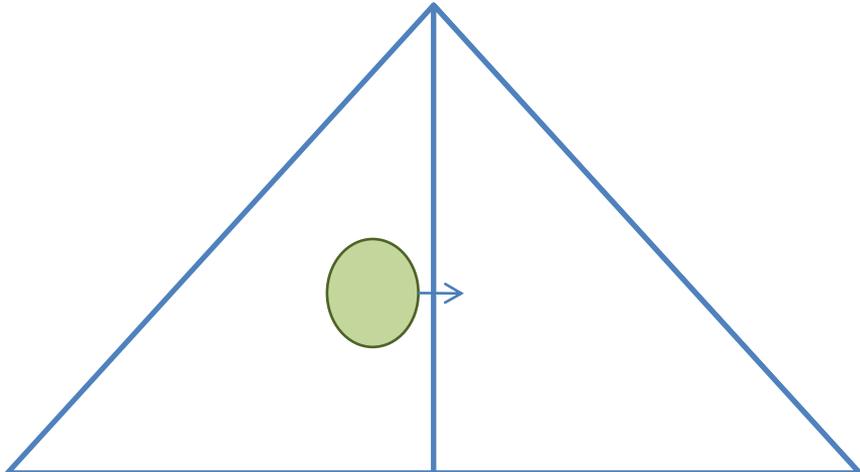


Loose Kd-tree



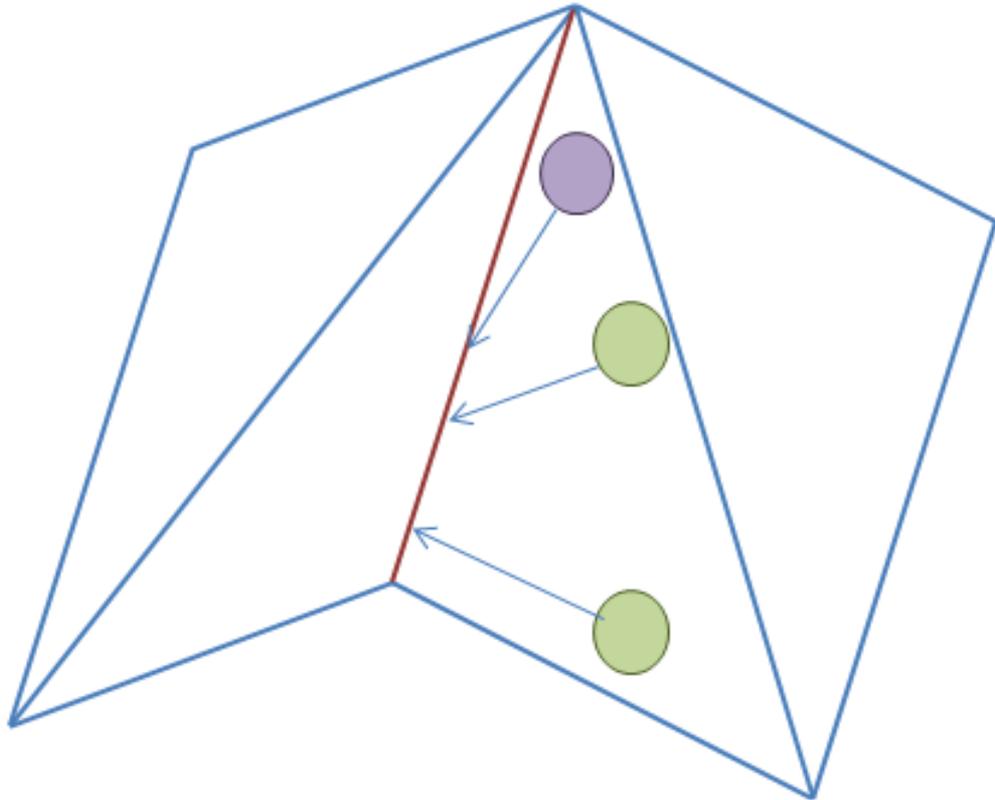


Edge Filtering



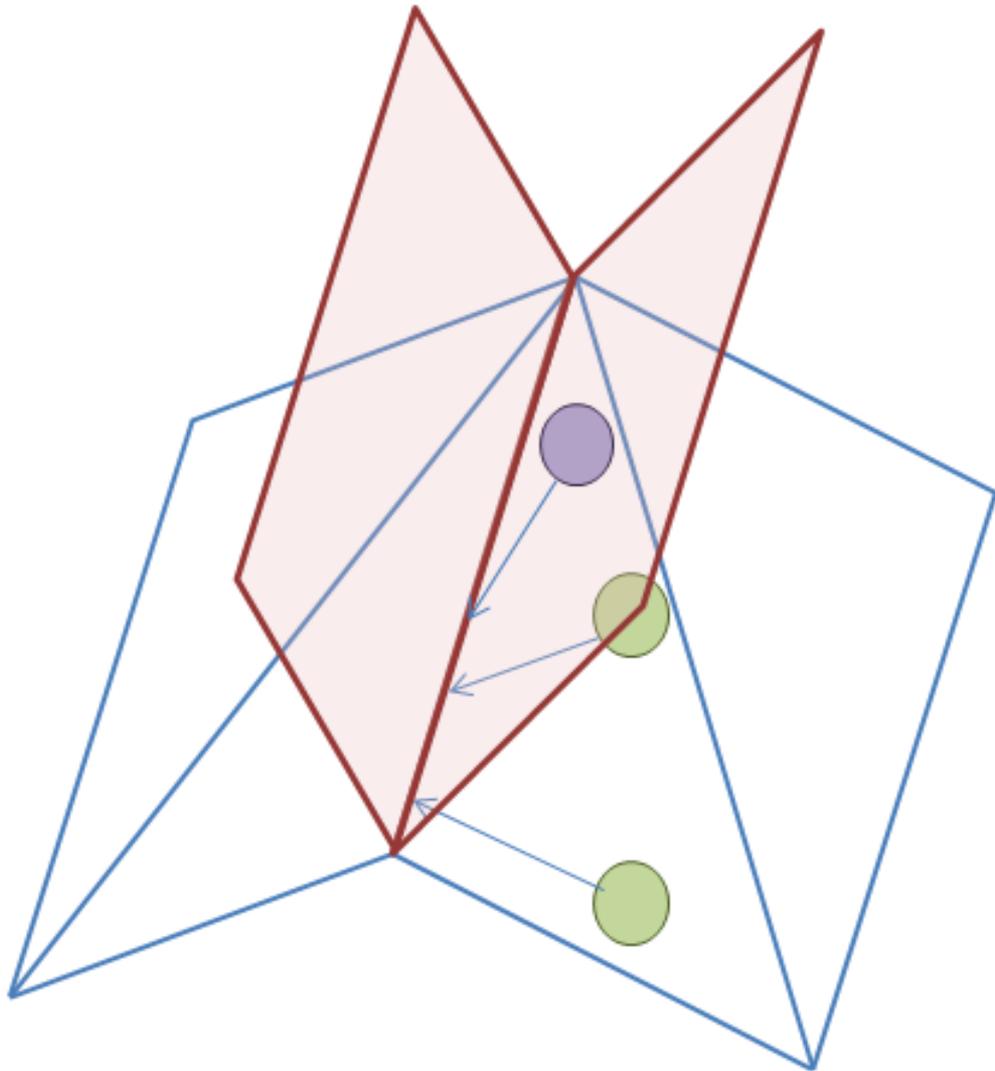


Voronoi Region



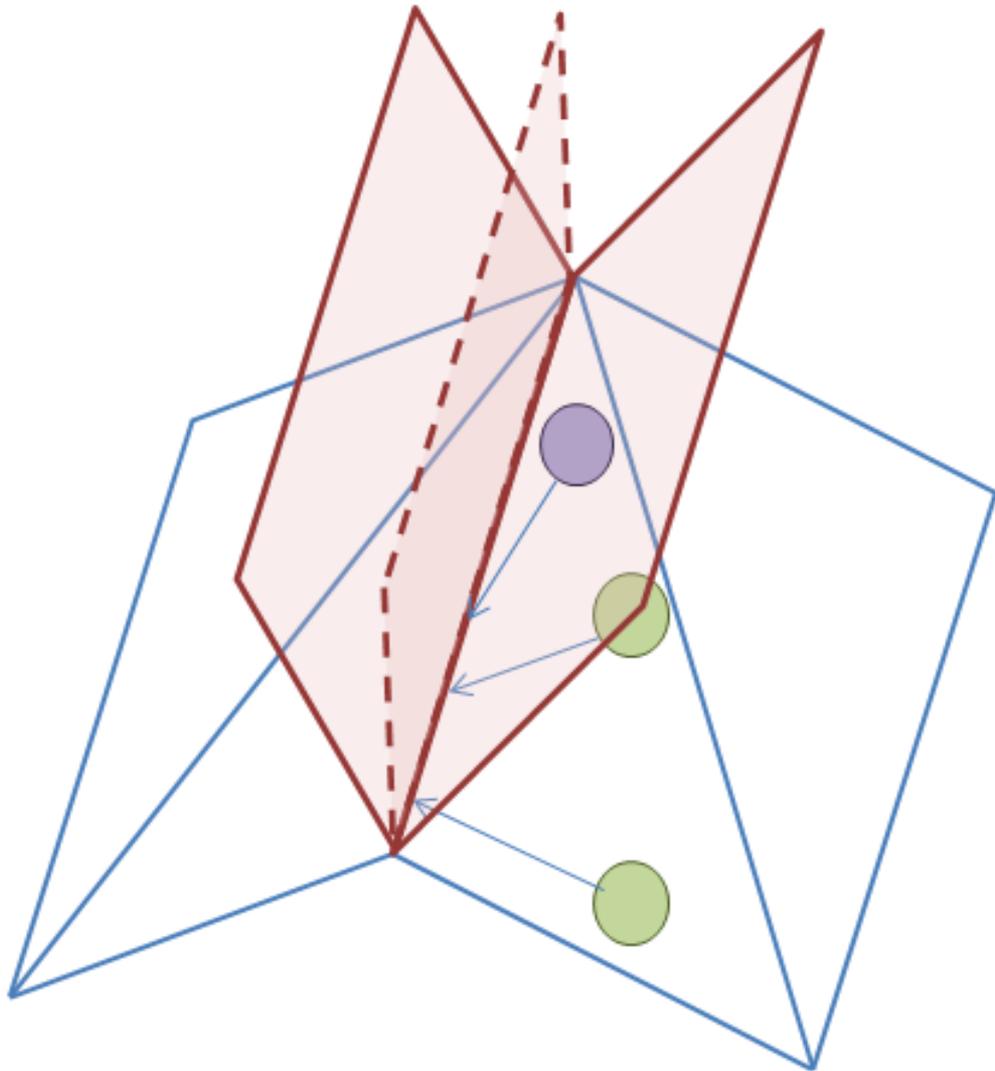


Voronoi Region



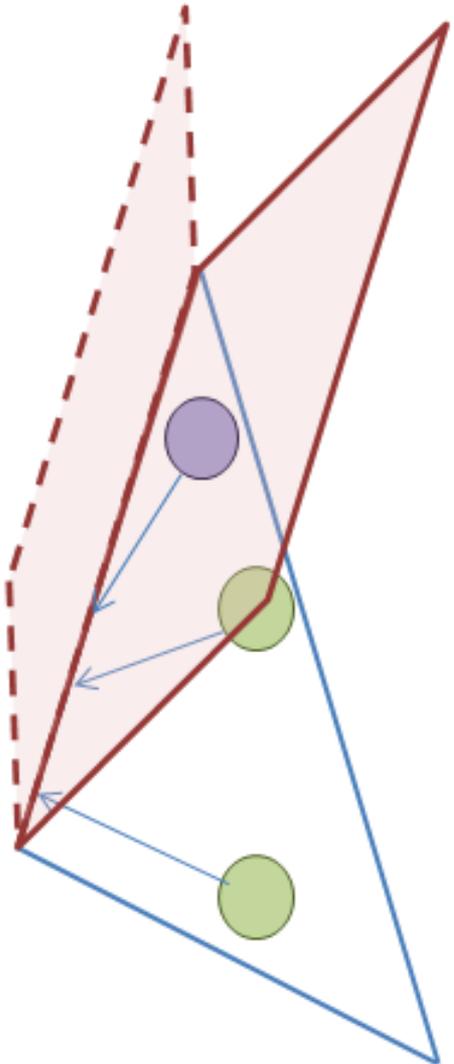


Voronoi Region





Voronoi Region





SSX Pipeline

Octree

Kd-Tree

Primitive
SAT

Edge
Filtering

Full
Manifold

Contact
Cache



SSX Video

- <http://www.youtube.com/watch?v=Duz7f2yye5k>



Challenges

- Many “mesh” representations
 - Graphics LODs
 - Collision
 - Audio
 - Nav mesh
- What algorithms will run on GPU?
- Is it possible to do collision LOD?



Questions?

Contact: sfrye@ea.com